

maxon motor control's EPOS4 products are small-sized, full digital, smart positioning control units. Their high power density allows flexible use for brushed DC and brushless EC (BLDC) motors up to approximately 1'050 Watts with various feedback options, such as Hall sensors, incremental encoders as well as absolute sensors in a multitude of drive applications.

EPOS4 controllers are specially designed to be commanded and controlled as a slave node in the CANopen network. In addition, the units can be operated via any USB or RS232 communication port of a Windows or Linux workstation. Moreover, the integrated extension interface allows optional communication interfaces, such as EtherCAT or other additional functionalities.

Latest technology, such as field-oriented control (FOC) and acceleration/velocity feed forward in combination with highest control cycle rates allow sophisticated, ease-of-use motion control.

Legend: ✓ = included / nnnnnn = order number / ** = available shortly / (a) requires an optionally available extension card (see "Accessories" on page 7) / (b) optional for separate logic supply / (c) mandatory for supply of power stage / (d) with suitable motherboard




epos.maxonmotor.com

	EPOS4 Module 24/1.5 (536630)	EPOS4 Compact 24/1.5 CAN (546714)	EPOS4 50/5 (546047)	EPOS4 Module 50/5 (534130)	EPOS4 Compact 50/5 CAN (541718)	EPOS4 Module 50/8 (504384)	EPOS4 Compact 50/8 CAN (520885)	EPOS4 Module 50/15 (504383)	EPOS4 Compact 50/15 CAN (520886)	EPOS4 70/15 (594385)
<p>for comparison purposes: US Half Dollar coin (Ø30.6 mm)</p>										
Communication Interfaces										
CANopen Slave	max. 1 Mbit/s									
CANopen Application Layer and Communication Profile	CiA 301									
CANopen Layer Setting Services and Protocol (LSS)	CiA 305**									
CANopen Device Profile Drives and Motion Control	CiA 402									
USB 2.0 / USB 3.0	Full speed									
Gateway function USB-to-CAN	✓									
RS232	max. 115'200 bit/s									
Gateway function RS232-to-CAN	✓									
EtherCAT Slave	✓ (a)	—	✓ (a)	✓ (a)	—	✓ (a)	—	✓ (a)	—	✓ (a)
IEC 61158 Digital data communication for measurement and control Fieldbus for use in industrial control systems	Type 12 (EtherCAT) max. 100 Mbit/s (100 Base Tx)	—	Type 12 (EtherCAT) max. 100 Mbit/s (100 Base Tx)	Type 12 (EtherCAT) max. 100 Mbit/s (100 Base Tx)	—	Type 12 (EtherCAT) max. 100 Mbit/s (100 Base Tx)	—	Type 12 (EtherCAT) max. 100 Mbit/s (100 Base Tx)	—	Type 12 (EtherCAT) max. 100 Mbit/s (100 Base Tx)
IEC 61800-7 Generic interface and use of profiles for power drive systems	Profile type 1 (CiA 402)	—	Profile type 1 (CiA 402)	Profile type 1 (CiA 402)	—	Profile type 1 (CiA 402)	—	Profile type 1 (CiA 402)	—	Profile type 1 (CiA 402)
CAN application layer over EtherCAT (CoE)	✓	—	✓	✓	—	✓	—	✓	—	✓
File transfer over EtherCAT (FoE)	✓**	—	✓**	✓**	—	✓**	—	✓**	—	✓**
Distributed clocks support	✓	—	✓	✓	—	✓	—	✓	—	✓
Cyclic modes support cycle times down to...	1 ms	—	1 ms	1 ms	—	1 ms	—	1 ms	—	1 ms
Process data	PDO mapping (Variable)	—	PDO mapping (Variable)	PDO mapping (Variable)	—	PDO mapping (Variable)	—	PDO mapping (Variable)	—	PDO mapping (Variable)
Motors										
Brushed DC motors up to (continuous / max.)	36 W / 108 W	36 W / 108 W	250 W / 750 W	250 W / 750 W	250 W / 750 W	400 W / 1'500 W	400 W / 1'500 W	750 W / 1'500 W	750 W / 1'500 W	1'050 W / 2'100 W
Brushless EC motors (BLDC) up to (continuous / max.)	36 W / 108 W	36 W / 108 W	250 W / 750 W	250 W / 750 W	250 W / 750 W	400 W / 1'500 W	400 W / 1'500 W	750 W / 1'500 W	750 W / 1'500 W	1'050 W / 2'100 W

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Sensors (Feedback)										
Digital Hall sensors (EC motors)	✓									
Digital incremental encoder (2-/3-channel, single-ended or differential)	✓									
Analog incremental encoder (3-channel, sin/cos, differential)	✓**									
SSI absolute encoder (configurable)	✓									
BiSS C absolute encoder (configurable)	✓ (a)**	—	✓ (a)**	✓ (a)**	—	✓ (a)**	—	✓ (a)**	—	✓ (a)**
EnDat 2.2 absolute encoder (configurable)	✓ (a)**	—	✓ (a)**	✓ (a)**	—	✓ (a)**	—	✓ (a)**	—	✓ (a)**
Commutation										
Digital Hall sensors	✓									
Digital Hall sensors + digital incremental encoder	✓									
Digital Hall sensors + analog incremental encoder	✓**									
Digital Hall sensors + absolute encoder	✓									
Absolute encoder	✓									
Electrical Data										
Nominal power supply voltage (+V _{CC})	10...24 VDC	10...24 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...70 VDC
Nominal logic supply voltage (+V _C)	10...24 VDC	10...24 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...70 VDC
Absolute supply voltage limits (+V _{min} / +V _{max})	8 VDC / 28 VDC	8 VDC / 28 VDC	8 VDC / 56 VDC	8 VDC / 56 VDC	8 VDC / 56 VDC	8 VDC / 56 VDC	8 VDC / 56 VDC	8 VDC / 56 VDC	8 VDC / 56 VDC	8 VDC / 76 VDC
Output voltage (max.)	0.9 x +V _{CC}									
Output current (I _{cont} / I _{max})	1.5 A / 4.5 A (<30 s)	1.5 A / 4.5 A (<30 s)	5 A / 15 A (<15s)	5 A / 15 A (<3 s)	5 A / 15 A (<3 s)	8 A / 30 A (<5 s)	8 A / 30 A (<5 s)	15 A / 30 A (<60 s)	15 A / 30 A (<60 s)	15 A / 30 A (<60 s)
Pulse width modulation frequency	100 kHz	100 kHz	50 kHz	50 kHz	50 kHz	50 kHz	50 kHz	50 kHz	50 kHz	50 kHz
Sampling rate PI current controller	25 kHz (40 μs)									
Sampling rate PID speed controller	2.5 kHz (400 μs)									
Sampling rate PID positioning controller	2.5 kHz (400 μs)									
Max. efficiency	89%	89%	98%	97%	97%	98%	98%	98%	98%	98%
Max. speed DC motor	limited by max. permissible speed (motor)									
Max. speed EC motor, block commutation	100'000 rpm (1 pole pair)									
Max. speed EC motor, sinusoidal commutation	50'000 rpm (1 pole pair)									
Built-in motor choke	—	3 x 94 μH; 1.5 A	3 x 15 μH; 5 A	—	3 x 9.4 μH; 5 A	—	3 x 2.2 μH; 15 A	—	3 x 2.2 μH; 15 A	3 x 15 μH; 15 A
Inputs / Outputs										
Digital Hall sensor signals	H1, H2, H3 (+2...+24 VDC, internal pull-up)									
Digital incremental encoder signals	A, A\, B, B\, I, I\ (EIA RS422, 6.25 MHz)									
Encoder signals	A, A\, B, B\, I, I\ (EIA RS422, 6.25 MHz) Clock, Clock\ Data, Data\ 4 (+2.1...+36 VDC)									
Digital inputs	all Modules all Compacts and housing versions 4; level selectable by DIP switch: (Logic level: +2.0...+30 VDC) or (PLC level: +9.0...+30 VDC)									
Digital outputs	2 (open collector, max. 36 VDC / 500 mA, internal pull-up)									
High-speed digital inputs	4 (EIA RS422, 6.25 MHz)									
High-speed digital outputs	1 (EIA RS422, 6.25 MHz)									
Analog inputs	2 (resolution 12-bit, -10...+10 V, 10 kHz, differential)									
Analog outputs	2 (resolution 12-bit, -4...+4 V, 25 kHz)									
STO inputs	2 (+4.5...+30 VDC, optically isolated)									

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STO outputs	1 (max. 30 VDC / 15 mA, optically isolated with self-resetting short-circuit protection)												
Sensor supply voltage	+5 VDC (I _L ≤100 mA)												
Auxiliary output voltage	+5 VDC (I _L ≤150 mA)												
Status indicators (LEDs or bi-color LEDs)	Device status	Device status	Device status	Device status	Device status	Device status	Device status	Device status	Device status	Device status			
	—	—	NET status	—	—	—	—	—	—	NET status			
	—	—	NET port	—	—	—	—	—	—	NET port			
Connections													
X1	Power Supply	—	Molex Mini-Fit Jr. 2 poles	Box header (1.27 mm) 2x23 poles	—	Pin header (2.54 mm) 2x16 poles	Molex Mega-Fit 2 poles	Pin header (2.54 mm) 2x16 poles	Molex Mega-Fit 2 poles	Molex Mega-Fit 2 poles			
X2	Logic Supply	—	Molex Mini-Fit Jr. 2 poles		—		Molex Mini-Fit Jr. 2 poles		Molex Mini-Fit Jr. 2 poles	Molex Mini-Fit Jr. 2 poles			
X1/X2	Power & Logic Supply	Harting har-flexicon 3 poles	—		Harting har-flexicon 3 poles		—		—	—			
X3	Motor	—	Molex Mini-Fit Jr. 4 poles		—		Molex Mini-Fit Jr. 4 poles		—	—			
X3a	Motor (I _{cont} ≤11 A)	—	—		—		Molex Mini-Fit Jr. 4 poles		—	Molex Mini-Fit Jr. 4 poles	Molex Mini-Fit Jr. 4 poles		
X3b	Motor (I _{cont} ≤15 A)	—	—		—		—		—	Molex Mega-Fit 4 poles	Molex Mega-Fit 4 poles		
X3c	Motor	Hirose DF3DZ 3 poles	—		—		—		—	—	—		
X3a/X4a	Motor & Hall Sensor	Harting har-flexicon 8 poles	—		—		—		—	—	—		
X3b/X4b	Motor & Hall Sensor	Lumberg Minimodul 8 poles	—		—		—		—	—	—		
X4	Hall Sensor	—	Molex Micro-Fit 3.0 6 poles		—		Molex Micro-Fit 3.0 6 poles		—	Molex Micro-Fit 3.0 6 poles	Molex Micro-Fit 3.0 6 poles	Molex Micro-Fit 3.0 6 poles	
X5	Encoder	Pin header 2.54 mm 2x5 poles	Pin header 2.54 mm 2x5 poles		—		Pin header 2.54 mm 2x5 poles		—	Pin header 2.54 mm 2x5 poles	Pin header 2.54 mm 2x5 poles	Pin header 2.54 mm 2x5 poles	
X6	Sensor	Molex CLIK-Mate 2x5 poles	Molex CLIK-Mate 2x5 poles		Box header (1.27 mm) 2x23 poles		Molex CLIK-Mate 2x5 poles		Pin header (2.54 mm) 2x23 poles	Molex CLIK-Mate 2x5 poles	Pin header (2.54 mm) 2x23 poles	Molex CLIK-Mate 2x5 poles	Molex CLIK-Mate 2x5 poles
X7	Digital I/O	Molex CLIK-Mate 8 poles	Molex CLIK-Mate 8 poles				Molex CLIK-Mate 8 poles			Molex CLIK-Mate 8 poles		Molex CLIK-Mate 8 poles	Molex CLIK-Mate 8 poles
X8	Analog I/O	Molex CLIK-Mate 7 poles	Molex CLIK-Mate 7 poles	Molex CLIK-Mate 7 poles		Molex CLIK-Mate 7 poles	Molex CLIK-Mate 7 poles	Molex CLIK-Mate 7 poles					
X9	STO	Molex CLIK-Mate 8 poles	Molex CLIK-Mate 8 poles	Molex CLIK-Mate 8 poles		Molex CLIK-Mate 8 poles	Molex CLIK-Mate 8 poles	Molex CLIK-Mate 8 poles		Molex CLIK-Mate 8 poles			
X10	RS232	Molex CLIK-Mate 5 poles	Molex CLIK-Mate 5 poles	Molex CLIK-Mate 5 poles		Molex CLIK-Mate 5 poles	Molex CLIK-Mate 5 poles	Molex CLIK-Mate 5 poles		Molex CLIK-Mate 5 poles			
X11	CAN 1	Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles		Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles		Molex CLIK-Mate 4 poles			
X12	CAN 2	Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles		Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles	Molex CLIK-Mate 4 poles		Molex CLIK-Mate 4 poles			
X13	USB	USB Type micro B, female											
X14	Extension IN (a)	—	—	RJ45 10/100-BASE-TX	—	—	—	—	—	RJ45 10/100-BASE-TX			
X15	Extension OUT (a)	—	—	RJ45 10/100-BASE-TX	—	—	—	—	—	RJ45 10/100-BASE-TX			
X16	Extension Signal (a)	—	—	Molex CLIK-Mate 2x5 poles	—	—	—	—	—	Molex CLIK-Mate 2x5 poles			

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Digital I/O Functionality										
Inputs (configurable)										✓
Touch Probe										✓**
Reference switches										✓
Limit switches										✓
Quickstop										✓
Drive Enable										✓
General purpose										✓
Outputs (configurable)										✓
Position Compare										✓**
Holding Brake										✓
Ready/Fault										✓
General purpose										✓
Analog I/O Functionality										
Inputs (configurable)										✓
Analog set value										✓**
General purpose										✓
Outputs (configurable)										✓**
Current monitor										✓**
Velocity monitor										✓**
Position monitor										✓**
Temperature monitor										✓**
General purpose										✓**
Built-in Protection										
Current limiter (adjustable)										✓
Overcurrent										✓
Thermal motor protection										✓
Thermal controller protection										✓
Overvoltage										✓
Undervoltage										✓
Voltage transients										✓
Short-circuit of motor winding										✓
Loss of feedback signal										✓
Following error										✓
Status reporting										✓
Firmware error handling										✓

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Software										
Installation Program	EPOS Setup									
Graphical User Interface	EPOS Studio									
	 The EPOS video library features video tutorials that provide easy to follow instructions on how to get started with «EPOS Studio» and shows you tips and tricks on how to setup communication interfaces, motors and sensors, and so on. Explore on Vimeo: → https://vimeo.com/album/4646388									
Startup	✓									
Regulation Tuning	✓									
Diagnostics	✓**									
Firmware Update	✓									
Motion Commander	✓									
I/O Monitor	✓									
Parameters	✓									
Data Recording	✓									
Command Analyzer	✓									
CANopen Wizard	✓									
Online Help	✓									
Language	English									
Operating System	Windows 10, 8, 7									
Windows DLL for PC	32-bit / 64-bit									
CAN interfaces	IXXAT National Instruments Kvaser Vector									
Programming examples	Microsoft Visual Basic, Visual Basic.NET, Visual C#, Visual C++ Borland C++, Delphi National Instruments LabView, LabWindows/CVI									
Linux Shard Object Library	X86 32-bit/64-bit, ARMv7/v8 32-bit									
CAN interfaces	IXXAT Kvaser									
Programming examples	C++									
IEC 61131-3 library for CAN master	Beckhoff**									
maxon library for NI SoftMotion	National Instruments Compact Rio**									

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Accessories (not included in delivery)										
520858	CAN-CAN Cable	—	✓	✓	—	✓	—	✓	—	✓
520857	CAN-COM Cable	—	✓	✓	—	✓	—	✓	—	✓
275934	Encoder Cable	—	✓	✓	—	✓	—	✓	—	✓
422827	Ethernet Cable	—	—	✓	—	—	—	—	—	✓
275878	Hall Sensor Cable	—	—	✓	—	✓	—	✓	—	✓
520854	Signal Cable 7core	—	✓	✓	—	✓	—	✓	—	✓
520853	Signal Cable 8core	—	✓	✓	—	✓	—	✓	—	✓
275851	Motor Cable	—	—	✓	—	✓	—	✓	—	✓
520851	Motor Cable High Current	—	—	—	—	—	—	—	—	✓
275829	Power Cable	—	—	✓	—	—	—	✓ (b)	—	✓ (b)
520850	Power Cable High Current	—	—	—	—	—	—	✓ (c)	—	✓ (c)
520856	RS232-COM Cable	—	✓	✓	—	✓	—	✓	—	✓
520852	Sensor Cable 5x2core	—	✓	✓	—	✓	—	✓	—	✓
520860	STO Idle Connector X9	—	✓ (included)	✓ (included)	—	✓ (included)	—	✓ (included)	—	✓ (included)
403968	USB Type A - micro B Cable	✓	✓	✓	✓	✓	✓	✓	✓	✓
536997	EPOS4 CB 24/1.5 CAN	✓	—	—	—	—	—	—	—	—
534133	EPOS4 CB 50/5 CAN	—	—	—	✓	—	—	—	—	—
520884	EPOS4 CB Power CAN	—	—	—	—	✓	—	✓	—	—
520859	EPOS4 Connector Set	—	✓	✓	—	✓	—	✓	—	✓
581245	EPOS4 EtherCAT Card	✓ (d)	—	✓	✓ (d)	—	✓ (d)	—	✓ (d)	✓

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