FE060-10-CM

FlexPro® Series
Product Status: Active

SPECIFICATIONS

Current Peak	**20 A**
Current Continuous	**10 A**
DC Supply Voltage	**10 – 55 VDC**
Network Communication	**CANopen**
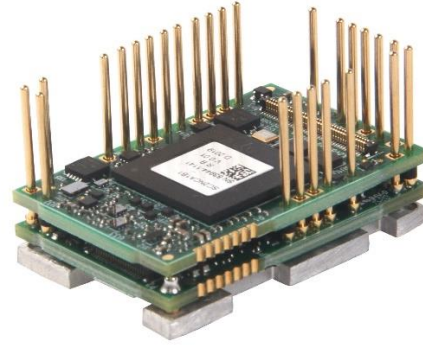
The **FE060-10-CM** is a FlexPro® series servo drive with IMPACT™ architecture.

The **FE060-10-CM** offers full tuning control of all servo loops and is designed to drive brushed and brushless servo motors, stepper motors, and AC induction motors. The drive accepts a variety of external command signals, or can use the built-in Motion Engine, an internal motion controller used with Sequencing and Indexing commands. Programmable digital and analog I/O are included to enhance interfacing with external controllers and devices.

The **FE060-10-CM** features a CANopen interface for network communication and USB connectivity for drive configuration and setup. All drive and motor parameters are stored in non-volatile memory.

IMPACT™ (**I**ntegrated **M**otion **P**latform **A**nd **C**ontrol **T**echnology combines exceptional processing capability and high-current components to create powerful, compact, feature-loaded servo solutions. IMPACT™ is used in all FlexPro® drives and is available in custom products as well.

FEATURES

- Follows the CAN in Automation (CiA) 301 Communications Profile and 402 Device Profile
- Four Quadrant Regenerative Operation
- Programmable Gain Settings
- PIDF Velocity Loop
- Space Vector Modulation (SVM) Technology

- Fully Configurable Current, Voltage, Velocity and Position Limits
- Compact Size, High Power Density
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching
- Dedicated Safe Torque Off (STO) Inputs

Feedback Supported	- Absolute Encoder - BiSS C-Mode - EnDat 2.2 - Incremental Encoder - Hall Sensors - Aux Incremental Encoder ±10 VDC Position - Tachometer (±10V)	Motors Supported	- Three Phase - Single Phase - Stepper - AC Induction	Modes of Operation	- Profile Modes - Cyclic Synchronous Modes - Current - Velocity - Position - Interpolated Position Mode (PVT)
Command Sources	- Over the Network ±10V Analog - Sequencing - Indexing - Jogging - Step & Direction - Encoder Following	Inputs / Outputs	4 Programmable Digital Inputs 3 Programmable Digital Outputs 1 Programmable Analog Input	Agency Approvals	- RoHS - UL (Pending) - CE (Pending) - TUV Rheinland (STO) (Pending)

BLOCK DIAGRAM

FE060-10-CM
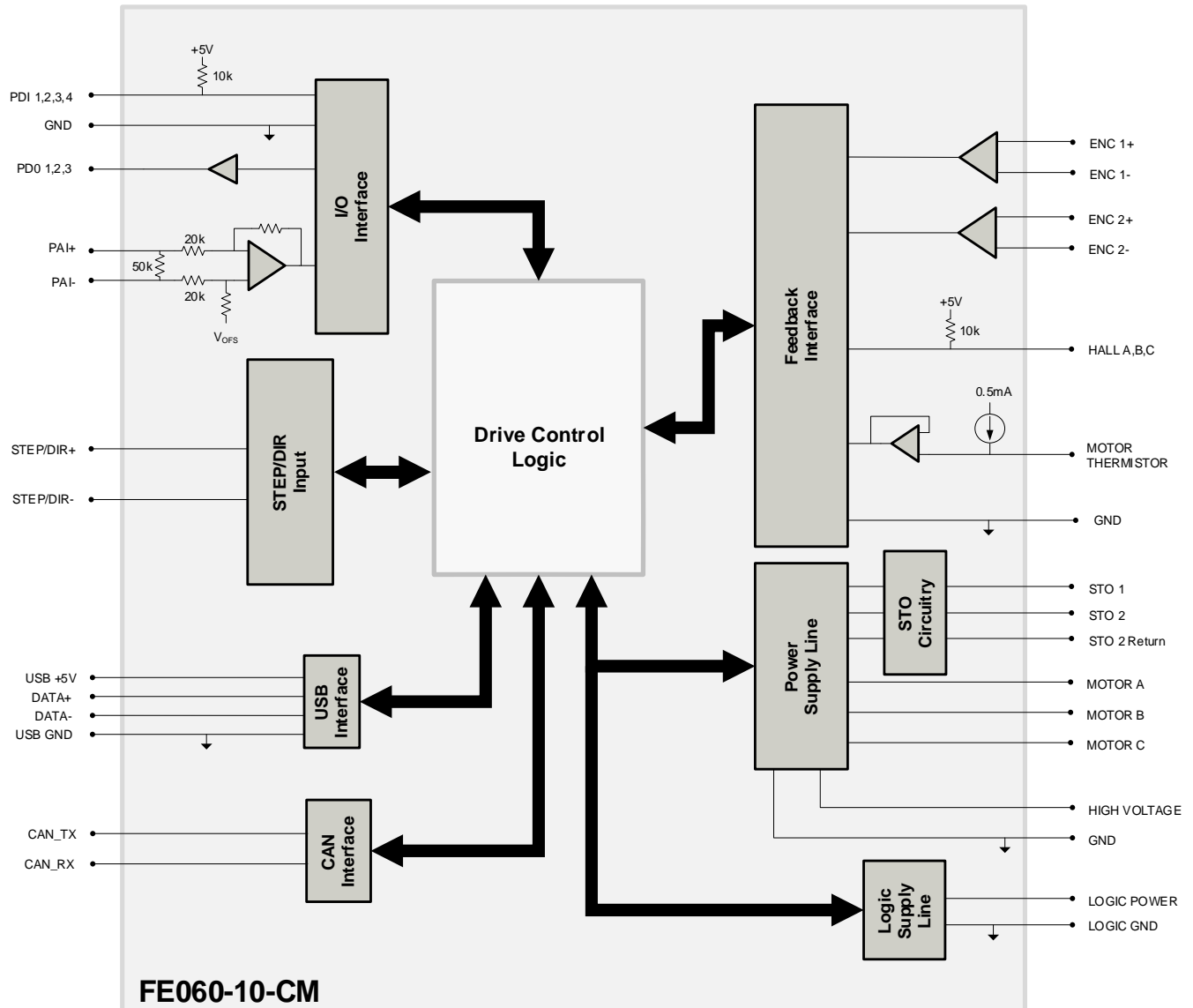
INFORMATION ON APPROVALS AND COMPLIANCES

RoHS Compliant

The RoHS Directive restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

Sold & Serviced By:

SPECIFICATIONS

Electrical Specifications		
Description	Units	Value
DC Supply Input Range	VDC	10 – 55
DC Supply Undervoltage	VDC	8
DC Supply Overvoltage	VDC	58
Logic Supply Input Range (optional)	VDC	10 – 55
Safe Torque Off Voltage (Default)	VDC	5
Minimum Required External Bus Capacitance	μF	500
Maximum Peak Current Output[1]	A (Arms)	20 (14.1)
Maximum Continuous Current Output[2]	A (Arms)	10 (10)
Efficiency at Rated Power	%	99
Maximum Continuous Output Power	W	545
Maximum Power Dissipation at Rated Power	W	6
Minimum Load Inductance (line-to-line)[3]	μH	150 (@ 48VDC supply); 75 (@24VDC supply); 40 (@12VDC supply)
Switching Frequency	kHz	20
Maximum Output PWM Duty Cycle	%	85
Control Specifications		
Description	Units	Value
Communication Interfaces	-	CANopen (USB for configuration)
Command Sources	-	±10 V Analog, Over the Network, Sequencing, Indexing, Jogging, Step & Direction, Encoder Following
Feedback Supported	-	Absolute Encoder (BiSS C-Mode, EnDat 2.2), Hall Sensors, Incremental Encoder, Auxiliary Incremental Encoder, ±10 VDC Position, Tachometer (±10V)
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Profile Modes, Cyclic Synchronous Modes, Current, Velocity, Position, Interpolated Position Mode (PVT)
Motors Supported[4]	-	Three Phase (Brushless Servo), Single Phase (Brushed Servo, Voice Coil, Inductive Load), Stepper (2- or 3-Phase Closed Loop), AC Induction (Closed Loop Vector)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs	-	4/3
Programmable Analog Inputs/Outputs	-	1/0
Primary I/O Logic Level	-	5 VDC, not isolated
Current Loop Sample Time	μs	50
Velocity Loop Sample Time	μs	100
Position Loop Sample Time	μs	100
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)
Mechanical Specifications		
Description	Units	Value
Size (H x W x D)	mm (in)	38.1 x 25.4 x 11.5 (1.50 x 1.00 x 0.45)
Weight	g (oz)	19.8 (0.7)
Ambient Operating Temperature Range[5]	°C (°F)	0 – 65 (32 – 149)
Storage Temperature Range	°C (°F)	-40 – 85 (-40 – 185)
Relative Humidity	-	0-95%, non-condensing
Form Factor	-	PCB Mounted
P1 SIGNAL CONNECTOR	-	80-pin 0.4mm spaced connector
TERMINAL PINS	-	15x Terminal Pins
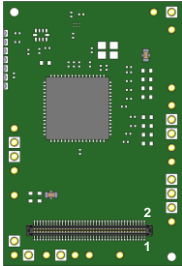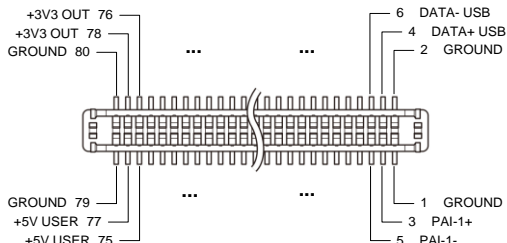
Notes
1. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
2. Continuous A$_{rms}$ value attainable when RMS Charge-Based Limiting is used.
3. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
4. Maximum motor speed for stepper motors is 600 RPM. Consult the hardware installation manual for 2-phase stepper wiring configuration.
5. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

Pin	Name	Description / Notes	I/O	Pin	Name	Description / Notes	I/O
			P1 – Signal Connector				
1	GROUND	Ground	GND	2	GROUND	Ground	GND
3	PAI-1+	Differential Programmable Analog Input or Reference Signal Input (12-bit Resolution)	I	4	DATA+ USB	USB Data Channel	I/O
5	PAI-1-		I	6	DATA- USB		I/O
7	THERMISTOR	Motor Thermal Protection.	I	8	GROUND	Ground	GND
9	GROUND	Ground	GND	10	SCLA	I²C Data Signals for Addressing, Network Error LED, and Bridge Status LED. See Hardware Manual for more info.	O
11	ENC 1 DATA+ / A+	Differential Data Line for Absolute Encoders (BiSS: SLO+/-) or Differential Incremental Encoder A.	I/O	12	SDAA		I/O
13	ENC 1 DATA- / A-		I/O	14	HALL A	Single-ended Commutation Sensor Inputs	I
15	ENC 1 CLK+ / B+	Differential Clock Line for Absolute Encoders (BiSS: MA+/-) or Differential Incremental Encoder B.	I/O	16	HALL B		I
17	ENC 1 CLK- / B-		I/O	18	HALL C		I
19	GROUND	Ground	GND	20	GROUND	Ground	GND
21	ENC 1 REF+ / I+	Differential Reference Mark for Absolute Encoders (Leave open for BiSS) or Differential Incremental Encoder Index.	I	22	ENC 2 A+	Differential Incremental Encoder A.	I
23	ENC 1 REF- / I-		I	24	ENC 2 A-		I
25	CAN_TX	CAN Transmit Line (requires external transceiver)	I/O	26	ENC 2 B+	Differential Incremental Encoder B.	I
27	CAN_RX	CAN Receive Line (requires external transceiver)	I/O	28	ENC 2 B-		I
29	CAN STANDBY	Low power CAN mode control	I/O	30	ENC 2 I+	Differential Incremental Encoder Index.	I
31	PDI-1	Programmable Digital Input	I	32	ENC 2 I-		I
33	PDI-2	Programmable Digital Input	I	34	PDO-1	Programmable Digital Output (TTL/8mA)	O
35	PDI-3	Programmable Digital Input	I	36	PDO-2	Programmable Digital Output (TTL/8mA)	O
37	PDI-4	Programmable Digital Input	I	38	PDO-3	Programmable Digital Output (TTL/8mA)	O
39	GROUND	Ground	GND	40	GROUND	Ground	GND
41	RESERVED	Reserved. Do not connect.	-	42	RESERVED	Reserved. Do not connect.	-
43	RESERVED	Reserved. Do not connect.	-	44	RESERVED	Reserved. Do not connect.	-
45	RESERVED	Reserved. Do not connect.	-	46	RESERVED	Reserved. Do not connect.	-
47	RESERVED	Reserved. Do not connect.	-	48	RESERVED	Reserved. Do not connect.	-
49	RESERVED	Reserved. Do not connect.	-	50	RESERVED	Reserved. Do not connect.	-
51	RESERVED	Reserved. Do not connect.	-	52	RESERVED	Reserved. Do not connect.	-
53	RESERVED	Reserved. Do not connect.	-	54	RESERVED	Reserved. Do not connect.	-
55	RESERVED	Reserved. Do not connect.	-	56	RESERVED	Reserved. Do not connect.	-
57	RESERVED	Reserved. Do not connect.	-	58	RESERVED	Reserved. Do not connect.	-
59	GROUND	Ground	GND	60	GROUND	Ground	GND
61	RESERVED	Reserved. Do not connect.	-	62	RESERVED	Reserved. Do not connect.	-
63	RESERVED	Reserved. Do not connect.	-	64	RESERVED	Reserved. Do not connect.	-
65	RESERVED	Reserved. Do not connect.	-	66	RESERVED	Reserved. Do not connect.	-
67	RESERVED	Reserved. Do not connect.	-	68	STEP	Step Input.	I
69	RESERVED	Reserved. Do not connect.	-	70	DIR	Direction Input.	I
71	RESERVED	Reserved. Do not connect.	-	72	RESERVED	Reserved. Do not connect.	-
73	+5V_OUT	+5VDC unprotected supply (See Note 1)	O	74	RESERVED	Reserved. Do not connect.	-
75	+5V_USER	+5VDC User Supply for feedback and local logic (See Note 1)	O	76	+3V3 OUT	+3.3VDC Supply Output for local logic signals (100 mA max)	O
77	+5V_USER		O	78	+3V3 OUT		O
79	GROUND	Ground	GND	80	GROUND	Ground	GND

Connector Information	80-pin, 0.4mm spaced connector	
Mating Connector Details	PANASONIC: P/N AXT380224	
Mating Connector Included with Drive	No	


```
+3V3 OUT  76                              6  DATA- USB
+3V3 OUT  78                              4  DATA+ USB
GROUND  80        ...        ...          2  GROUND

GROUND  79        ...        ...          1  GROUND
+5V USER  77                              3  PAI-1+
+5V USER  75                              5  PAI-1-
```

Notes
1. Total current through pins P1-73/75/77 should not exceed 300mA, while no single pin should be loaded more than 150mA.

Drive Status LED and Node Addressing

SCLA (P1-10); SDAA (P1-12)

The *SCLA and SDAA* pins allow Drive Status LED monitoring and Node Addressing to be performed with an I²C bus I/O expander. For more information on how to utilize and configure the I/O expander into an interface board, consult the hardware installation manual.

TERMINAL PIN LOCATIONS

The 15 Terminal Pins provide connection to the high power drive signals. Terminal Pins must be soldered to an interface board.
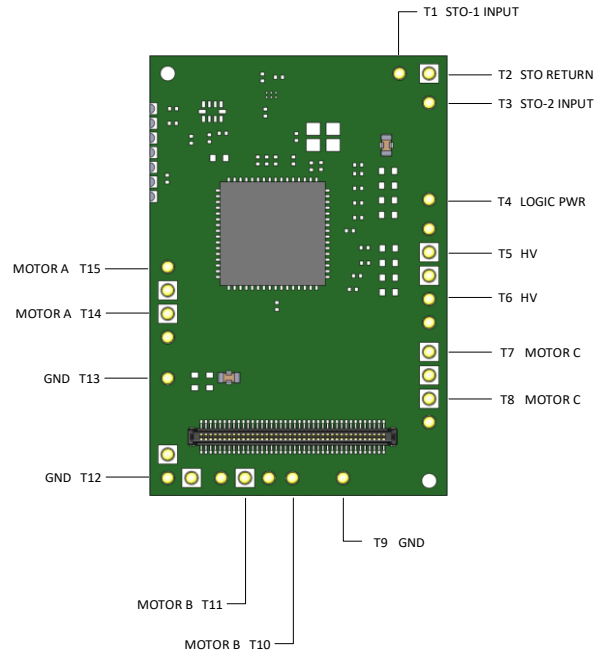
Pin	Name	Description / Notes	I/O
T1	STO-1 INPUT	Safe Torque Off – Input 1	I
T2	STO RETURN	Safe Torque Off Return	STORET
T3	STO-2 INPUT	Safe Torque Off – Input 2	I
T4	LOGIC PWR	Logic Supply Input (10 – 55VDC) (optional)	I
T5	HV	DC Supply Input (10 - 55 VDC). Minimum 500µF external capacitance required between HV and POWER GND.	I
T6	HV		I
T7	MOTOR C	Motor Phase C. All provided motor phase output pins must be used.	O
T8	MOTOR C		O
T9	GND	Ground.	GND
T10	MOTOR B	Motor Phase B. All provided motor phase output pins must be used.	O
T11	MOTOR B		O
T12	GND	Ground.	GND
T13	GND		GND
T14	MOTOR A	Motor Phase A. All provided motor phase output pins must be used.	O
T15	MOTOR A		O

Terminal Pin Details

Safe Torque Off (STO) Inputs
The Safe Torque Off (STO) inputs are dedicated +5VDC sinking single-ended inputs. For applications not using STO functionality, disabling of the STO feature is required for proper drive operation. STO may be disabled by following the STO Disable wiring instructions as given in the hardware installation manual. Consult the hardware installation manual for more information.
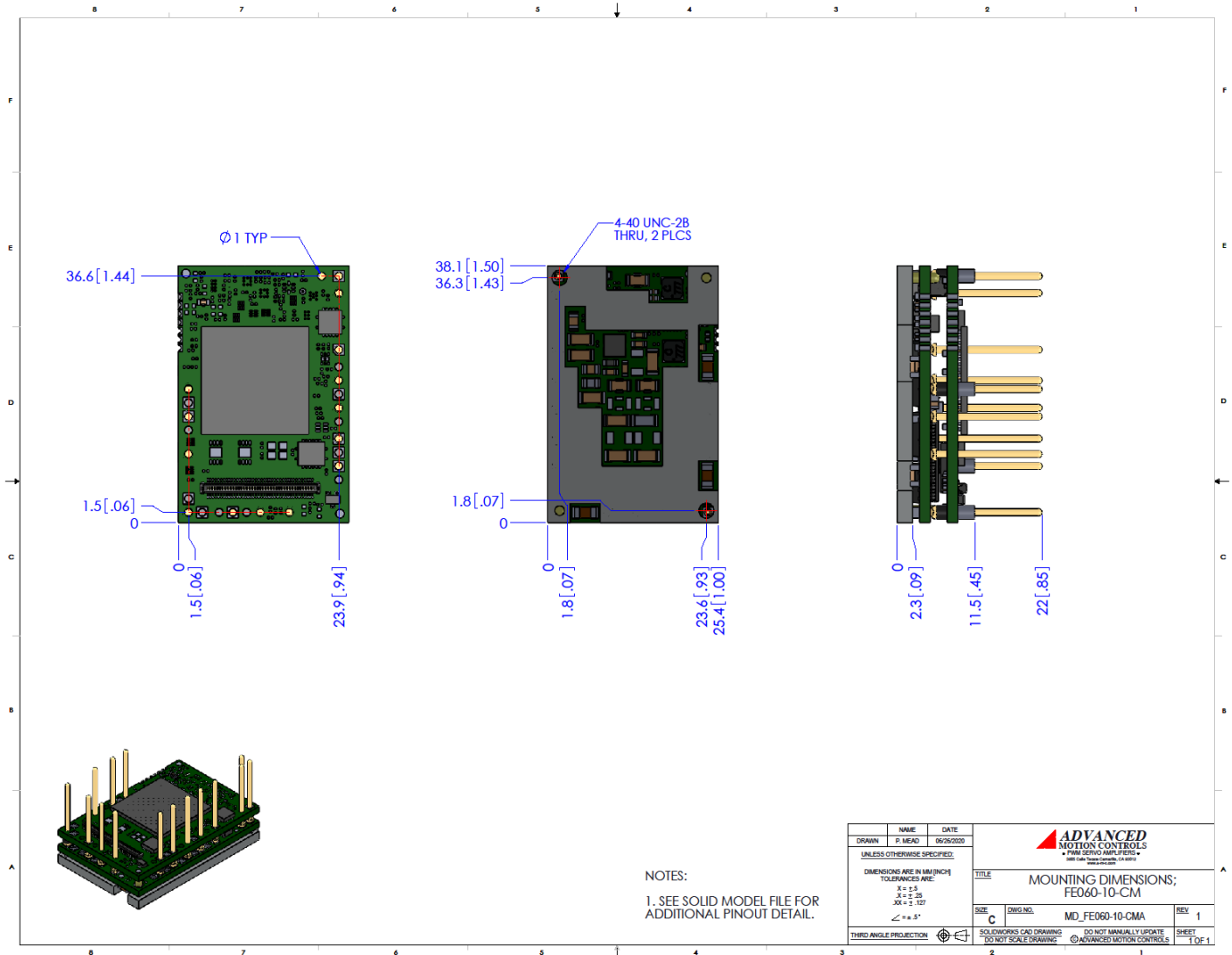
MOUNTING DIMENSIONS

Ø1 TYP

36.6[1.44]

1.5[.06]
0

1.5[.06]
0

23.9[.94]

4-40 UNC-2B
THRU, 2 PLCS

38.1[1.50]
36.3[1.43]

1.8[.07]
0

0
1.8[.07]

23.6[.93]
25.4[1.00]

0
2.3[.09]
11.5[.45]
22[.85]

NOTES:

1. SEE SOLID MODEL FILE FOR ADDITIONAL PINOUT DETAIL.

	NAME	DATE
DRAWN	P. MEAD	06/26/2020

UNLESS OTHERWISE SPECIFIED:

DIMENSIONS ARE IN MM [INCH]
TOLERANCES ARE:
X = ± .5
.X = ± .25
.XX = ± .127
∠ = ± .5°

THIRD ANGLE PROJECTION

ADVANCED MOTION CONTROLS
PWM SERVO AMPLIFIERS
3805 Calle Tecate Camarillo, CA 93012
www.a-m-c.com

TITLE: MOUNTING DIMENSIONS;
FE060-10-CM

SIZE: C
DWG NO. MD_FE060-10-CMA
REV 1

SOLIDWORKS CAD DRAWING
DO NOT SCALE DRAWING

DO NOT MANUALLY UPDATE
© ADVANCED MOTION CONTROLS

SHEET 1 OF 1

PART NUMBERING AND CUSTOMIZATION INFORMATION

F E 060 – 10 – C M

Drive Series

F   **F**lexPro®

Environment

X   E**X**tended Environment

Form Factor

E   FlexPro® **E**mbedded
D   FlexPro® E (W/ **D**evelopment board)
M   FlexPro® **M**achine Mount

Maximum DC Bus Voltage

060   **60** VDC

Feedback

M   **M**ulti Encoder (Absolute, 5V Incremental)

Network Communication

E   **E**therCAT
C   **C**ANopen

Continuous Current

5   **5**A
10   **10**A
25   **25**A
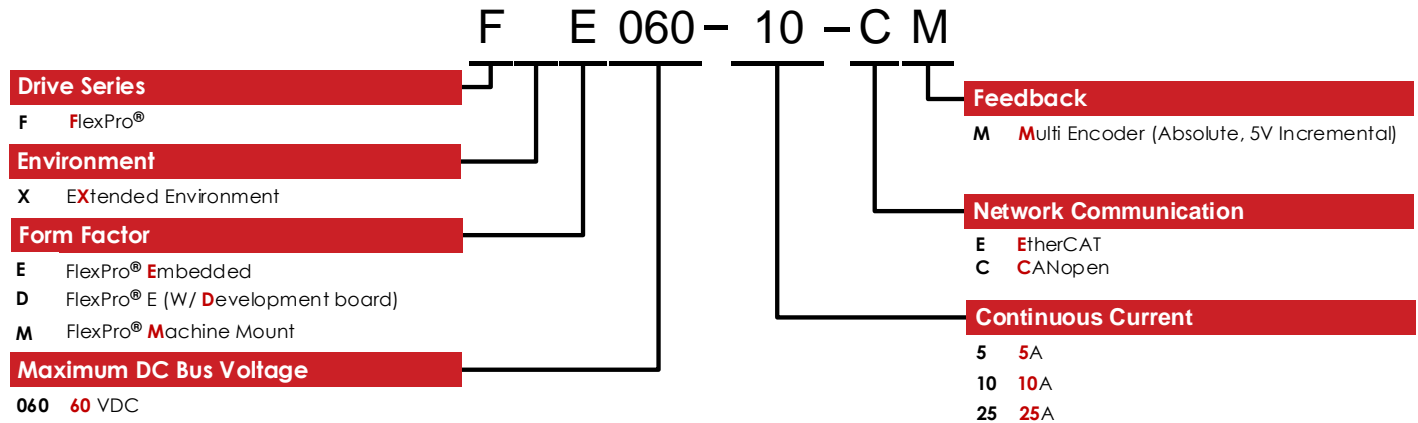
ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, *ADVANCED* Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- Optimized Footprint
- Private Label Software
- OEM Specified Connectors
- No Outer Case
- Increased Current Resolution
- Increased Temperature Range
- Custom Control Interface
- Integrated System I/O

- Tailored Project File
- Silkscreen Branding
- Optimized Base Plate
- Increased Current Limits
- Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- Reduced Profile Size and Weight

Feel free to contact us for further information and details!

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

Development Board

The FE060-10-CM is offered in a pre-soldered development board assembly to provide easy connections to motor, power, and signal functions. The development board assembly can be ordered as model number **FD060-10-CM**.

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.