

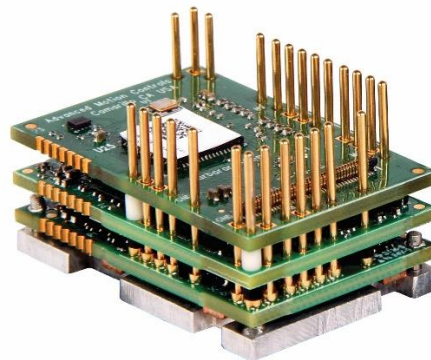
FE060-25-IPM

FlexPro® Series

Product Status: Active

SPECIFICATIONS

Current Peak	50 A
Current Continuous	25 A
DC Supply Voltage	10 – 55 VDC
Network Communication	Ethernet/IP



The **FE060-25-IPM** is a FlexPro® series servo drive with IMPACT™ architecture.

The **FE060-25-IPM** offers full tuning control of all servo loops and is designed to drive brushed and brushless servo motors, and closed loop stepper motors. The drive accepts a variety of external command signals, or can use the built-in Motion Engine, an internal motion controller used with Sequencing and Indexing commands. Programmable digital and analog I/O are included to enhance interfacing with external controllers and devices.

The **FE060-25-IPM** utilizes Ethernet/IP network communication and is configured via USB. All drive and motor parameters are stored in non-volatile memory. ADVANCED Motion Controls' Ethernet/IP protocol operates based on a control state machine as defined by CANopen standards. CIP Motion and CIP Sync are not currently supported.

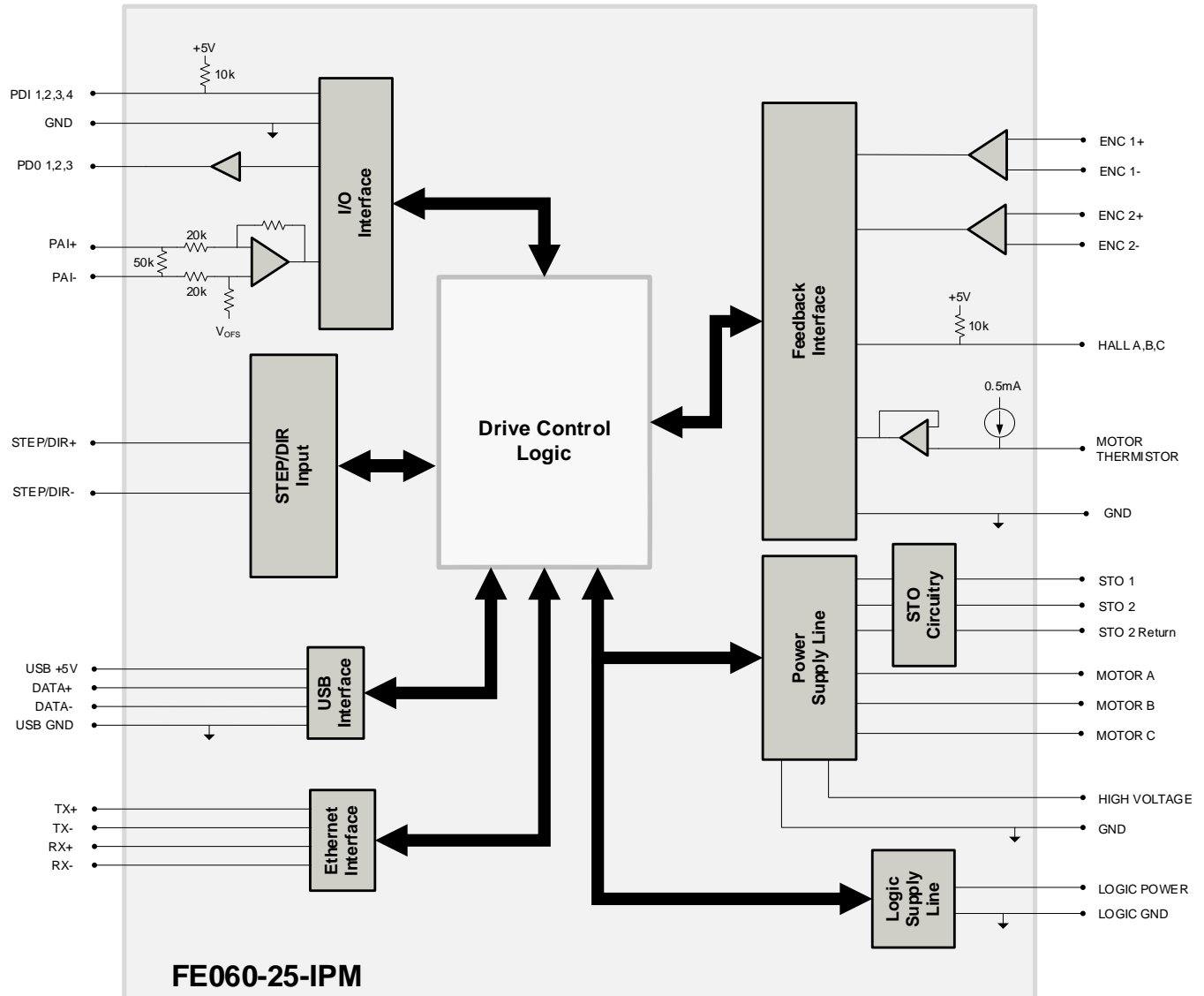
IMPACT™ (Integrated Motion Platform And Control Technology) combines exceptional processing capability and high-current components to create powerful, compact, feature-loaded servo solutions. IMPACT™ is used in all FlexPro® drives and is available in custom products as well.

FEATURES

- Four Quadrant Regenerative Operation
- Programmable Gain Settings
- PIDF Velocity Loop
- Compact Size, High Power Density
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching
- Dedicated Safe Torque Off (STO) Inputs
- Space Vector Modulation (SVM) Technology

Feedback Supported	<ul style="list-style-type: none"> • Absolute Encoder <ul style="list-style-type: none"> ◦ BiSS C-Mode • Incremental Encoder • Hall Sensors • Aux Incremental Encoder • Tachometer (±10V) 	Motors Supported	<ul style="list-style-type: none"> • Three Phase • Single Phase • Stepper 	Modes of Operation	<ul style="list-style-type: none"> • Profile Modes • Current • Velocity • Position
Command Sources	<ul style="list-style-type: none"> • Over the Network • ±10V Analog • Sequencing • Indexing • Jogging • Step & Direction • Encoder Following 	Inputs / Outputs	<ul style="list-style-type: none"> • 4 Programmable Digital Inputs • 3 Programmable Digital Outputs • 1 Programmable Analog Input 	Agency Approvals	<ul style="list-style-type: none"> • RoHS • UL/cUL • CE Class A (LVD) • CE Class A (EMC) • TUV Rheinland (STO) (Pending)

BLOCK DIAGRAM



INFORMATION ON APPROVALS AND COMPLIANCES



US and Canadian safety compliance with UL/IEC 61800-5-1, the industrial standard for adjustable speed electrical power drive systems. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.

Compliant with European EMC Directive 2014/30/EU on Electromagnetic Compatibility (specifically EN 61000-6-4:2007/A1:2011 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2014/35/EU (specifically, EN 60204-1:2019, a Low Voltage Directive to protect users from electrical shock).

The RoHS Directive restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

Sold & Serviced By:



Canadian and International Sales

ELECTROMATE

877-737-8698

sales@electromate.com

www.electromate.com

U.S. Sales

SERVO2GO.com

877-378-0240

sales@servo2go.com

www.servo2go.com

SPECIFICATIONS

Description		Electrical Specifications		Value
		Units		
Nominal DC Supply Input Range		VDC	12 – 48	
DC Supply Input Range		VDC	10 – 55	
DC Supply Undervoltage		VDC	8	
DC Supply Overvoltage		VDC	58	
Logic Supply Input Range (optional)		VDC	10 – 55	
Safe Torque Off Voltage (Default)		VDC	5	
Minimum Required External Bus Capacitance		µF	500	
Maximum Peak Current Output ¹		A (Arms)	50 (35.3)	
Maximum Continuous Current Output ²		A (Arms)	25 (25)	
Efficiency at Rated Power		%	99	
Maximum Continuous Output Power		W	1361	
Maximum Power Dissipation at Rated Power		W	14	
Minimum Load Inductance (line-to-line) ³		µH	150 (@ 48VDC supply); 75 (@24VDC supply); 40 (@12VDC supply)	
Switching Frequency		kHz	20	
Maximum Output PWM Duty Cycle		%	83	
Description		Control Specifications		Value
		Units		
Communication Interfaces		-	Ethernet/IP (USB for configuration)	
Command Sources		-	±10 V Analog, Over the Network, Sequencing, Indexing, Jogging, Step & Direction, Encoder Following	
Feedback Supported		-	Absolute Encoder (BiSS C-Mode), Hall Sensors, Incremental Encoder, Auxiliary Incremental Encoder, Tachometer (±10V)	
Commutation Methods		-	Sinusoidal, Trapezoidal	
Modes of Operation		-	Profile Modes, Current, Velocity, Position	
Motors Supported ⁴		-	Three Phase (Brushless Servo), Single Phase (Brushed Servo, Voice Coil, Inductive Load), Stepper (2- or 3-Phase Closed Loop)	
Hardware Protection		-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs		-	4/3	
Programmable Analog Inputs/Outputs		-	1/0	
Primary I/O Logic Level		-	5 VDC, not isolated	
Current Loop Sample Time		µs	50	
Velocity Loop Sample Time		µs	100	
Position Loop Sample Time		µs	100	
Maximum Encoder Frequency		MHz	20 (5 pre-quadrature)	
Description		Mechanical Specifications		Value
		Units		
Size (H x W x D)		mm (in)	38.1 x 25.4 x 16.0 (1.50 x 1.00 x 0.61)	
Weight		g (oz)	22.7 (0.8)	
Ambient Operating Temperature Range ⁵		°C (°F)	0 – 65 (32 – 149)	
Storage Temperature Range		°C (°F)	-40 – 85 (-40 – 185)	
Relative Humidity		-	0-95%, non-condensing	
Form Factor		-	PCB Mounted	
P1 SIGNAL CONNECTOR*		-	80-pin 0.4mm spaced connector	
TERMINAL PINS		-	26x Terminal Pins	

Notes

1. Capable of supplying drive rated peak current for 2 seconds with 5 second foldback to continuous value. Longer times are possible with lower current limits.
2. Continuous I_{Arms} value attainable when RMS Charge-Based Limiting is used.
3. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
4. Maximum motor speed for stepper motors is 600 RPM. Consult the hardware installation manual for 2-phase stepper wiring configuration.
5. Additional cooling and/or heatsink may be required to achieve rated performance.

*Mating Connector Kit

Surface mount board connector for P1 and board spacers can be ordered as a kit using ADVANCED Motion Controls' part number **KC-MC1XFE01**.

Sold & Serviced By:



Canadian and International Sales

ELECTROMATE

877-737-8698

sales@electromate.com

www.electromate.com

U.S. Sales

SERVO2GO.com

877-378-0240

sales@servo2go.com

www.servo2go.com

PIN FUNCTIONS

P1 – Signal Connector							
Pin	Name	Description / Notes	I/O	Pin	Name	Description / Notes	I/O
1	GROUND	Ground	GND	2	GROUND	Ground	GND
3	PAI-1+	Differential Programmable Analog Input or Reference Signal Input (12-bit Resolution)	I	4	DATA+ USB	USB Data Channel	I/O
5	PAI-1-		I	6	DATA- USB		I/O
7	THERMISTOR	Motor Thermal Protection.	I	8	GROUND	Ground	GND
9	GROUND	Ground	GND	10	SCLA	I ² C Data Signals for Addressing, Network Error LED, and Bridge Status LED. See Hardware Manual for more info.	O
11	ENC 1 DATA+ / A+	Differential Data Line for Absolute Encoders (BiSS: SLO+/-) or Differential Incremental Encoder A.	I/O	12	SDAA		I/O
13	ENC 1 DATA- / A-		I/O	14	HALL A	Single-ended Commutation Sensor Inputs	I
15	ENC 1 CLK+ / B+	Differential Clock Line for Absolute Encoders (BiSS: MA+/-) or Differential Incremental Encoder B.	I/O	16	HALL B		I
17	ENC 1 CLK- / B-		I/O	18	HALL C		I
19	GROUND	Ground	GND	20	GROUND	Ground	GND
21	ENC 1 REF+ / I+	Differential Reference Mark for Absolute Encoders (Leave open for BiSS) or Differential Incremental Encoder Index.	I	22	ENC 2 A+	Differential Incremental Encoder A.	I
23	ENC 1 REF- / I-		I	24	ENC 2 A-		I
25	NET_STATUS	Network Status indicator. Function based on protocol specification. See Hardware Information below.	I/O	26	ENC 2 B+	Differential Incremental Encoder B.	I
27	RESERVED	Reserved. Do not connect.	-	28	ENC 2 B-		I
29	RESERVED	Reserved. Do not connect.	-	30	ENC 2 I+	Differential Incremental Encoder Index.	I
31	PDI-1	Programmable Digital Input	I	32	ENC 2 I-		I
33	PDI-2	Programmable Digital Input	I	34	PDO-1	Programmable Digital Output (TTL/8mA)	O
35	PDI-3	Programmable Digital Input	I	36	PDO-2	Programmable Digital Output (TTL/8mA)	O
37	PDI-4	Programmable Digital Input	I	38	PDO-3	Programmable Digital Output (TTL/8mA)	O
39	GROUND	Ground	GND	40	GROUND	Ground	GND
41	TX- IN	Transmit Line IN (100 Base TX)	I	42	TX- OUT	Transmit Line OUT (100 Base TX)	O
43	TX+ IN		I	44	TX+ OUT		O
45	RX- IN	Receive Line IN (100 Base TX)	I	46	RX- OUT	Receive Line OUT (100 Base TX)	O
47	RX+ IN		I	48	RX+ OUT		O
49	+3V BIAS IN	+3V Supply for Transformer/Magnetics Bias	O	50	+3V BIAS OUT	+3V Supply for Transformer/Magnetics Bias	O
51	LINK/ACT IN	Link and Activity Indicator for IN port.	I/O	52	LINK/ACT OUT	Link and Activity Indicator for OUT port.	I/O
53	MOD_STATUS	Module Status indicator. Function based on protocol specification. See Hardware Information below.	I/O	54	RESERVED	Reserved. Do not connect.	-
55	RESERVED	Reserved. Do not connect.	-	56	RESERVED	Reserved. Do not connect.	-
57	RESERVED	Reserved. Do not connect.	-	58	RESERVED	Reserved. Do not connect.	-
59	GROUND	Ground	GND	60	GROUND	Ground	GND
61	RESERVED	Reserved. Do not connect.	-	62	RESERVED	Reserved. Do not connect.	-
63	RESERVED	Reserved. Do not connect.	-	64	RESERVED	Reserved. Do not connect.	-
65	RESERVED	Reserved. Do not connect.	-	66	RESERVED	Reserved. Do not connect.	-
67	RESERVED	Reserved. Do not connect.	-	68	STEP	Step Input.	I
69	RESERVED	Reserved. Do not connect.	-	70	DIR	Direction Input.	I
71	RESERVED	Reserved. Do not connect.	-	72	RESERVED	Reserved. Do not connect.	-
73	+5V_OUT	+5VDC unprotected supply (See Note 1)	O	74	RESERVED	Reserved. Do not connect.	-
75	+5V_USER	+5VDC User Supply for feedback and local logic (See Note 1)	O	76	+3V3 OUT	+3.3VDC Supply Output for local logic signals (100 mA max)	O
77	+5V_USER		O	78	+3V3 OUT		O
79	GROUND	Ground	GND	80	GROUND	Ground	GND

Notes

- Total current through pins P1-73/75/77 should not exceed 300mA, while no single pin should be loaded more than 150mA.

Sold & Serviced By:



Canadian and International Sales

ELECTROMATE

877-737-8698

sales@electromate.com

www.electromate.com

U.S. Sales

SERVO2GO.com

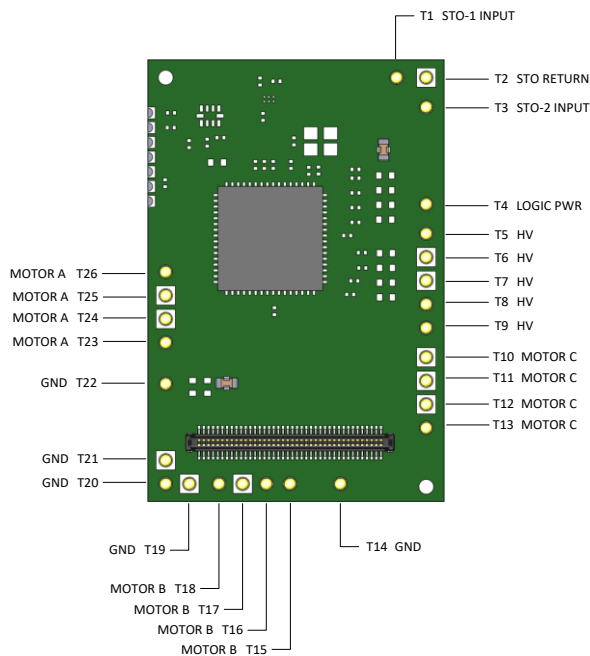
877-378-0240

sales@servo2go.com

www.servo2go.com

TERMINAL PIN LOCATIONS

The 26 Terminal Pins provide connection to the high power drive signals. Terminal Pins must be soldered to an interface board.



Pin	Name	Description / Notes	I/O
T1	STO-1 INPUT	Safe Torque Off – Input 1	I
T2	STO RETURN	Safe Torque Off Return	STORET
T3	STO-2 INPUT	Safe Torque Off – Input 2	I
T4	LOGIC PWR	Logic Supply Input (10 – 55VDC) (optional)	I
T5	HV	DC Supply Input (10-55VDC). Minimum 500µF external capacitance required between HV and POWER GND.	I
T6	HV		I
T7	HV		I
T8	HV		I
T9	HV		I
T10	MOTOR C	Motor Phase C. All provided motor phase output pins must be used.	O
T11	MOTOR C		O
T12	MOTOR C		O
T13	MOTOR C		O
T14	POWER GND	Ground.	GND
T15	MOTOR B	Motor Phase B. All provided motor phase output pins must be used.	O
T16	MOTOR B		O
T17	MOTOR B		O
T18	MOTOR B		O
T19	POWER GND	Ground.	GND
T20	POWER GND		GND
T21	POWER GND		GND
T22	POWER GND		GND
T23	MOTOR A	Motor Phase A. All provided motor phase output pins must be used.	O
T24	MOTOR A		O
T25	MOTOR A		O
T26	MOTOR A		O

Terminal Pin Details

Safe Torque Off (STO) Inputs

The Safe Torque Off (STO) inputs are dedicated +5VDC sinking single-ended inputs. For applications not using STO functionality, disabling of the STO feature is required for proper drive operation. STO may be disabled by following the STO Disable wiring instructions as given in the hardware installation manual. Consult the hardware installation manual for more information.

Sold & Serviced By:



Canadian and International Sales

ELECTROMATE

877-737-8698

sales@electromate.com

www.electromate.com

U.S. Sales

SERVO2GO.com

877-378-0240

sales@servo2go.com

www.servo2go.com

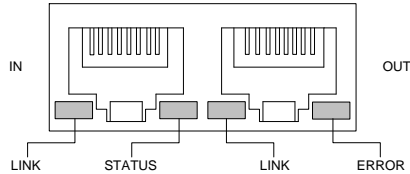
HARDWARE INFORMATION

LED Functionality

LINK/ACT IN (P1-51); LINK/ACT OUT (P1-52); STATUS (P1-53);

The LINK/ACT IN, LINK/ACT OUT, MOD_STATUS, and NET_STATUS pins serve as Ethernet/IP network indicators. On a standard RJ-45 connector used with Ethernet/IP network topology, the typical network indicator LED locations are as shown in the below diagrams.

Note that the drive features signals for connection to LEDs on an RJ-45 connector, but the connector itself is not included on the drive.



LINK/ACT IN and LINK/ACT OUT are used to drive the corresponding LINK IN and LINK OUT LEDs on a typical RJ-45 connector. The MOD_STATUS pin is used to drive the Module Status LED, and the NET_STATUS pin is used to drive the Network Status LED. Consult the hardware installation manual for recommended wiring connections. The LED Function Protocol tables below describe typical LED functionality.

Communication Status LED Functions (on RJ-45 Communication Connectors)

LED	Description	
MODULE STATUS	Off	No power
	Green	Device Operational
	Flashing Green	Standby
	Flashing Red	Minor Fault
	Red	Major Fault
	Flashing Green/Red	Self-test
NETWORK STATUS	Off	Not powered, no IP address
	Flashing Green	No connections
	Green	Connected
	Flashing Red	Connection Timeout
	Red	Duplicate IP address
	Flashing Green/Red	Self-test

Sold & Serviced By:



Canadian and International Sales

ELECTROMATE

877-737-8698

sales@electromate.com

www.electromate.com

U.S. Sales

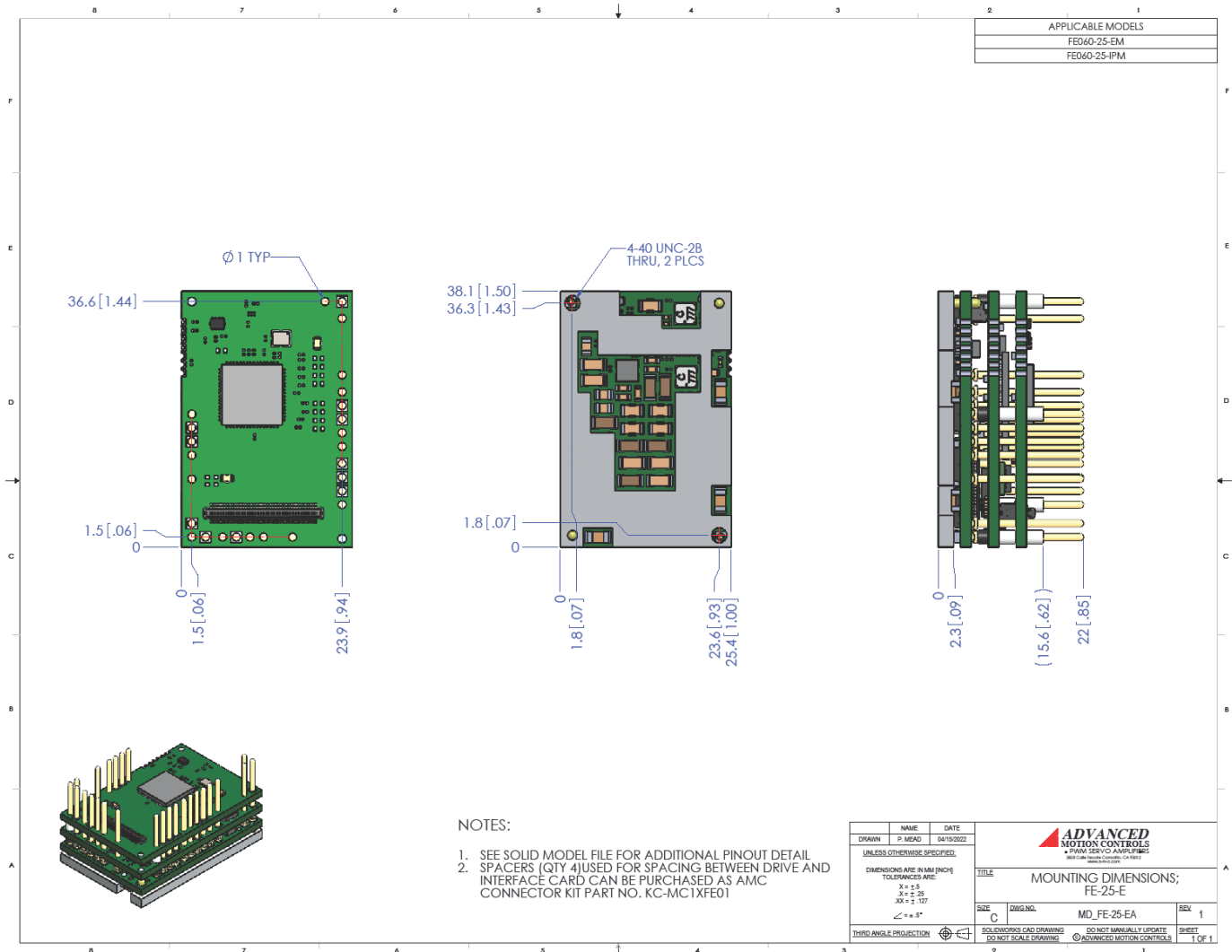
SERVO2GO.com

877-378-0240

sales@servo2go.com

www.servo2go.com

MOUNTING DIMENSIONS



Sold & Serviced By:



Canadian and International Sales

ELECTROMATE

877-737-8698

sales@electromate.com

www.electromate.com

U.S. Sales

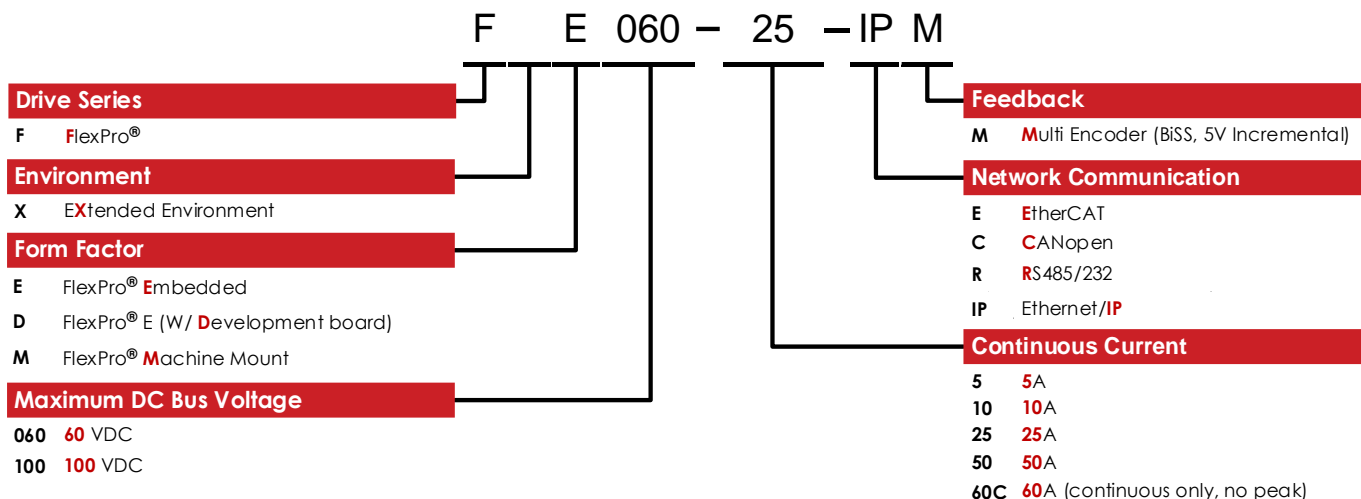
SERVO2GO.com

877-378-0240

sales@servo2go.com

www.servo2go.com

PART NUMBERING AND CUSTOMIZATION INFORMATION



ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- | | |
|--|--|
| <ul style="list-style-type: none"> ▲ Optimized Footprint ▲ Private Label Software ▲ OEM Specified Connectors ▲ No Outer Case ▲ Increased Current Resolution ▲ Increased Temperature Range ▲ Custom Control Interface ▲ Integrated System I/O | <ul style="list-style-type: none"> ▲ Tailored Project File ▲ Silkscreen Branding ▲ Optimized Base Plate ▲ Increased Current Limits ▲ Increased Voltage Range ▲ Conformal Coating ▲ Multi-Axis Configurations ▲ Reduced Profile Size and Weight |
|--|--|

Feel free to contact us for further information and details!

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

Sold & Serviced By:

Canadian and International Sales

ELECTROMATE
 877-737-8698
sales@electromate.com
www.electromate.com

U.S. Sales

SERVO2GO.com
 877-378-0240
sales@servo2go.com
www.servo2go.com