Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com

# ECNOTION®

direct drive in motion

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## Generation 2 ironless vacuum motor series



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## THE NEW BENCHMARK IN VACUUM MOTORS

Generation 2 vacuum ironless linear motor series is designed with the unique challenges of vacuum applications in mind and based on years of collaboration with high-end semiconductor manufacturers. The portfolio is suitable for even the strictest vacuum requirements with a large force range.

Optimal thermal properties, added safety, excellent RGA performance, lower outgassing and flexibility to install make the Generation 2 vacuum motor series the benchmark for motion in vacuum applications. With multiple winding types and coil unit sizes available, the Vacuum Generation 2 Series always offers the right direct drive motor.

#### We direct drive your motion technology

Tecnotion direct drive motors are seamlessly integrated in a wide range of applications such as semiconductors, machine tooling, robotics, display applications and printing industry. Being an independent supplier of linear- and torque motors Tecnotion provides specialized motor technology to place in customers motion solutions. As global technology leader with almost 30 years of experience we always offer the best motor solution for your motion needs, whether it is catalogue or custom. With a wealth of experience, we are accustomed to design and build any motion question.

### Ironless vacuum motors Powerful and precise processes

To minimize the chance of unwanted chemical reactions or pollution of the process or surrounding equipment, more and more high-tech applications require vacuum solutions, such as:

- > Lithography
- > Inspection
- > Display
- > Science & aerospace

One of the biggest challenges in a vacuum environment is heat transfer and motion. The closed design of the Generation 2 vacuum motors is optimized for low heat dissipation and optimal mounting. These features allow an easy system design which is suited for integration of multiple motors in one system.

#### Cost of ownership

Linear vacuum rated motors have no moving parts and are frictionless, making the motors maintenance free. Tecnotion's vacuum ironless motors can be placed in high vacuum as a whole and therefore require no feedthrough resulting in saving costs. The initial investment of vacuum linear motors can be higher than other drive systems but because of low maintenance costs, the total cost of ownership is reduced.

#### **Extremely low outgassing**

The production process can be affected by outgassing of the motion system. The vacuum ironless linear motors are specially designed coil units and magnetic yokes for use in high vacuum, up to 10<sup>-8</sup> mbar, and offer the lowest achievable outgassing for a series product\*.

\* Specifications concerning outgassing of the vacuum motor series are available. The outgassing values depend on materials and environmental conditions. Please contact us directly for advise in the specific application.





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#### UXXV - G2 Series

Fp1340 - 4020 N Fc 233 - 698 N

The UXXV coil is the most powerful and efficient coil in the vacuum rated linear motor series. The UXXV series is ideal for heavy duty applications, such as display production, that demand ultra-precision and maximum force output. With the longest available coil unit, the UXXV18 is perfectly suitable for long strokes.

Its efficiency and high motor constant allow for a low heat output while generating a high force.

#### ULV - G2 Series

Fp 720 N | Fc 165 N

The ULV coils are the medium size series in the high end vacuum rated linear motor series. The ULV series is commonly used for applications demanding peak force or low heat output, such as lithography and inspection.

In longer strokes ULV coils can be combined to save magnet material but still achieve high performance.

#### UMV - G2 Series

#### Fp 100 - 401 N | Fc 22 - 87 N

The UMV coils are the smallest coils in the vacuum rated linear motor series. Specifically suitable for low loads and tight spaces because of the short length.

This series is ideal for positioning, e.g. in science and aerospace, gantries, or other high dynamic, lightweight applications which require extreme accuracy.

### Features Ironless vacuum motor series

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#### Design

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The stainless steel strip on the body of the coil unit makes installation easy, reliable and repeatable. Together with the standard flying leads, this give the opportunity to design the wire management most suited for your application.

Bolt holes at the short side of the yoke allow for easy installation of optional shielding to lower stray fields. This ensures minimal interference in e-beam applications.

#### Unique design Fully enclosed to prevent outgassing

**Thermal management** Low thermal resistance (R<sub>th</sub>) Coil

#### Capabilities and outgassing

- > Coil unit and yoke are completely vacuum compatible
- ➤ Minimum pressure down to 10<sup>-8</sup> mbar
- > Typical total outgassing of 10<sup>-5</sup> mbar\*l/s
- > Typical C<sub>x</sub>H<sub>x</sub> outgassing of 10<sup>-8</sup> mbar\*l/s

RGA performance is excellent, because the coil units are fully enclosed in vacuum compatible stainless steel. The corresponding magnet yokes have vacuum compatible nickel coating. All other materials used that are exposed to the vacuum have been selected to minimize outgassing. The lower outgassing values result in shorter bake-out and pumping time.

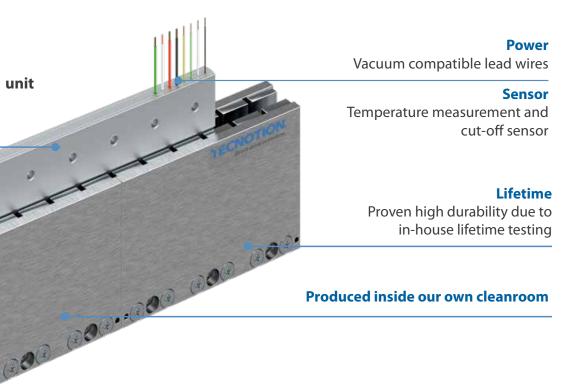
#### **Connection and sensors**

Monitoring and overheating protection of the coil is possible at all times because they are equipped with temperature measurement and cut-off sensors. Each phase is equipped with a NTC temperature sensor to monitor temperature levels. The sensors and three phases of the coil units are connected via vacuum compatible cables.

**Completely vacuum compatible** 



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#### Cleanliness

Tecnotion follows a strict production and cleaning protocol to ensure a high level of cleanliness is achieved when the vacuum motors are shipped. All products are subjected to a final inspection to assure they meet the stringent cleanliness levels. Once approved all products are packed securely to assure cleanliness up until the moment of installation.

#### **Thermal characteristics**

The enclosed coil units have an additional temperature sensor and improved thermal resistance ( $R_{th}$ ). These measures ensure that the temperature increase of the coil unit is minimized and the heat flow away from the application is optimized. This is paramount to minimize thermal expansion and thus maintain accuracy and repeatability. The stainless strip further facilitates heat flow away from the coil unit and lowers variation in thermal resistance.



UMV3 G2 coil unit in 150mm magnet yoke

Explanation of name U = Ironless MV = Series type/vacuum 3/6/12 = Number of coils N/S = Winding type

UMV G2 3 N

## UMV - G2 ironless vacuum series

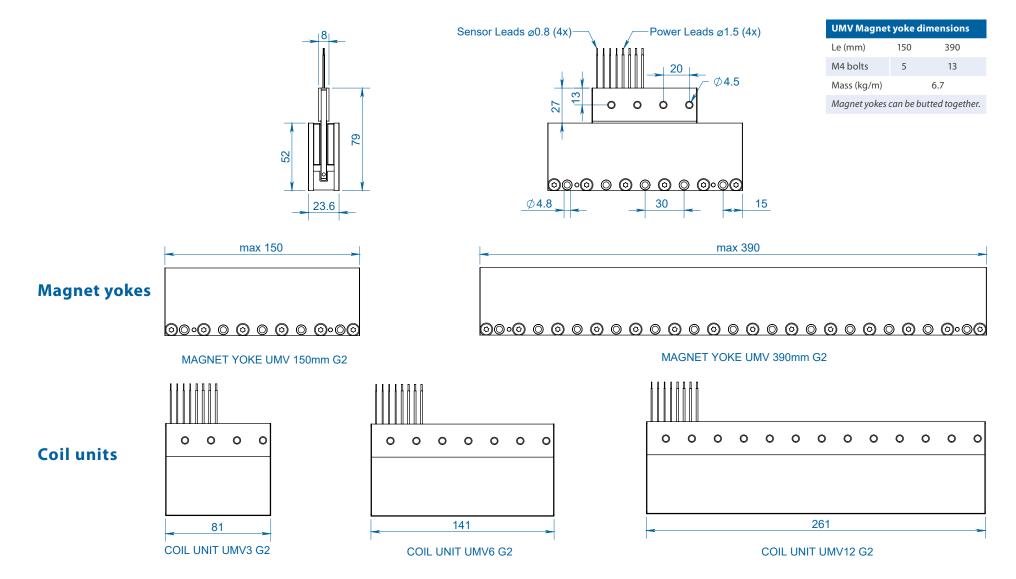
Parameter	Remarks	Symbol	Unit	UMV3 G2	UMV6 G2	UMV12 G2	
Winding type				S	S	N	S
Motortype, max voltage ph-ph	3-phase synchronous		$V_{acrms}(V_{dc})$		230 (325)		
e Peak force @ 20°C/s increase	magnet @ 25°C	Fp	Ν	100	200	400	401
Peak force @ 20°C/s increase Continuous force passive cooled* Continuous force active cooled**	@ T <sub>max</sub>	Fc	Ν	5.9	10.8	20	20
Continuous force active cooled**	@ T <sub>max</sub>	Fc	Ν	22	44	86	87
Maximum speed***	@ 325 V	V <sub>max</sub>	m/s	18.5	18.5	7.0	18.5
Motor force constant	coils @ 25°C	К	N/A <sub>rms</sub>	20.0	20.0	47.8	20.0
Motor constant	coils @ 25°C	S	N <sup>2</sup> /W	23	46	89	93
Peak current	magnet @ 25°C	l <sub>p</sub>	A <sub>rms</sub>	5.0	10.0	8.4	20.1
Max. cont. current passive cooled*	coils @ T <sub>max</sub>	l <sub>c</sub>	A <sub>rms</sub>	0.30	0.54	0.42	1.02
Max. cont. current active cooled**	coils @ T <sub>max</sub>	l <sub>c</sub>	A <sub>rms</sub>	1.09	2.18	1.79	4.36
Back EMF phase-phase		B <sub>emf</sub>	V <sub>dc</sub> / m/s	16	16	39	16
Back EMF phase-phase Resistance per phase	coils @ 25°C ex. cable	$R_{ph}$	Ω	5.8	2.9	8.5	1.4
Induction per phase	l < 0.6 lp	$L_{ph}$	mH	1.9	1.0	2.8	0.5
Electrical time constant	coils @ 25°C	$ au_e$	ms	0.3	0.3	0.3	0.3
Maximum continuous power loss	all coils	Pc	W	25	50	100	
Maximum coil temperature		T <sub>max</sub>	°C		80		
Thermal resistance	coils to mount. sfc.	R <sub>th</sub>	°C/W	2.4	1.2	0.	60
Thermal time constant*	up to 63% max coil temp.	$ au_{th}$	S		42	7	
Temperature cut-off / sensor					3xPTC +	+ 1xNTC	
Coil unit weight	ex. cables	W	kg	0.19	0.33	0.	61
Coil unit length	ex. cables	L	mm	81	141	20	51
Motor attraction force	Fa		Ν	0			
Motor attraction force Magnet pitch NN Lead wire weight	net pitch NN		mm	30			
Lead wire weight	all wires	m	g		4		
Lead wire type (Power, 4x)	length 1.0m	d	mm (AWG)	1.5 (20)			
Lead wire type (Sensor, 4x)	length 1.0m	d	mm (AWG)		0.8 (26)		

\* Depends on environmental conditions in the application. Continuous force noted has been determined with a typical thermal resistance value for passive cooling, and a vacuum chamber wall of 40°C. \*\* Depends on environmental conditions in the application. Continuous force noted has been determined with a thermal resistance of 0.02 K/W and a mounting surface of 20°C when the motor is driven

at max. continuous current.

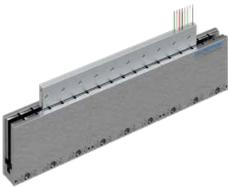
\*\*\* Actual values depend on bus voltage.

8 **IECNOTION** direct drive in motion All specifications  $\pm 10\%$ 



Mounting instructions and flatness or parallelism requirements can be found in the Ironless installation manual. 3D CAD files can be downloaded from our website.

\* All sizes are in mm



ULV9 G2 coil unit in 126mm magnet yokes

#### Explanation of name

U = Ironless
LV = Series type/vacuum
9 = Number of coils
N / S = Winding type

#### ULV G2 9 N

## ULV - G2 ironless vacuum series

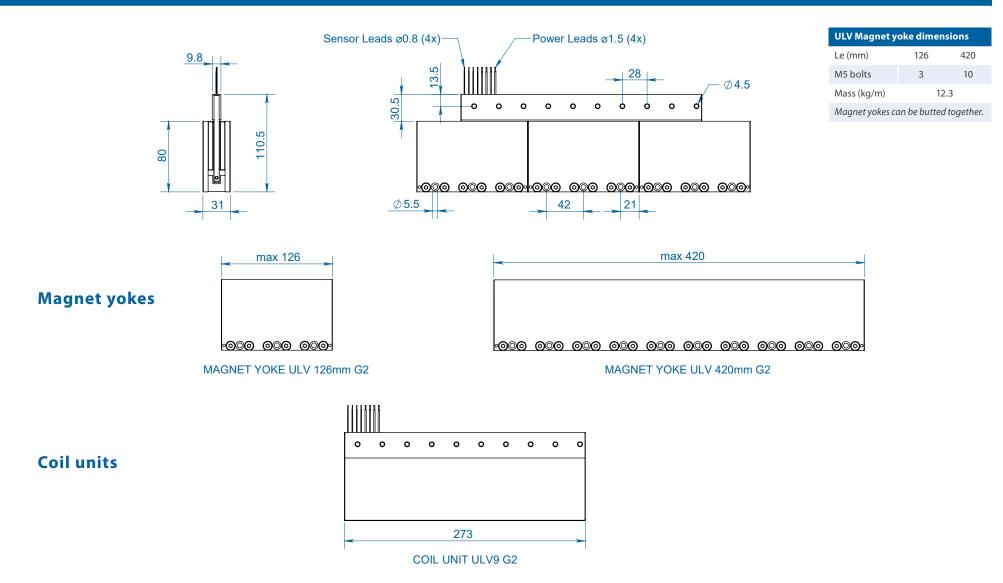
	Parameter	Remarks	Symbol	Unit	ULV9 G2	ULV9 G2		
Performance	Winding type				N	S		
	Motortype, max voltage ph-ph	3-phase synchronous		$V_{acrms}(V_{dc})$	230	(325)		
	Peak force @ 20°C/s increase	magnet @ 25°C	Fp	Ν	720	719		
	Continuous force passive cooled*	@ T <sub>max</sub>	Fc	Ν	41	41		
	Continuous force active cooled**	@ T <sub>max</sub>	Fc	Ν	164	165		
	Maximum speed***	@ 300 V	V <sub>max</sub>	m/s	5.0	13.6		
	Motor force constant	coils @ 20°C	К	N/A <sub>rms</sub>	68.0	27.3		
	Motor constant	coils @ 25°C	S	N <sup>2</sup> /W	275	278		
Electrical	Peak current	magnet @ 25°C	lp	A <sub>rms</sub>	10.6	26.3		
	Max. cont. current passive cooled*	coils @ T <sub>max</sub>	l <sub>c</sub>	A <sub>rms</sub>	0.61	1.52		
	Max. cont. current active cooled**	coils @ T <sub>max</sub>	l <sub>c</sub>	A <sub>rms</sub>	2.42	6.05		
	Back EMF phase-phase		$B_{emf}$	V <sub>dc</sub> / m/s	56	22		
	Resistance per phase	coils @ 25°C ex. cable	R <sub>ph</sub>	Ω	5.6	0.9		
	Induction per phase	l < 0.6 lp	$L_{ph}$	mH	4.4	0.7		
	Electrical time constant	coils @ 25°C	τ <sub>e</sub>	ms	0.8			
	Maximum continuous power loss	all coils	Pc	W	120			
_	Maximum coil temperature		T <sub>max</sub>	°C	80			
Thermal	Thermal resistance	coils to mount. sfc.	R <sub>th</sub>	°C/W	0.50			
The	Thermal time constant*	up to 63% max coil temp.	$\tau_{th}$	S	8	38		
	Temperature cut-off / sensor				3xPTC + 1xNTC			
	Coil unit weight	ex. cables	W	kg	1.10			
	Coil unit length	ex. cables	L	mm	273			
ical	Motor attraction force		Fa	Ν	0			
Mechanical	Magnet pitch NN		τ	mm	42			
Med	Lead wire weight	all wires	m	g	41			
	Lead wire type (Power, 4x)	length 1.0m	d	mm (AWG)	1.5 (20)			
	Lead wire type (Sensor, 4x)	length 1.0m	d	mm (awg)	0.8 (26)			

\* Depends on environmental conditions in the application. Continuous force noted has been determined with a typical thermal resistance value for passive cooling, and a vacuum chamber wall of 40°C. \*\* Depends on environmental conditions in the application. Continuous force noted has been determined with a thermal resistance of 0.02 K/W and a mounting surface of 20°C when the motor is driven

at max. continuous current.

\*\*\* Actual values depend on bus voltage.





#### Mounting instructions and flatness or parallelism requirements can be found in the Ironless installation manual. 3D CAD files can be downloaded from our website.

## **UXXV - G2 ironless vacuum series**



Explanation of name U = Ironless XXV = Series type/vacuum 6 / 9 / 18 = Number of coils N / S = Winding type

UXXV G2 18 N

	Parameter	Remarks	Symbol	Unit	UXXV6 G2	UXXV9 G2		UXXV18 G2
	Winding type				N	N	S	N
Performance	Motortype, max voltage ph-ph	3-phase synchronous		$V_{acrms}(V_{dc})$		230 (325)		
	Peak force @ 20°C/s increase	magnet @ 25°C	Fp	N	1340	2010	2012	4020
	Continuous force passive cooled*	@ T <sub>max</sub>	Fc	Ν	64	94	94	184
rfor	Continuous force active cooled**	@ T <sub>max</sub>	Fc	Ν	233	349	350	698
Pe	Maximum speed***	@ 300 V	V <sub>max</sub>	m/s	2.8	2.8	7.7	2.8
	Motor force constant	coils @ 20°C	К	N/A <sub>rms</sub>	117.5	117.5	47.7	117.5
	Motor constant	coils @ 25°C	S	N <sup>2</sup> /W	562	843	847	1686
	Peak current	magnet @ 25°C	lp	A <sub>rms</sub>	11.4	17.1	42.2	34.2
	Max. cont. current passive cooled*	coils @ T <sub>max</sub>	l <sub>c</sub>	A <sub>rms</sub>	0.55	0.80	1.98	1.56
	Max. cont. current active cooled**	coils @ T <sub>max</sub>	l <sub>c</sub>	A <sub>rms</sub>	1.98	2.97	7.34	5.94
Electrical	Back EMF phase-phase		B <sub>emf</sub>	V <sub>dc</sub> / m/s	96	96	39	96
Elect	Resistance per phase	coils @ 25°C ex. cable	$R_{ph}$	Ω	8.2	5.5	0.9	2.7
	Induction per phase	l < 0.6 lp	$L_{ph}$	mH	14.2	9.5	1.6	4.7
	Electrical time constant	coils @ 25°C	$ au_e$	ms		1.7		
	Maximum continuous power loss	all coils	Pc	W	118	176		353
_	Maximum coil temperature		T <sub>max</sub>	°C		80		
Thermal	Thermal resistance	coils to mount. sfc.	R <sub>th</sub>	°C/W	0.51	0.34		0.17
The	Thermal time constant*	up to 63% max coil temp.	$ au_{th}$	S		15	3	
	Temperature cut-off / sensor					3xPTC + 1xNTC		
	Coil unit weight	ex. cables	W	kg	1.74	2.54		4.95
	Coil unit length	ex. cables	L	mm	251	36	5	707
ical	Motor attraction force		Fa	Ν		C	)	
Mechanical	Magnet pitch NN		τ mm 57		7			
Med	Lead wire weight	all wires	m	g	55			
	Lead wire type (Power, 4x)	length 1.0m	d	mm (AWG)	1.75 (18)			
	Lead wire type (Sensor, 4x)	length 1.0m	d	mm (AWG)	0.8 (26)			

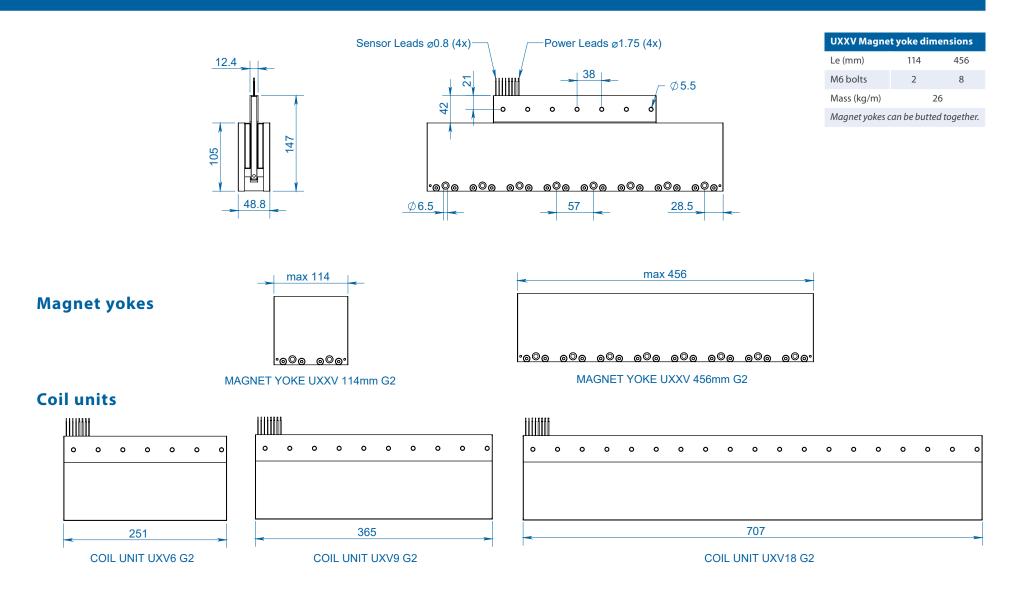
\* Depends on environmental conditions in the application. Continuous force noted has been determined with a typical thermal resistance value for passive cooling, and a vacuum chamber wall of 40°C. \*\* Depends on environmental conditions in the application. Continuous force noted has been determined with a thermal resistance of 0.02 K/W and a mounting surface of 20°C when the motor is driven

at max. continuous current.

\*\*\* Actual values depend on bus voltage.

All specifications  $\pm 10\%$ 





Mounting instructions and flatness or parallelism requirements can be found in the Ironless installation manual. 3D CAD files can be downloaded from our website.

\* All sizes are in mm

## We direct drive your motion technology





### Linear motors

### Unmatched acceleration and dynamic movements

Tecnotion's linear motor series excel in their force density ratings. They offer continuous force in a range of 10 Newton to 3000 Newton in a surprisingly small package.

Tecnotion provides linear solutions for most applications requiring a strong iron core linear motor or a highly dynamic ironless linear motor. www.tecnotion.com/linear

#### **Torque motors** Tu 0.64-2202 Nm Tc 0.27-907 Nm

Increased accuracy and dynamic performance of your application Tecnotion torque motor series features superior force density, low thermal resistance, low cogging and housed design.

The torque series consists of different outer diameters ranging from 65mm to 485mm for the largest motor and various building heights ranging from 17mm up to 105mm. www.tecnotion.com/torque **Custom motors** Motor solutions

### Adapt standard motor series to meet your needs

In case the standard motor series are not sufficient for your application, it is also possible to have these motors customized in a variety of ways. Customization can range from simple modifications, like adding a connector, to fully tailor-made motors designed from scratch.

Some examples: custom windings, cable confection, additional sensors, additional certifications and customization for vacuum applications. For more information please contact Tecnotion. www.tecnotion.com/custom

## Motor simulation tool

Analyze your application

### Size your application with the motor selection and simulation tool

Online motor simulation software helps you find the best motor for the application and generate reports within seconds, without having to make time consuming calculations by hand.

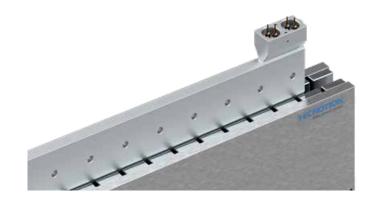
The motor sizing simulation tool helps to select the right torque or linear motor, using your application characteristics.

The tool will provide you with diagrams for position, velocity, acceleration, jerk, torque, power, voltage, current, temperature and torque vs. velocity. www.tecnotion.com/simtool



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## Custom ironless vacuum motor series

Generation 2 vacuum motor series are prepared for feedthrough instead of lead wires.

Contact us if your application is more demanding and has stricter outgassing requirements.

### **Article numbers**

Series	Article	Article code
VACUUM Generation 2	Coil unit UMV3S G2	114360
VACUUM Generation 2	Coil unit UMV6S G2	117288
VACUUM Generation 2	Coil unit UMV12N G2	117289
VACUUM Generation 2	Coil unit UMV125 G2	117290
VACUUM Generation 2	Magnet yoke UMV 150mm G2	114416
VACUUM Generation 2	Magnet yoke UMV 390mm G2	117295
VACUUM Generation 2	Coil unit ULV9N G2	117291
VACUUM Generation 2	Coil unit ULV9S G2	115773
VACUUM Generation 2	Magnet yoke ULV 126mm G2	117296
VACUUM Generation 2	Magnet yoke ULV 420mm G2	117297
VACUUM Generation 2	Coil unit UXV6N G2	117292
VACUUM Generation 2	Coil unit UXV9N G2	117293
VACUUM Generation 2	Coil unit UXV9S G2	117294
VACUUM Generation 2	Coil unit UXV18N G2	114389
VACUUM Generation 2	Magnet yoke UXXV 114mm G2	117298
VACUUM Generation 2	Magnet yoke UXXV 456mm G2	114411



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