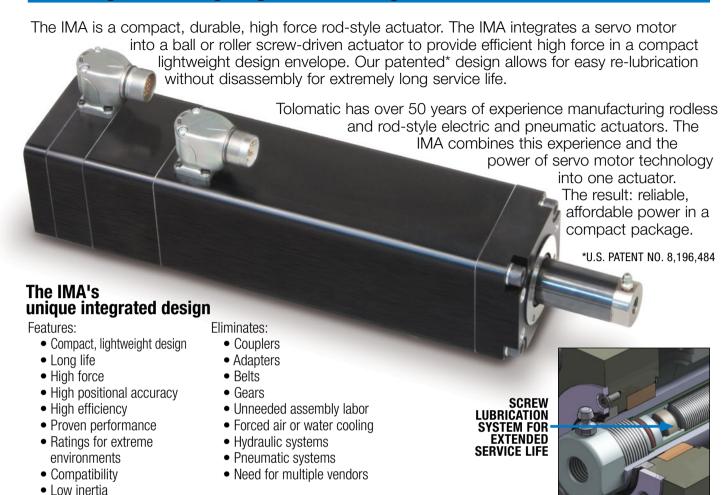


INTEGRATED MOTOR ROD-STYLE ACTUATOR



The longest lasting, high-force integrated actuator on the market!

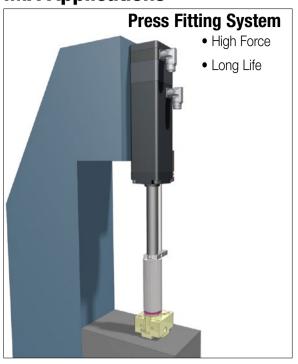


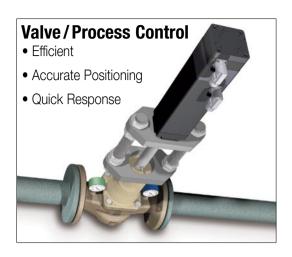
TOLOMATIC'S ELECTRIC ROD-STYLE ACTUATORS

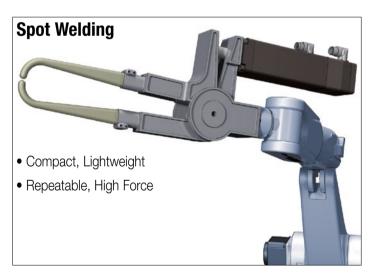
S

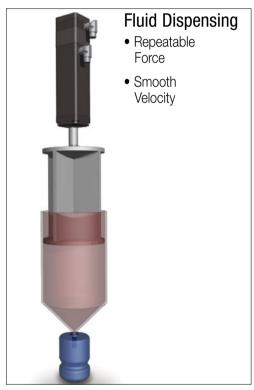
	ERD	ICR	RSA	GSA	<i>IMA</i>
	Rod-Style Actuator	Integrated Control Rod-Style Actuator	Rod-Style Actuator	Guided Rod-Style Actuator	Integrated Motor Rod-Style Actuator
Thrust up to:	4,500 lbf [20,017 N]	720 lbf [3,202.7 N]	13,039 lbf [58,001 N]	950 lbf [4,226 N]	6,875 lbf [30,594 N]
Speed up to:	58 in/sec [1473 mm/sec]	25 in/sec [635 mm/sec]	123 in/sec [3,124 mm/sec]	123 in/sec [3,124 mm/sec]	52.5 in/sec [1,334 mm/sec]
Stroke Length up to:	39.4 in [1000 mm]	24 in [609 mm]	60 in [1,524 mm]	36 in [914 mm]	18 in [457 mm]
Screw/Nut Type	Solid, Ball & Roller	Ball	Solid, Ball & Roller	Solid & Ball	Ball & Roller
	Fo	r complete informatior	n see www.tolomatic.c	om or literature numb	er: SELECTE
Literature Number:	2190-4000	2100-4000	3600-4609	3600-4609	2700H4000hone (87

IMA Applications









More Applications:

- Aerospace
- Animation
- Assembly
- Automated assembly
- Automatic tool changers
- Automotive
- Clamping
- Converting
- Conveyors
- Cycle testing
- Fillers

- Formers
- Hydraulic replacement
- Laser positioning
- Machine tools
- Material handling systems
- Medical equipment
- Military
- Molding
- Motion simulators
- Open/close doors
- Packaging equipment

- Parts clamping
- Patient lifts
- Pick & place
- Pneumatic replacement
- Precision grinders
- Product test simulations
- Riveting / fastening / joining
- Robot manipulator arms
- Sawmill equipment

- Semiconductor
- Stamping
- Table positioning
- Tension control
- Test stands
- Tube bending
- Volumetric pumps
- Water jet control
- Wave generation
- Web guidance
- Welding
- Wire winding



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IMA INTEGRATED MOTOR ACTUATOR

ENDURANCE TECHNOLOGY■

Endurance Technology features are designed for maximum durability to provide extended service life.

The IMA is a compact, durable, high force rod-style actuator. The IMA integrates a servo motor into a ball or roller screw-driven actuator to provide efficient high force in a compact lightweight design envelope. Our patented design allows for easy re-lubrication without disassembly for extremely long service life. Built-to-order in stroke lengths up to 18 inches with your choice of screw technology.

• MULTIPLE SCREW TECHNOLOGIES • YOU CAN CHOOSE:

 Ball nuts offer efficiency at a cost effective price

•Roller nuts provide the highest thrust and life ratings available





HIGH POSITIONAL ACCURACY

SCREW ACCURACY

Roller Nut ± 0.0004 "/ft. ± 0.0102 mm/300mm Ball Nut ± 0.002 "/ft. ± 0.051 mm/300mm

OINTERNAL BUMPERSO

•Bumpers protect the screw and nut assembly from damage at end of stroke

• REPLACEABLE ROD WIPER •

 Prevents contaminants from entering the actuator for extended life

• GREASE PORT ○

- •Screw re-lubrication system provides extended screw service life
- Convenient lubrication without disassembly (IMA22 is lubed for life and does not include grease port)

INTEGRAL MOUNTING

•Four metric threaded holes on front face are available for direct mounting or addition of customized options

othreaded rod end≎

- Zinc plated alloy steel construction for corrosion resistance
- Provides a common interface to multiple rod end options

THRUST TUBE

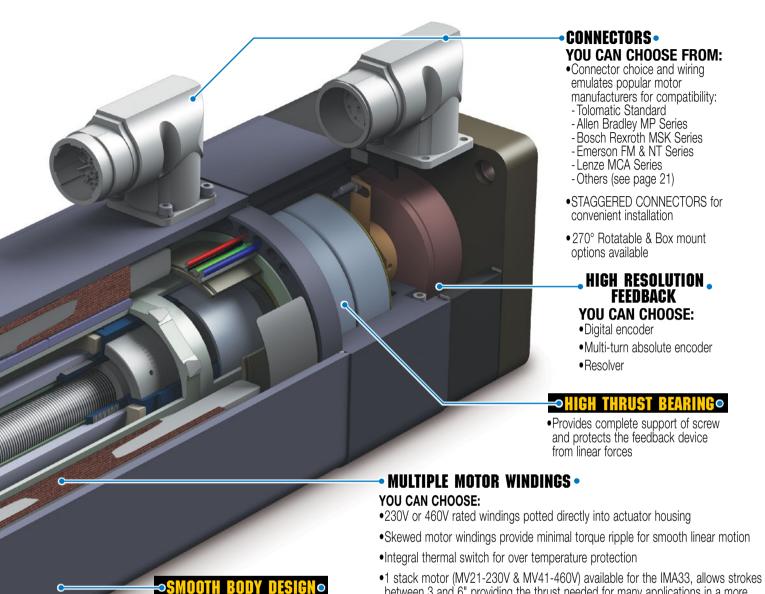
- •Steel thrust tube supports extremely high force capabilities
- Salt bath nitride treatment provides excellent corrosion resistance, surface hardness and is very resistant to adherence of weld slag, water and other potential contaminants

ALUMINUM DESIGN

Black anodized extrusion
 design is optimized for addity
 and strength
 ELECTROMAT

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Tolomatic... MAXIMUM DURABILITY





Modifications:

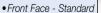
 Contact Tolomatic for stainless steel, manual override. food grade or mil-spec versions of the IMA (See the white epoxy IMA on the next page)

OPTIONS

Eliminates potential contaminant

collection points

MOUNTING



· Side Mounting Holes, 2 sides & bottom (no photo)





compact, lighter weight package



• Rear Clevis



between 3 and 6" providing the thrust needed for many applications in a more



Front Flange



• Trunnion, Rear or Front

ROD END

CABLES

• Internal Thread - Standard

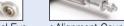












Spherical Eve

Alignment Coupler

IP67 • For protection against water and dust ingress



Anti- Toll







• 24V Spring held electronically released

• Signal Cable (6m)

• Power Cable (6m)



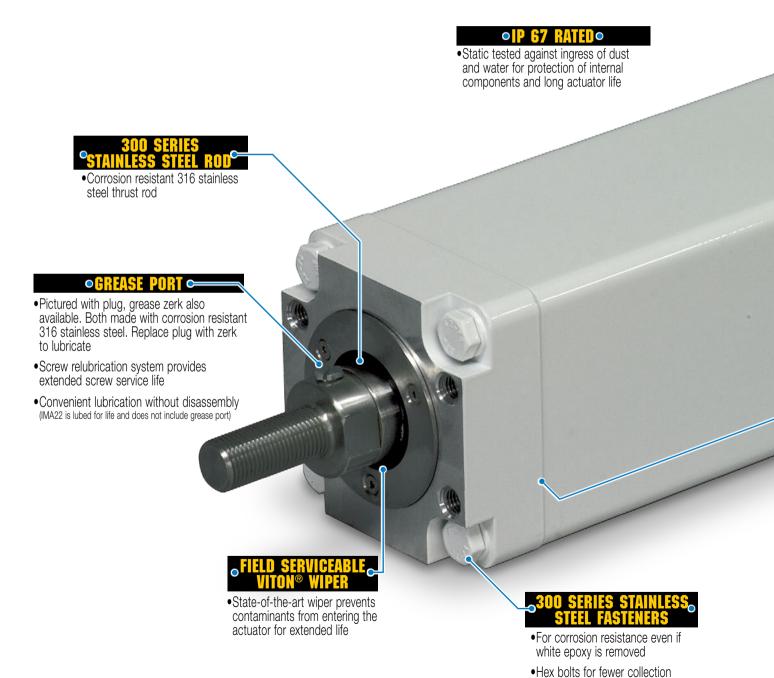
Rotate

FOOD GRADE IMA

○ENDURANCE TECHNOLOGY ○

Endurance Technology features are designed for maximum durability to provide extended service life.

The standard production IMA is a highly capable actuator with an environmental rating of IP65. Yet the world of industrial automation places actuators in increasingly challenging environments. The white epoxy IMA has all the features of the IMA shown on the previous pages plus these features that are suited to challenging environments.



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points for contaminents in wash-down environments sold & Serviced By:





 Fewer collection points for contaminants in wash-down environments

Modifications That Expand the Operating Environment of the IMA

The IMA can support the following modifications. many included on the white epoxy IMA featured. Contact Tolomatic with your requirements.



Food Grade Greases provide the lubrication actuators require and comply with international food/health & safety regulations. They are nontoxic, inert, tasteless and odorless. Contact Tolomatic for specific grease options and availability for your application.



Stainless Steel Fasteners for all external assembly and mounting on the



Stainless Steel Exterior Components provide corrosion resistance and may change the overall shape and external design of the Tolomatic actuator. Contact Tolomatic to determine the type of stainless steel to be used based on the application environment.



Food-grade White Epoxy Paint applied to all external components for corrosion resistance. Contact Tolomatic for the best corrosion resistant option for the application environment.



Purge Port: Through this port air is added into the Tolomatic electric actuator. Positive air pressure exhausts air out through the small entry points, minimizing the potential of particulate ingress into the actuator.



IP67: INGRESS PROTECTION: FIRST DIGIT = Solids, 6 = Dust Tight (No. ingress of dust; complete protection against contact) SECOND DIGIT = Liquids, 7 = Immersion up to 1 m (Ingress of water in harmful quantity shall not be possible when the enclosure is immersed in water under defined conditions of pressure and time up to 1 m of submersion).

IP69K: INGRESS PRUTEUTION: definial statement of the property IP69K: INGRESS PROTECTION: German standard DIN 40050-9 extends the must not only be dust tight (IP6X), but also able to withstand high pressures

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and steam cleaning.

OPTIONS MOUNTING

 Viton®, a high performance elastomer, has a proven reputation for outstanding

performance in hot and corrosive

environments.

- Front Face Standard
- Side Mounting Holes, Rear Clevis 2 sides & bottom (no photo)







 Trunnion, Rear or Front

Performance & Mechanical Specifications:

	SERIES	IMA22 (1 Stack, MV21/41)	IMA22 (3 Stack, MV23/43)		IMA33 (1	Stack, N	IV21/41)			IMA33 (3	S Stack, N	/IV23/43)	
NUT	/SCREW	BN05	BN05	BN05	BN10	BN20	RN05	RN10	BN05	BN10	BN20	RN05	RN10
CODEWLEAD	in	0.197	0.197	0.197	0.394	0.788	0.197	0.394	0.197	0.394	0.788	0.197	0.394
SCREW LEAD	mm	5	5	5	10	20	5	10	5	10	20	5	10
DYNAMIC	lbf	1,286	1,286	1,958	1,214	2,560	10,211	6,805	1,958	1,214	2,560	10,211	6,805
(1 mil revs)	N	5,720	5,720	8,710	5,400	11,387	45,421	30,270	8,710	5,400	11,387	45,421	30,270
CONT.	lbf	200	325	365	183	92	350	175	900	450	225	850	425
THRUST	N	890	1,446	1,624	814	409	1,557	778	4,003	2,002	1,001	3,781	1,891
PEAK	lbf	325	325	1,000	549	276	1,050	525	1,000	900	675	1,700	850
THRUST	N	1,446	1,446	4,448	2,442	1,228	4,671	2,335	4,448	4,003	3,003	7,562	3,781
MAX.	in/sec	14	14	12	24	48	12	24	11.5	23	46	11.5	23
VELOCITY	mm/sec	356	356	305	610	1,219	305	610	292	584	1,168	292	584
**BASE	lb-in ²	0.3078	0.5078	0.9464	0.9537	1.0253	0.9525	0.9618	1.6645	1.6717	1.7832	1.6723	1.6815
INERTIA	kg-cm²	0.9007	1.4859	2.7696	2.7908	3.0003	2.7874	2.8145	4.8709	4.8922	5.2184	4.8937	4.9208
INERTIA PER UNIT OF	lb-in²/in	0.00123	0.00123	0.00266	0.00313	0.01211	0.00358	0.00413	0.00266	0.00313	0.01211	0.00358	0.00413
STROKE	kg-cm²/mm	0.00014	0.00014	0.00031	0.00036	0.00140	0.00041	0.00048	0.00031	0.00036	0.00140	0.00041	0.00048
BREAKAWAY	in-lb	3.0	3.0	4.8	4.8	4.8	5.3	5.3	4.8	4.8	4.8	5.3	5.3
TORQUE	N-m	0.34	0.34	0.54	0.54	0.54	0.60	0.60	0.54	0.54	0.54	0.60	0.60
BACK DRIVE	lbf	49	49	78	39	20	78	39	78	39	20	78	39
FORCE*	N	218	218	347	173	89	347	173	347	173	89	347	173

	SERIES			IMA44					IMA55		
NUT	/SCREW	BN05	BN10	BN25	RN05	RN10	BN05	BN10	BN20	RN05	RN10
SCREW LEAD	in	0.197	0.394	0.985	0.197	0.394	0.197	0.394	0.788	0.197	0.394
SUNEW LEAD	mm	5	10	25	5	10	5	10	20	5	10
DYNAMIC	lbf	4,035	3,372	2,537	12,703	12,703	6,714	7,476	5,528	21,973	11,750
(1 mil revs)	N	17,949	15,000	11,285	56,506	56,506	29,865	33,255	24,590	97,741	52,288
CONT.	lbf	1,750	875	350	1,650	825	2,950	1,475	738	2,750	1,375
THRUST	N	7,784	3,892	1,557	7,340	3,670	13,128	6,564	3,283	12,238	6,119
PEAK	lbf	2,000	1,750	700	3,300	1,650	3,000	2,950	1,845	6,875	2,750
THRUST	N	8,896	7,784	3,114	14,679	7,340	13,350	13,128	8,207	30,594	12,238
MAX.	in/sec	11.5	23	52.5	11.5	23	7.9	15.7	31.4	7.9	15.7
VELOCITY	mm/sec	292	584	1,334	292	584	201	399	797	201	399
**BASE	lb-in ²	3.4193	3.4329	3.5276	3.3442	3.3602	26.6260	26.6684	26.8318	26.1949	26.2425
INERTIA	kg-cm²	10.0063	10.0459	10.3231	9.7864	9.8334	77.9185	78.0428	78.5208	76.6569	76.7962
INERTIA	lb-in²/in	0.01811	0.01872	0.02303	0.00984	0.01056	0.15246	0.15385	0.15939	0.11051	0.11204
PER UNIT OF STROKE	kg-cm²/mm	0.00209	0.00216	0.00265	0.00113	0.00122	0.01757	0.01773	0.01836	0.01273	0.01291
BREAKAWAY	in-lb	5.6	5.6	5.6	6.2	6.2	9.4	9.4	9.4	10.3	10.3
TORQUE	N-m	0.63	0.63	0.63	0.70	0.70	1.06	1.06	1.06	1.16	1.16
BACK DRIVE	lbf	91	46	18	91	46	153	77	38	152	76
FORCE*	N	405	205	80	405	205	681	343	169	676	338

Performance data was validated using an aluminum face mount plate: IMA22/33 (8.25" x 7.0" x 0.7"); IMA44 (9.0" x 9.0" x 0.7"); IMA55 (9.0"

Ambient Temperature = 77°F (25°C); Elevation < 3281' (1,000 m); Drive specifications: Sinusoidal Commutation and PWM Voltage Source Toll Free Phone (877) SERV098
*In vertical applications an unpowered IMA will require a brake to maintain position if the load on the actuator exceeds this value

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^{**}Value given is for a zero stroke actuator † To be determined, visit www.tolomatic.com for up-to-date information

Performance & Mechanical Specifications:

		SERIES	IMA22 (1 Stack, MV21/41)	IMA22 (3 Stack, MV23/43)	IMA33 (1 Stack, MV21/41)	IMA33 (3 Stack, MV23/43)	IMA44	IMA55		
FACE	CITE	in	2.5		3.3		4.4	5.6		
PAGE	SIZE	mm	63.5		8	3	110	142		
STROKE		in	3.0 to 12.0	6.0 to 12.0	3.0 to 18.0	6.0 to	18.0	6.0 to 18.0		
311	IUKE	mm	76.2 to 304.8	152.4 to 304.8	76.2 to 457.2	152.4 to	0 457.2	152.4 to 457.2		
**BASE WE	IСПТ	lb	5.3	6.4	11.4	14.1	28.6	54.5		
DAGE WE	iuni	kg	2.4	2.9	5.2	6.4	13	24.8		
WEIGHT PER UNIT OF ST	DUNE	lb/in	0.2428		0.6603		1.1035	2.1115		
WEIGHT PER UNIT UP 31	NUNE	kg/mm	0.0073			118	0.0197	0.03771		
SCREW LEAD ACCURACY	BN		in/ft = 0.002 $mm/300 = 0.051$ (0.004 in/ft for IMA33BN20 and IMA44BN25)							
SUNEW LEAD ACCORACT	RN	in/ft = 0.0004 mm/300 = 0.0102								
SCREW LEAD BACKLASH	BN	in = 0.004 $mm = 0.1$								
SUILW LLAD DAUKLASII	RN		in = 0.0012							
TEMP RA	NCE	°F	°F 50 to 104 (Contact Tolomatic if higher temperature is required)							
I LIVII 117	MUL	°C		10 to 40 (C	Contact Tolomatic if	higher temperature	is required)			
IP RA	TING			Standard	IP65, Optional IP6	7 (Static)				
REL. HUM (NON-CONDI					5 to 90%					
SH	IOCK			20g	peak, 6 msec dura	ation				
VIBRA	TION			2	.5g 302,000 H	-lz				

^{*}In vertical applications an unpowered IMA will require a brake to maintain position if the load on the actuator exceeds this value

Motor Specifications:

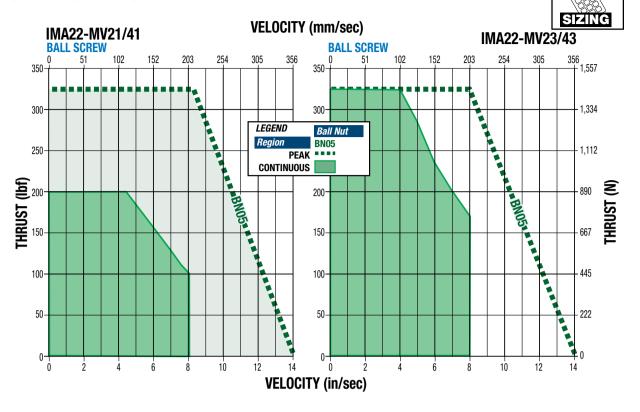
	SERIES		IM	A22			IM	A33		IMA44		IMA55	
WINDING/MOTO	R VOLTAGE	MV21	MV41	MV23	MV43	MV21	MV41	MV23	MV43	MV23	MV43	MV23	MV43
TORQUE	in-Ib/A Peak	3.3	6.6	4.3	8.2	5.4	10.7	5.5	10.7	5.4	10.6	6.7	13.4
CONSTANT (K _t)	N-m/A Peak	0.37	0.74	0.49	0.93	0.61	1.21	0.62	1.21	0.61	1.20	0.76	1.51
VOLTAGE Constant (K _e)	V/Krpm Peak	51	102	61	122	81	160	79.8	154	78.1	153.1	100	201
CONTINUOUS	in-lb	7	.5	13	3.3	1	6	39	38	74	75	112	112
STALL TORQUE	N-m	0.	85	1.	1.50		.8	4.4	4.3	8.4	8.5	12.7	12.7
CONTINUOUS STALL CURRENT	Arms	1.6	0.8	2.2	1.15	2.1	1.1	5	2.5	9.7	5	11.8	5.9
PEAK TOROUE	in-lb	22	2.5	39	9.9	4	.8	117	114	222	225	280	280
PEAK TURQUE	N-m	2.	54	4	.5	5.4		13.2	12.9	25.1	25.4	25.3	25.3
PEAK CURRENT	Arms	4.8	2.4	6.6	3.45	6.3	3.3	15	7.5	29.1	15	29.5	14.8
RESISTANCE	Ohms	18.1	72.4	7.1	28.3	10	40.1	2.07	8.3	0.58	2.32	0.57	2.93
INDUCTANCE	mH	10.7	42	4.5	18	13.6	54.1	3.8	15	2.75	11.5	1.4	5.8
NO. OF POLES								8					
BUS VOLTAGE	Vrms	230	460	230	460	230	460	230	460	230	460	230	460
SPEED @ Rated v	RPM			4,2	264				3,5	500		2,	QQ Service

RoHs Compliant Components;

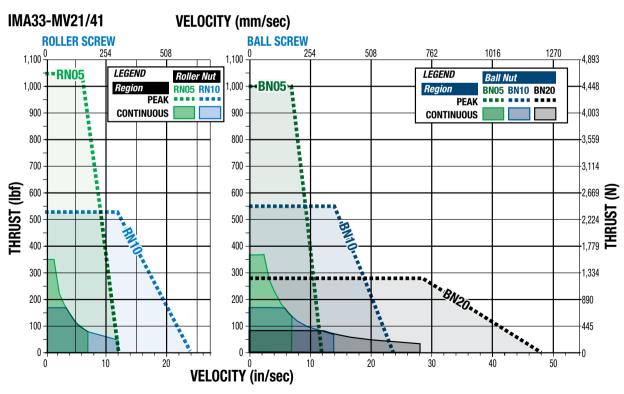
c₩°us (€.

^{**}Value given is for a zero stroke actuator

SPEED vs THRUST



ON-LINE SIZING Available at www. Tolomatic.com Actuator

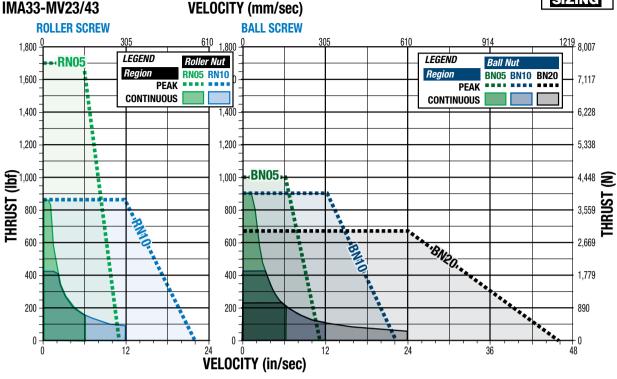


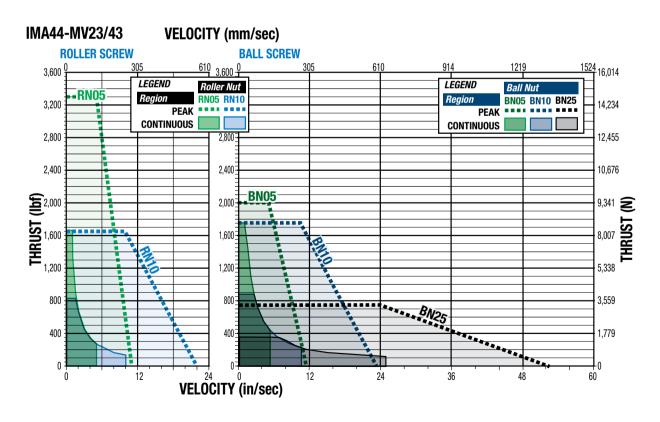
PEAK REGION is the maximum performance capabilities of the actuator system. Higher peak thrusts are achievable by servo motor actuator systems, so please consult Tolomatic before exceeding catalog rating.

SPEED vs THRUST



ELECTROMATE

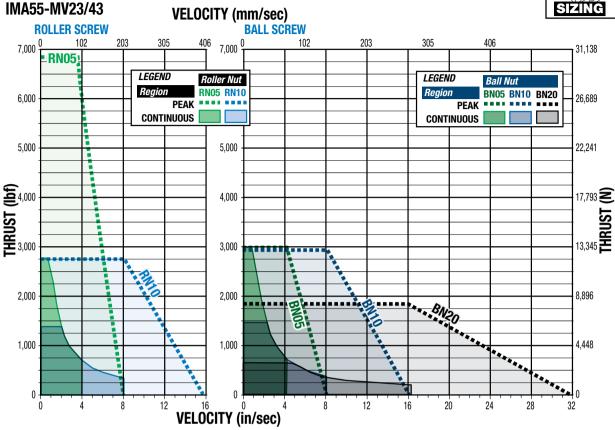




PEAK REGION is the maximum performance capabilities of the actuator system. Higher peak thrusts are achievable by servo motor actuator systems, so please consult Tolomatic before exceeding catalog rating.

SPEED vs THRUST

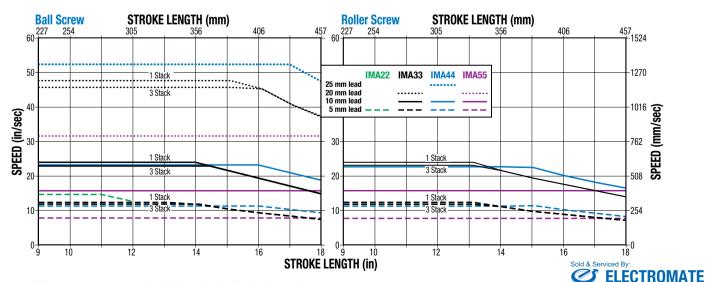




PEAK REGION is the maximum performance capabilities of the actuator system. Higher peak thrusts are achievable by servo motor actuator systems, so please consult Tolomatic before exceeding catalog rating.

CONTINUOUS REGION is defined as the RMS thrust and velocity limit that is derived from the thermal limits of the actuator system to achieve the dynamic load rating of the screw. (Example: Extend and retract under force 100% of the time with no dwells.)

CRITICAL SPEED

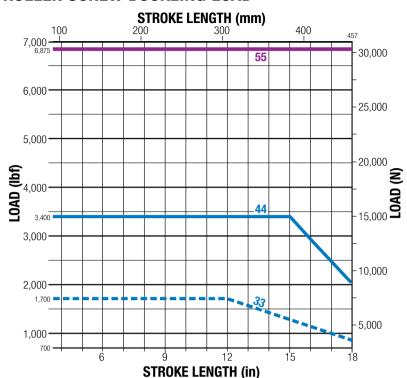


All curves represent properly lubricated and maintained actuators.

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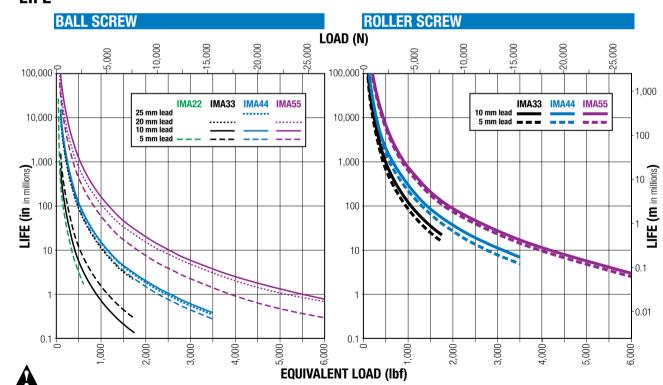
ROLLER SCREW BUCKLING LOAD





All curves represent properly lubricated and maintained actuators.

LIFE



NOTE: The $\mathbf{L_{10}}$ expected life of a ball screw linear actuator is expressed as the linear travel distance that 90% of properly maintained ball screw manufactured are expected to meet or exceed. This is not a guarantee and this graph should be used for estimation purposes only.

The underlying formula that defines this value is:

$$\mathbf{L}_{10} = \left(\frac{\mathbf{C}}{\mathbf{P}_{\!\boldsymbol{\theta}}} \right)^{\!3} \bullet \mathcal{L} \equiv$$

Travel life in millions of units (in or mm), where:

 $\mathbf{C} = \text{Dynamic load rating (lbf) or (N)}$ \mathbf{P}_{e} = Equivalent load (lbf) or (N)

 $\ell = \text{Screw lead (in/rev)} \text{ or (mm/rev)}$

Use the "Equivalent Load" calculation below, when the load is not constant throughout the entire stroke. In cases where there is only minor variation in loading, use greatest load for life calculations.

 $\%(\mathbf{P}_{1})^{3} + \%(\mathbf{P}_{2})^{3} + \%(\mathbf{P}_{2})^{3}$

100

Where: \mathbf{P}_{e} = Equivalent load (lbs) or (N)

 $P_n = \text{Each increment at different load (lbs) or (N)}$

Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com %_n = Percentage of stroke at load increment

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CALCULATING RMS THRUST AND **VELOCITY FOR SEVERE DUTY**

Servo motor actuator systems have two speed / thrust curves: one for severe duty (continuous) and another for operating region (intermittent or peak). The root mean square (RMS) thrust & velocity is based on the application duty cycle and must fall within the severe duty region of the actuator system. The application maximum thrust & velocity must fall within the operating region of the actuator system. Higher peak thrusts are achievable by the actuator system. so please consult Tolomatic before exceeding catalog ratings. Use the following formulas when calculating the RMS thrust & velocity. When selecting a servo motor actuator system, it is recommended to add a margin of safety of 15% to the thrust and velocity required to move the load.

$$\mathbf{T}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{T}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

$$\mathbf{V}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{V}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

 $\mathbf{T}_{\mathrm{RMS}} = \mathrm{RMS} \ \mathrm{Thrust}$ $\mathbf{V}_{\mathrm{RMS}} = \mathrm{RMS} \ \mathrm{Velocity}$

 $\mathbf{T}_{i} = \text{Thrust during interval i}$

 $\mathbf{V}_{i} = \text{Velocity during interval i}$

 $\mathbf{t} = \text{Time interval i}$

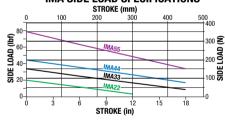
SIDE LOAD CONSIDERATIONS

The IMA integrated motor actuator is not meant to be used in applications where side loading occurs.

Loads must be guided and supported. Loads should be aligned with the line of motion of the thrust rod.

Side loading will affect the life of the actuator.

IMA SIDE LOAD SPECIFICATIONS



CALCULATING LUBRICATION INTERVAL

IMA actuators require periodic re-lubrication to maintain optimal performance. Below are formulas to help determine lubrication interval. See IMA User Guide (#2700-4001) for formula definitions, complete instructions and examples.

BALL SCREW

STEP 1: $\mathbf{P}_{\text{IMA}} = \mathbf{V}_{\text{RMS}} \times \mathbf{T}_{\text{RMS}} \times 0.113$ (watts)

STEP 2. Select the appropriate actuator power level

STEP 3:
$$\mathbf{K}_{p} = \frac{\mathbf{P}_{c}}{\mathbf{P}_{\text{IM}\Delta}}$$

STEP 4:
$$\mathbf{t}_1 = 1000 \text{ (hours)} = \mathbf{K}_p < 1$$

 $\mathbf{t}_1 = 9000 \text{ (hours)} = \mathbf{K}_p > 1$

- Re-lubricate with Mobilith SHC220 Grease #2744-1016 (Quantity: IMA33: 3.0 g; IMA44: 5.0 g; IMA55: 7.0 g) into the grease zerk located on the rod end.
- IMA22 ballscrew does not require re-lubrication

ROLLER SCREW

STEP 1: $\mathbf{t}_{\text{RI}} = 4500 \text{ x } (\mathbf{V}_{\text{RMS}})^{-1.57} \text{ (hours)}$

STEP 2:
$$\mathbf{K}_{T} = \mathbf{K}_{Co} \left(\frac{T_{PEAK}}{P_{o}} \right) - 0.15$$

					,	
	33RN05	33RN10	44RN05	44RN10	55RN05	55RN10
K _c	0.24	0.44	0.26	0.40	0.31	0.84

STEP 3:
$$\mathbf{t}_{_{\!\!1}} = \mathbf{t}_{_{\!\!\!\mathrm{R}^{_{\!1}}}} \times \mathbf{K}_{_{\!\!\!\!\top}}$$
 (hours)

• Re-lubricate with Tolomatic Grease #2744-9099 (Quantity: IMA33: 3.0 g; IMA44: 5.0 g; IMA55: 7.0 g) into the grease zerk located on the rod end.

BRAKE CONSIDERATIONS

An un-powered IMA will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page IMA 8.

A brake can be used with the actuator to keep it from backdriving, typically in vertical applications. A brake may be used for safety

See "P" dimension, pg. 11

reasons or for energy savings allowing the actuator to hold position when un-powered. See page IMA 23 for ordering information.

NOTE: The optional Spring-Applied/Electronically-Released Brake requires 24V power. Input current rating:

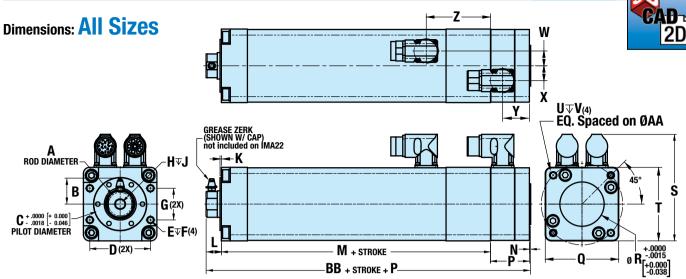
IMA22 - 0.35 Amps;

IMA33 - 0.43 Amps;

IMA44 - 0.67 Amps: IMA55 - 0.66 Amps.

Brake Specifications:

	SERIES	IMA22	IMA33	IMA44	IMA55	
ROTOR	oz-in ²	0.052	0.112	0.656	0.587	
INERTIA	gm-cm ²	19	73	239	214	
CURRENT	Amp	0.35	0.43	0.67	0.66	
HOLDING	in-lb	14	35	89	145	
TORQUE	N-m	1.6	4.0	9.0	16.4	
ENGAGE TIME	mSec	75	40	25	15 Sold & Service	ed By:
DISENGAGE TIME	mSec	20	50	35	Toll Free	LECTROMATI Phone (877) SERV098
VOLTAGE	Vdc		2	4	WWW	Fax (877) SERV099 .electromate.com @electromate.com



	IMA22	IMA33	IMA44	IMA55
Α	0.999	1.186	1.499	2.249
mm	25.38	30.13	38.08	57.13
В	_	1.11	1.27	1.65
mm	-	28.3	32.3	41.9
С	1.8898	2.3622	2.8346	3.937
mm	48.000	60.000	72.000	100.000
D	2.126	2.717	3.346	4.331
mm	54.00	69.00	85.00	100.00
Ε	-	-	-	-
mm	M6 x 1.0	M8 x 1.25	M8 x 1.25	M12 x 1.75
F	0.52	0.57	0.68	0.89
mm	13.2	14.5	17.1	22.5
G	0.787	1.417	2.165	2.559
mm	20.00	36.00	55.00	65.00
Н	_	_	_	_
mm	M8 x 1.25	M12 x 1.25	M20 x 1.5	M27 x 2.0
J	0.65	0.88	1.02	1.50
mm	16.5	22.2	25.9	38.1
K	0.06	0.06	0.06	0.06
mm	1.5	1.5	1.5	1.5
L	0.68	0.68	0.66	0.95
mm	17.3	17.3	16.8	24.1
M	4.32	6.05	7.88	10.48
mm	109.8	153.7	200.0	266.2
N	0.06	0.06	0.06	0.06
mm	1.5	1.5	1.5	1.5
P1	1.62	1.74	1.74	1.90
mm	41.2	44.2	44.2	48.2
P2	3.41	3.18	3.15	3.81
mm	86.7	80.8	80.0	96.8
P3		1.98	1.98	2.14
mm	_	50.3	50.3	54.3
P4		3.68	3.50	3.81
mm	-	93.5	89.0	96.8
P5	1.62	1.74	1.74	2.36
mm	41.2	44.2	44.2	59.9

	IMA22	IMA33	IMA44	IMA55
P6	3.41	3.18	3.15	3.81
mm	86.7	80.8	80.0	96.8
P7	2.31	2.33	2.33	2.66
mm	58.7	59.2	59.2	67.5
P8	3.79	3.96	3.90	4.39
mm	96.3	100.6	99.1	111.5
Q	2.50	3.29	4.35	5.66
mm	63.5	83.6	110.5	143.6
R	1.5748	1.9685	2.9528	3.937
mm	40.000	50.000	75.000	100.000
S1	4.11	4.91	5.96	7.26
mm	104.4	124.6	151.4	184.3
S2	4.02	4.81	5.87	7.16
mm	102.0	122.2	149.0	181.9
S3	4.11	4.91	5.96	7.26
mm	104.4	124.6	151.4	184.3
S4	4.11	4.91	5.96	7.26
mm	104.4	124.6	151.4	184.3
S5	_	4.47	5.53	6.82
mm	_	113.5	140.4	173.3
T	2.50	3.29	4.35	5.66
mm	63.5	83.6	110.5	143.6
U	_	-	_	-
mm	M6 x 1.0	M8 x 1.25	M8 x 1.25	M12 x 1.75
V	0.53	0.65	0.65	0.80
mm	13.5	16.5	16.5	20.5
W	0.38	0.66	0.88	0.88
mm	9.5	16.8	22.2	22.2
Х	0.38	0.66	0.88	0.88
mm	9.5	16.8	22.2	22.2
Υ	1.08	1.20	1.20	1.35
mm	27.3	30.4	30.4	34.4
Z	2.39	2.88	3.07	3.42
mm	60.6	73.1	77.9	86.9
AA	2.756	3.622	5.000	6.102
mm	70.00	92.00	127.00	155.00
BB	5.06	6.79	8.6	11.49
mm	128.6	172.5	218.3	291.8

P6 = Resolver with Brake									
P7 =	Al	solute End	oder						
P8 =	Al	solute End	oder w/ Bi	rake					
S1 =	To	Iomatic Sta	andard						
S2 =	Вс	sch MSK I	Motor Serie	es					

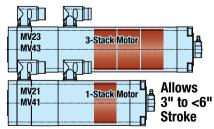
KEY FEATURES: 1-STACK & 3-STACK MOTORS

3D CAD AVAILABLE AT WWW.TOLOMATIC.COM

IWAZZ										
SE	RIES	MV21/41	MV23/43							
STROKE	in	3.0 to 12.0	6.0 to 12.0							
SINUKE	mm	76.2 to 304.8	152.4 to 304.8							
PEAK	lbf	up to 325	up to 325							
THRUST	N	up to 1,446	up to 1,446							

IIVIAJ	J		
SE	RIES	MV21/41	MV23/43
STROKE	in	3.0 to 18.0	6.0 to 18.0
SINUNE	mm	76.2 to 457.2	152.4 to 457.2
PEAK	lbf	up to 1,050	up to 1,700
THRUST	N	up to 4,673	up to 7,562
	Fr		

IMV33



S3 =	Emerson FM Series Lenze MCS Motor Se	Sold & Serviced By:	BAATI
S4 =	Lenze MCS Motor Se	ELECTRU	IVIAII

S5 = Emerson NT Series* Toll Free Phone (877) SERV099

*Uses Box Mount Connectors (1057 feb 5 341 d5 7) SERV099

*Not available as standard on Il WARS @ oloctromate.com

P1 =	Digital Encoder	
D0	5	

P2 = Digital Encoder with Brake

P4 = Digital Encoder with Brake (Emerson NT)

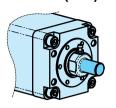
P5 = Resolver

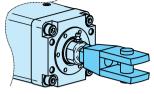
P3 = Digital Encoder (Emerson NT)

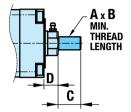
Dimensions: Rod End Options

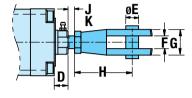




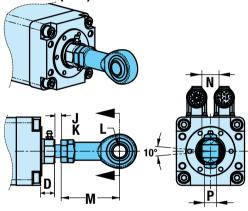




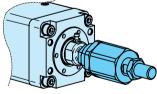


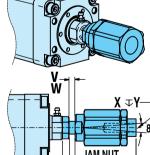


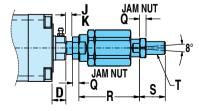
SPHERICAL ROD EYE (SRE)

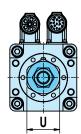




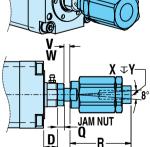








ALIGNMENT COUPLER
FEMALE (ALC)



		IIVIAOU	IIVIIATT	IIVIAOU						
Α		-	-							
mm	M10 x 1.25	M16 x 1.5	M20 x 1.5	M27 x 2.0						
В	0.87	1.35	1.63	1.80						
mm	22.1	34.3	41.4	38.1						
С	0.97	1.47	1.75	2.00						
mm	24.6	37.3	44.5	50.8						
D	0.68	0.68	0.66	0.95						
mm	17.3	17.3	16.8	24.1						
Е	0.394	0.630	0.787	1.181						
mm	10.00	16.00	20.00	30.00						
F	0.39	0.63	0.79	1.18						
mm	10.0	16.0	20.0	30.0						
G	0.79	1.26	1.57	2.17						
mm	20.0	32.0	40.0	55.0						
Н	1.77	2.83	3.54	4.86						
mm	45.0	72.0	90.0	123.5						
J	0.36	0.52	0.56	0.40						
mm	9.1	13.2	14.2	10.1						
K	0.10	0.12	0.12	0.20						
mm	2.5	3.0	3.0	5.1						
L	0.394	0.630	0.787	1.181						
mm	10.00	16.00	20.00	30.00						
M	1.89	2.84	3.43	4.86						
mm	48.0	72.0	87.0	123.5						
N	0.55	0.83	0.98	1.46						
mm	14.0	21.0	25.0	37.0						
Р	0.49	0.59	0.71	0.94						
mm	12.5	15.0	18.0	25.0						
Q	0.20	0.32	0.39	0.53						
mm	5.0	8.0	10.0	13.5						
R	2.09	2.99	3.23	3.66						
mm	53.0	76.0	82.0	93.0						
S	0.79	1.26	1.57	2.16						
mm	20.0	32.0	40.0	54.0						
T	_	_	_	_						
mm	M10 x 1.25	M16 x 1.5	M20 x 1.5	M27 x 2.0						
U	1.18	1.61	1.65	2.17						
mm	30.0	41.0	42.0	55.0						
V	_	_	0.43	0.43						
mm	-	-	11.0	11.0						
W	_	_	0.16	0.09						
mm	-	_	4.1	2.4						
X	_	_	_	_						
mm	-	-	M20 x 1.5	M27 x 1.75						
Υ	_	_		serv2ce1d3y:						
mm	-	-	42.0 FLE							
			T-1	L Euro - Discour						

IMA22

IMA33

IMA44

3D CAD AVAILABLE AT WWW.TOLOMATIC.COM

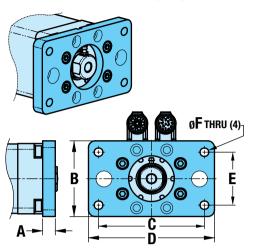
CAD¬⊾

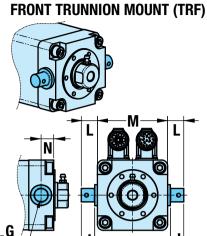
IMA55

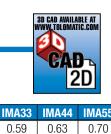
TROMATE

Dimensions: Mounting Options

FRONT FLANGE MOUNT (FFG)

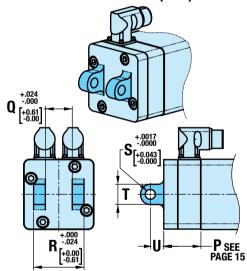




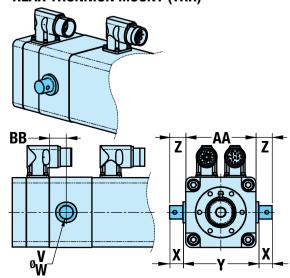


	mm	11.2	15.0	16.0	17.0
	В	2.65	3.43	4.35	5.91
	mm	67.3	87.0	110.5	150.0
	С	3.937	4.961	5.906	9.055
	mm	100.00	126.00	150.00	130.00
	D	4.62	5.91	6.69	10.24
M_ L	mm	117.3	150.0	170.0	260.0
	E	1.969	2.480	2.953	4.528
	mm	50.00	63.00	75.00	115.00
	F	0.34	0.48	0.58	0.66
	mm	8.7	12.3	14.7	16.7
	G	0.472	0.629	0.787	0.984
	mm	11.99	15.98	19.99	24.99
	Н	0.471	0.628	0.786	0.983
J	mm	11.96	15.95	19.96	24.97
The Research	J	0.34	0.63	0.79	0.98
	mm	8.6	16.0	20.1	24.9
	K	2.68	3.54	4.84	6.30
	mm	68.0	90.0	123.0	160.0
	L	0.43	0.76	1.04	1.30
	mm	10.9	19.2	26.3	33.1
	M	2.50	3.29	4.35	5.66
	mm	63.5	83.6	110.5	143.6
	N	0.59	0.59	0.83	1.10
	mm	15.0	15.0	21.0	28.0

REAR CLEVIS MOUNT (PCD)



BEAR	TRIII	ими	MOUNT	/TRR\
NEAN	INU		INIUUINI	unnı



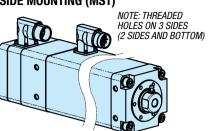
	IMA22	IMA33	IMA44	IMA55				
Q	1.0236 ¹	1.2598	1.9685	2.3622				
mm	26.000¹	32.000	50.000	60.000				
R	1.77172	2.3622	3.5433	4.33074				
mm	45.000°	60.000	90.000	110.0004				
S	0.39373	0.4724	0.6299	0.78745				
mm	10.000 ³	12.000	16.000	20.000 ⁵				
T	0.787	0.945	1.417	1.575				
mm	20.00	24.00	36.00	40.00				
U	0.512	0.630	0.866	1.063				
mm	13.00	16.00	22.00	27.00				
٧	0.472	0.629	0.787	0.984				
mm	11.99	15.98	19.99	24.99				
W	0.471	0.628	0.786	0.983				
mm	11.96	15.95	19.96	24.97				
Χ	0.34	0.63	0.79	0.98				
mm	8.6	16.0	20.1	24.9				
Υ	2.68	3.54	4.84	6.30				
mm	68.0	90.0	123.0	160.0				
Z	0.43	0.76	1.04	1.30				
mm	10.9	19.2	26.3	33.1				
AA	2.50	3.29	4.35	5.66				
mm	63.5	83.6	110.5	143.6				
BB	0.59	0.79	0.98	1.26				
mm	15.0	20.0	25.0	32.0				

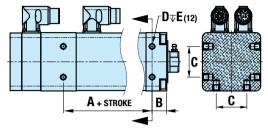
1	+0.0205"/-0.0000"
	+0.520mm/-0.000mm
2	+0.0000"/-0.0244"
	+0.000mm/-0.620mm
3	+0.0014"/-0.0000"
	+0.036mm/-0.000mm
4	+0.0000"/-0.0343"
	+0.000mm/-0.870mm
5	+0.0020"/-0.0000"
	+0.052mm/-0.000mm



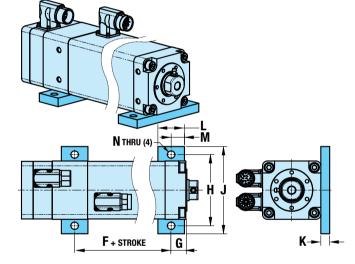
Dimensions: **Options**

SIDE MOUNTING (MST)





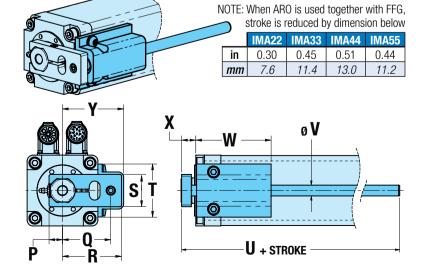
MOUNTING PLATES (MP2)



	IMA22	IMA33	IMA44	IMA55					
Α	2.67	3.97	5.63	7.53					
mm	67.8	100.7	143.0	191.2					
В	0.79	0.83	0.98	1.18					
mm	20.0	21.0	25.0	30.0					
С	1.339	1.732	1.969	3.346					
mm	34.00	44.00	50.00	85.00					
D	_	-	-	_					
mm	M6 X 1.0	M8 x 1.25	M8 x 1.25	M12 x 1.75					
Ε	0.52	0.57	0.68	0.89					
mm	13.1	14.5	17.1	22.5					
F	2.67	3.97	5.63	7.53					
mm	67.8	100.7	143.0	191.2					
G	0.79	0.83	0.98	1.18					
mm	20.0	21.0	25.0	30.0					
Н	3.150	4.016	5.118	6.693					
mm	80.00	102.00	130.00	170.00					
J	3.94	4.92	6.10	7.87					
mm	100.0	125.0	155.0	200.0					
K	0.43	0.50	0.50	0.79					
mm	11.0	12.7	12.7	20.0					
L	1.18	1.50	1.50	1.97					
mm	30.0	38.1	38.1	50.0					
М	0.59	0.75	0.75	0.98					
mm	15.0	19.1	19.1	0.5					
N	0.34	0.42	0.42	0.59					
mm	8.7	10.7	10.7	15.1					

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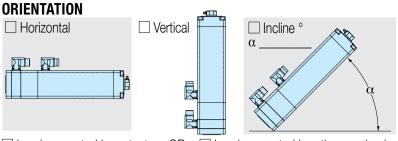




	IMA22	IMA33	IMA44	IMA55					
Р	0.50	0.63	0.78	1.25					
mm	12.7	15.9	19.8	31.8					
Q	1.71	2.24	2.78	3.74					
mm	43.3	57.0	70.5	95.1					
R	2.02	2.75	3.28	4.32					
mm	51.2	69.7	83.2	109.7					
S	1.37	1.50	1.81	2.69					
mm	34.8	38.1	45.9	68.2					
Т	1.82	2.47	2.47	4.20					
mm	46.2	62.7	62.7	106.7					
U	3.19	4.14	4.27	5.60					
mm	81.0	105.2	108.5	142.5					
٧	0.38	0.50	0.50	0.75					
mm	9.5	12.7	12.7	19.1					
W	2.56	3.50	3.66	4.55					
mm	65.0	89.0	93.0	115.6					
Χ	0.63	0.63		vice0 £90					
mm	16.1	16.1	Fa	EZEST	ROMATI				
Υ	2.16	2.85	3.58 Fr	ee PA66e (8	77) SERV098				
mm	54.9	72.3	<i>85.</i> Tøll F	ree/ 1788; 3(87	7) SERV099				
				ww.electron les@electro					

sales@electromate.com

APPLICATION DATA WORKSHEET Fill in known data. Not all information is required for all applications





MOVE PROFILE					LEI	NG	TH	_								_		PR										
EXTEND			er in ON					」n etric	nilli	me	ter	rs	(<u>S</u>	M)			⊰ep]i			IDII	ity						 neters
Move Distance millimeters							(-,								L	'	110	/1 1				ı				101010
		^ !	TON	E: If	loac	d or	forc num	ce o	cha	nge	s d	duri	ing	СУ	cle													MENT
Move Timesec						30L I	luitt							115				en	np	era	atu	re,	C	ont	an	nina	atio	on, Water, etc.
Max. Speed □ in/sec □ mm/sec			TE						RE								-											
Dwell Time After Movesec			AD						LO		_						_											
RETRACT			lb. Star	ndard)) (I	I Metr	kg. ic)		 U.S.		ndar	d)		 Metr		•												
Move Distance	ı	F0	RC	Ε					F0	RC	Έ																	
inch millimeters	[lb.		[ΚQ.			b.					kg													
Move TimeSec	(U.S.	. Star	ndard)) (Metr	ic)	(U.S.	Star	ndar	d)	(1	Metr	ic)													
Max. Speed □ in/sec □ mm/sec																												
Dwell Time After Movesec		-	10		PRC)FI	LE				_																_	0
	+	. 5	Speed	l ()_						+																	Graph your most demanding cycle,
NO. OF CYCLES		E																										including accel/decel, velocity and dwell
☐ per minute ☐ per hour		F									+																	times. You may also want to indicate load variations and I/O
HOLD POSITION? Required		E																										changes during the cycle. Label axes
☐ Not Required		F									+											t						with proper scale and units.
☐ After Move ☐ During Power Loss		F											H		H													urino.
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Co. Name, Etc.																												



USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT LECTROMATE www.tolomatic.com OR... CALL TOLOMATIC AT 1-800-328-2174. We will provide any assistance needed to determine the proper actuator for the job.

Selection Guidelines



ESTABLISH MOTION PROFILE

Using the application stroke length, desired cycle time and loads establish the motion profile details.

COMPARE OPERATING (PEAK) THRUST AND SPEED TO OPERATING REGION

Calculate the application required operating (peak) thrust and speed and compare to tables on pages IMA 8-9. The calculated thrust and speed must fall within the operating region of the actuator.

COMPARE SEVERE DUTY (CONTINUOUS) THRUST AND SPEED TO SEVERE DUTY REGION

Calculate the RMS thrust and speed required and compare to tables on pages IMA_8-9. The calculated thrust and speed must fall within the severe duty region. See complete instructions on page IMA 14 for help calculating continuous force.

$$\mathbf{T}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{T}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}} \quad \mathbf{V}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{V}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

CONSIDER SCREW/NUT CHOICES Choose roller nuts for its longer life (see Life graph on

page IMA 13) and higher peak loads (see graphs on pages IMA 10 & 11). Ball nuts are cost competitive and more efficient (see table on page IMA 8).

SCREW ACCURACY Roller Nut ± 0.0004 "/ft. ± 0.0102 mm/300mm

Ball Nut ± 0.002 "/ft. ± 0.051 mm/300mm

VERIFY CRITICAL SPEED OF THE SCREW

Verify that the application's peak linear velocity does not exceed the critical speed value for the size and lead of the screw selected.

NERIFY AXIAL BUCKLING STRENGTH OF THE SCREW (ROLLER SCREW)

Verify that the peak thrust does not exceed the critical buckling force for the size of the screw selected (see graph on page IMA 13).

MOTOR WINDINGS & VOLTAGES

Choose motor windings optimized for 230 Vac and 460 Vac voltage busses. The 1 stack motor (MV21-230V & MV41-460V), available for the IMA22/33, allows strokes between 3 and 6" providing the thrust needed for many applications in a more compact, lighter weight package

CALCULATE LUBRICATION INTERVAL

See page IMA 14 for an overview and IMA Users Guide (#2700-4001) for complete instructions to calculate lubrication interval.

TEMPERATURE

The IMA is intended to operate in an environment with an ambient temperature between 50-104°F, (10-40°C). Performance should be de-rated if the ambient temperature is above 77°F (25°C). Contact the factory if the ambient temperature does not fit within this range. NOTE: Temperature of the actuator's body can approach 180°F (82°C) in aggressive applications. Adequate clearance to ensure actuator's ambient conditions do not rise drastically should be allowed.

BRAKE CONSIDERATIONS An un-powered IMA will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page IMA_8.

A brake can be used with the actuator to keep it from backdriving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when un-powered. See page IMA 23 for ordering information.

NOTE: The optional Spring-Applied / Electronically Released Brake requires 24V power, Input current rating: IMA22 - 0.35 Amps; IMA33 - 0.43 Amps; IMA44 - 0.67 Amps; IMA55 - 0.66 Amps.

CHOOSE MOTOR CONNECTORS & FEEDBACK DEVICE

Connector choice and wiring emulates popular motor manufacturers for compatibility.

Current connector choices include:

- Bosch Rexroth MSK Series
- Emerson FM & NT Series
- Lenze MCA Series

Current feedback choices include:

- Digital Encoder
- Absolute Encoder
- Resolver

Contact Tolomatic for additional motor connectors, feedback combinations and motor files for third party drives.

CONSIDER MOUNTING & ROD END OPTIONS

Examine mounting options dimensional drawings on page IMA_15-18. Standard mounting on the IMA are 4 tapped holes on the front rod end face of the actuator. The Side Mount option (MST) includes 12 tapped holes, 4 on each side and 4 on the bottom of the actuator. Other fixed mounting options are the Front Flange Mount (FFG) and Mounting Plates (MP2). Pivoting mount options are Front Trunnion (TRF), Rear Trunnion (TRR) and Rear Clevis Mount (PCD).

Rod End Options include: External Threaded Rod End (MET), Clevis Rod End (RCL), Spherical Rod Eye (SRE) and Alignment Coupler (ALC).

NOTE: Regardless of the mounting option chosen, care must be taken to ensure that the load is guided and in-line with the thrust rod's line of motion. Misalignment of the thrust rod's line of motion will cause degradation in the actuator's expected life.

CONSIDER ENVIRONMENTAL RATING AND ANTI-ROTATE OPTIONS do & Serviced By:

The environmental rating for a stand choose IP67 for protection against water and dust ingress 877) SERVO98 Choose the Anti-Rotate Option (ARO) if required. Call-Tolomatic 7) SERV099 at 1-800-328-2174 for help in determining the best vactories mate.com for your application.

The IMA is matched to your drive/controller choice

The IMA has been successfully integrated with the following servo drive/controller and robot companies:

Controller/ Drive Manufacturers

- Allen Bradley
- Bosch Rexroth
- Copley
- Elmo
- Emerson
- Kollmorgen
- Lenze
- Omron
- Parker

Robot Manufacturers

- ABB
- Fanuc
- Kawasaki
- Kuka
- Motoman
- Nachi







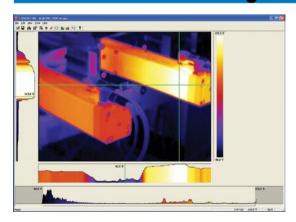




Licensed Partner

For additional information regarding the integration of the IMA to an Allen Bradley/Rockwell drive see tech note linked below: 3600-4187 01 TN IMA-AB-servo.pdf

The IMA is the most vigorously tested Tolomatic product yet



Cutting edge products like the IMA don't just fall into place. Over 20,000 hours of testing were required to prove the design that ships today. Thermal imaging, dynamic loading and other state-of-the-art techniques give us the confidence to stand behind our published performance data.



Replacement Option Parts Ordering

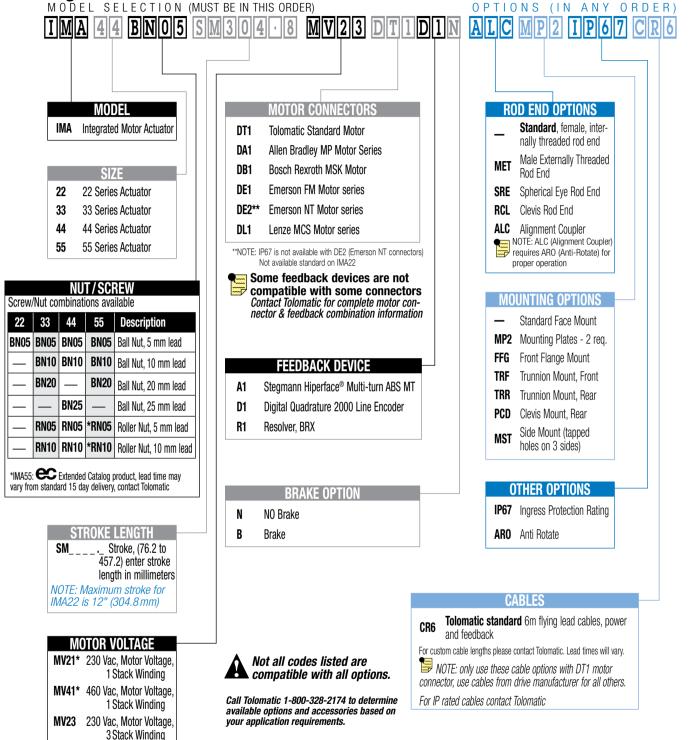
PART NO.	DESCRIPTION							
2722-9014	Spherical Rod Eye Kit, IMA22							
2733-9014	Spherical Rod Eye Kit, IMA33							
2744-9014	Spherical Rod Eye Kit, IMA44							
2755-9014	Spherical Rod Eye Kit, IMA55							
2722-9015	Clevis Rod End Kit, IMA22							
2733-9015	Clevis Rod End Kit, IMA33							
2744-9015	Clevis Rod End Kit, IMA44							
2755-9015	Clevis Rod End Kit, IMA55							
2124-1070	Alignment Coupler Kit, IMA22							
2132-1060	Alignment Coupler Kit, IMA33							
2150-1060	Alignment Coupler Kit, IMA44							
2164-1060	Alignment Coupler Kit, IMA55							
2722-9010	Mounting Plate Kit, IMA22							
2733-9010	Mounting Plate Kit, IMA33							
2744-9010	Mounting Plate Kit, IMA44							
2755-9010	Mounting Plate Kit, IMA55							
2722-9018	Front Flange Mount Kit, IMA22							
2733-9018	Front Flange Mount Kit, IMA33							
2744-9018	Front Flange Mount Kit, IMA44							
2755-9018	Front Flange Mount Kit, IMA55							
2722-2045	Rear Clevis Mount, IMA22							
2733-1045	Rear Clevis Mount, IMA33							
2744-1045	Rear Clevis Mount, IMA44							
2755-1045	Rear Clevis Mount, IMA55							
2722-9075	Anti Rotate, Bearing Assy, IMA22							
2733-9075	Anti Rotate, Bearing Assy, IMA33 & 44							
2755-9075	Anti Rotate, Bearing Assy, IMA55							

PART NO.	DESCRIPTION
2722-9074	Anti Rotate, Shaft Clamp Assy, IMA22
2722-2211	Anti Rotate, Shaft, IMA22 - Indicate Stroke
2733-9074	Anti Rotate, Shaft Clamp Assy, IMA33
2733-1211	Anti Rotate, Shaft, IMA33 - Indicate Stroke
2744-9074	Anti Rotate, Shaft Clamp Assy, IMA44
2744-1211	Anti Rotate, Shaft, IMA44 - Indicate Stroke
2755-9074	Anti Rotate, Shaft Clamp Assy, IMA55
2755-1211	Anti Rotate, Shaft, IMA55 - Indicate Stroke
2733-1221	Motor Power Cable, NO Brake, 460 Vac, MV4
2733-1222	Motor Power Cable, w/ Brake, 460 Vac, MV4
2744-1221	Motor Power Cable, NO Brake, 230 Vac, MV2
2744-1222	Motor Power Cable, w/ Brake, 230 Vac, MV2
2733-1223	Feedback Cable, 12 pin (Resolver & Stegmann), flying leads
2733-1224	Feedback Cable, 17 pin (Digital Encoder), flying leads
2744-1016	Mobilith SHC220 Grease (Ball nut/screw)
2744-9099	Grease (Roller nut/screw)
2552-1132	Wiper, IMA22
2115-1030	Wiper, IMA33
2744-1003	Wiper, IMA44
2140-1030	Wiper, IMA55
2744-1213	Zerk Cap
2744-9092	Kit, Zerk with Cap
2744-1214	Grease Ftg. Plug

All parts are listed for REPLACEMENT ONLY. If not ordered on original unit the IMA may require additional tapped holes or replacement rod end. Contact Tolomatic.









MV43 460 Vac, Motor Voltage,

3 Stack Winding

The Tolomatic Difference Expect More From the Industry Leader:



Tolomatic designs and builds the best standard products, modified products & unique custom products for your challenging applications.



The fastest delivery of catalog products... Electric products are built-to-order in 15 days; Pneumatic & Power Transmission products in 5 days.



Online sizing that is easy to use, accurate and always up-to-date. Find a Tolomatic electric actuator to meet your requirements.



Match your motor with compatible mounting plates that ship with any Tolomatic electric actuator



Easy to access CAD files available in the most popular formats to place directly into your assembly.



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Also Consider These Other Tolomatic Products:

Electric Products

Rod & Guided Rod Style Actuators, High Thrust Actuators, Screw & Belt Drive Rodless Actuators, Motors, Drives and Controllers

"Foldout" Brochure #9900-9074





Pneumatic Products

Rodless Cylinders: Band Cylinders, Cable Cylinders, Magnetically Coupled Cylinders/Slides; Guided Rod Cylinder Slides

"Foldout" Brochure #9900-9075



Power Transmission Products

Gearboxes: Float-A-Shaft®, Slide-Rite®; Disc Cone Clutch; Galiper Disc Brakes

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