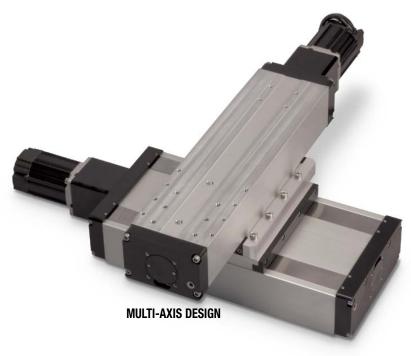


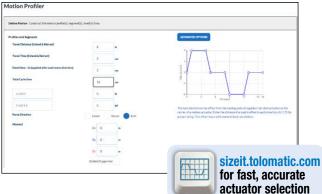


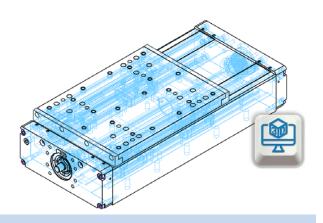
### **TRS: A Rugged, Accurate Stage**

The TRS is a highly capable stage product and is the perfect for a base in multi-axis systems. The machined, rigid design handles high moment loading while providing reliable positioning along the length of travel.

Maximum flexibility is achieved through stroke configurable design, ensuring the right stroke length can be selected to minimize footprint. Online CAD and Sizing tools enable rapid design iterations throughout the design process.





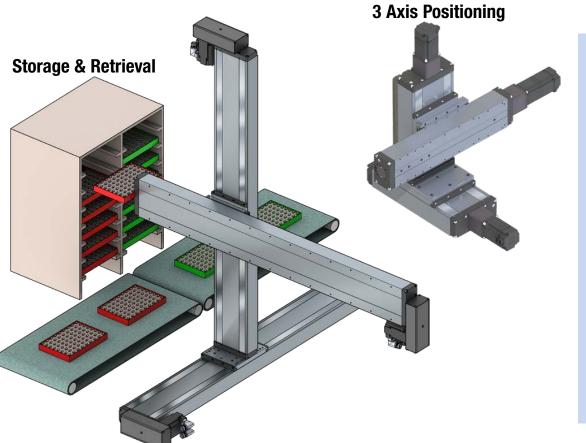


### **A Comparison of Screw Drive Actuators**

-	TRS	B3S	MXE-S	MXE-P
		ner.	000	
Features:	Superior rigidity, high moment load capacities	Internal bearing, highest load and bending moments	Basic guidance and support	High load and bending moment capacities
Load up to: (with options)	1,356 lb [615 kg]	8,000 lb [3,629 kg]	1,040 lb [472 kg]	2,584 lb [1,172 kg]
Thrust up to:	562 lbf [2.5 kN]	2,700 lbf [12 kN]	4,300 lbf [19.1 kN]	4,300 lbf 19.1 kN]
Speed up to:	36 in/sec [910 mm/sec]	60 in/sec [1,500 mm/sec]	60 in/sec [1,500 mm/sec]	60 in/sec [1,500 mm/sec]
Stroke Length up to:	43 in [1,090 mm]	179 in [4,550 mm]	179 in [4,550 mm]	179 in [4,550 mm]
Screw/Nut Type	Ball & Roller	Solid & Ball	Solid & Ball	Solid & Ball
	www.tolor	matic.com for complete in	formation, search by literatu	ıre number:
Literature Number:	3600-4222	3600-4176	8300-4000	8300-4000

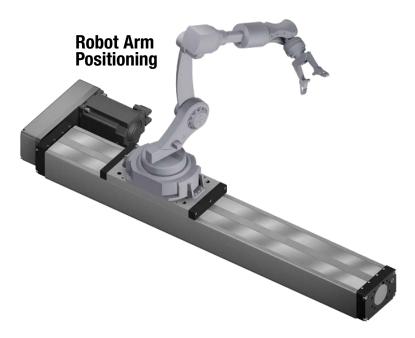
(Not all models deliver ALL maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)





### **CONTENTS**

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- Inspection and measurement
- Medical equipment
- Pick and place
- Precision grinders
- Stage motion control
- Table positioning
- Test stands
- Machine centers
- Machine tools
- Drilling
- Cutting

Positioning

- Material handling systems
- Pick and place
- X Y Z axis (2 and 3 axis configurations)

Sold & Serviced By:

**Laser Engraving** 



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# TWIN RAIL STAGE ENCLOSED DESIGN PROFILED RAIL ACTUATOR

ENDURANCE TECHNOLOGY
A Tolomatic Design Principle

REDUCE UNPLANNED DOWNTIME: Endurance Technology features are designed for maximum durability to provide extended service life.

The TRS Twin profile rail stage with enclosed design is built from the ground up to be highly rigid and accurate. Available in 100 and 165 sizes and capable of handling loads up to 1,356 lb (615 kg). To maximize design flexibility, the TRS actuator is stroke configurable to minimize overall machine footprint.

### **HIGH RIGIDITY**

Twin rails each with 2 bearings minimizes deflection for reliable and accurate positioning along the length of travel

#### CARRIER **TO CARRIER** MOUNTING

- Build a multi-axis system with reduced components by leveraging this standard mounting option
- Tolomatic representatives are available to assist with the sizing

### **MULTIPLE SCREW TECHNOLOGIES**

#### **ROLLER NUT**

Roller nuts provide the highest thrust and life ratings available



**SCREW ACCURACY** 

 $\pm 0.0102$ mm/300mm;  $\pm 0.0004$ "/ft.

#### BALL NUT

Ball nuts offer efficiency at a cost effective price

**SCREW ACCURACY** 

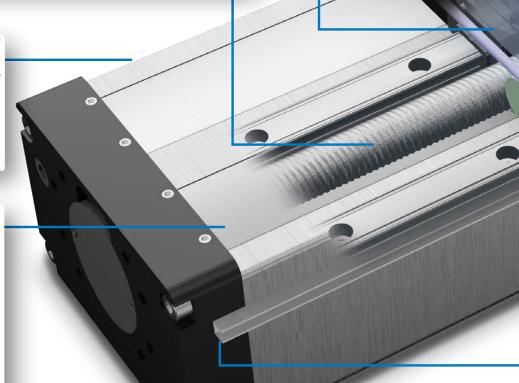
 $\pm 0.051$  mm/300mm;  $\pm 0.002$ "/ft.

#### **BREATHER/PURGE PORTS**

Positive pressure with air lines and filters helps reduce contamination of the interior of the actuator

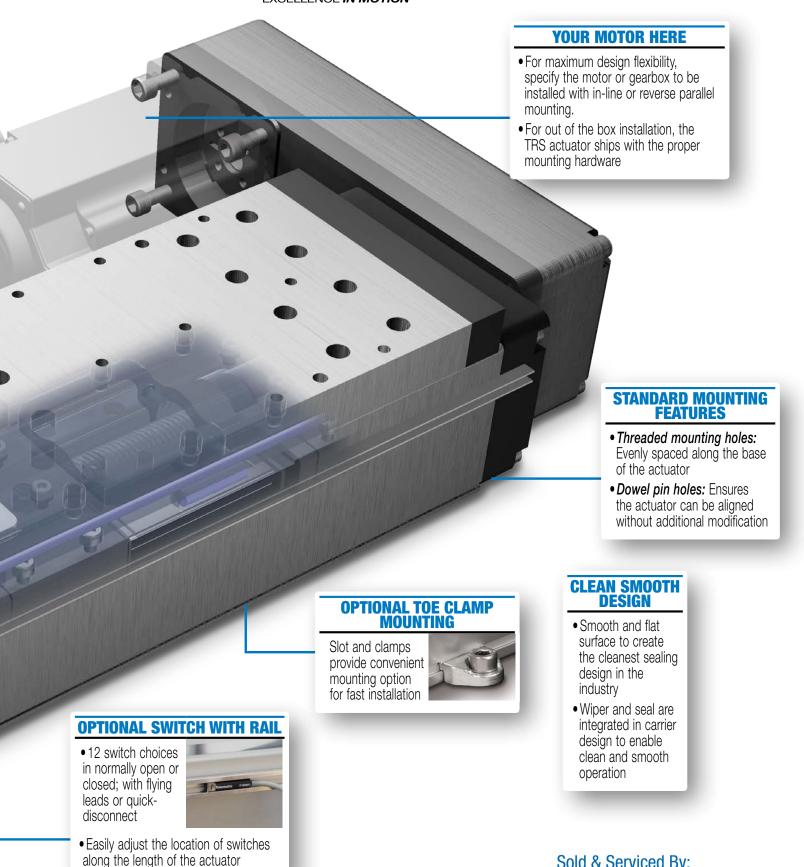
# IP44 RATED WITH STAINLESS STEEL DUST BANDS

- Perfect for industrial environments
- Limits the amount of contaminants that enter the actuator, which protects components for reduced maintenance and increased uptime





## **Tolomatic** ... MAXIMUM DURABILITY



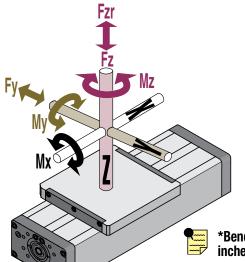
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### **BENDING MOMENTS**



	MAX. BENDING MOMENTS AND LOADS*													
		Metric	;	U.	S. Conven	tional								
Max. Bending Moments		100	165		100	165								
Mx (Roll)	N-m	101	294	lb-in	895	2,604								
My (Pitch)	N-m	194	284	lb-in	1,718	2,512								
Mz (Yaw)	N-m	175	256	lb-in	1,551	2,269								
Max. Loads														
Fz (Radial)	kg	492	615	lb	1,085	1,356								
Fzr (Reverse Radial)	kg	421	526	lb	928	1,160								
Fy (Lateral)	kg	380	475	lb	838	1,048								
·														

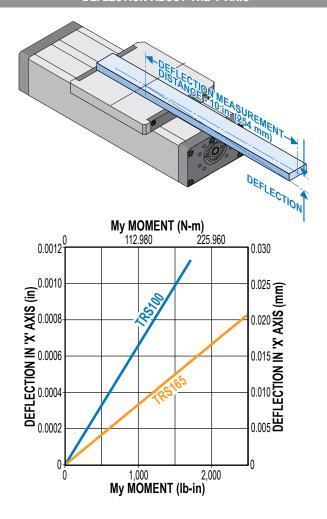
\*Bending moments & load specifications are based on (5,000 kM) 200,000,000 linear inches of carrier travel.

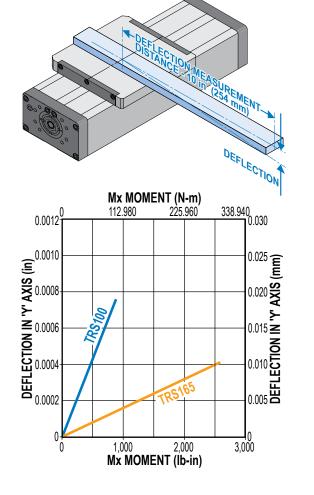
Deflection Considerations: In applications where substantial Mx or My moments come into play, deflection of the actuator frame, carrier and supports must be considered. The deflection values shown in the Load Deflection charts, are based on actuator mounted with its base fully restrained to a surface.

### **LOAD DEFLECTION**

#### **DEFLECTION ABOUT THE Y-AXIS**

#### **DEFLECTION ABOUT THE X-AXIS**







### TRS SPECIFICATIONS

### SPECIFICATIONS RELATED TO ACTUATOR SIZE AND SCREW SELECTION

					TRS	LEAD SCF	EWS MET	RIC			
						<b>∑</b> _	≦		INERTIA		ENE ENE
TOR .		9		955		MAXIMUM THRUST	MAXIMUM STROKE	BASE AC	TUATOR	PER/in	AF S
ACTUATOR	SCREW	LEAD	TOR NFIG	LEAD ACCU RACY	BACKLASH	AH.	MA	In Line	Rev. Parallel	OF STROKE	
AC.		(mm)	MO	(mm/300)	(mm)	(N)	(mm)	(kg-m <sup>2</sup> x 10 <sup>-6</sup> )	(kg-m <sup>2</sup> x 10 <sup>-6</sup> )	(kg-m <sup>2</sup> x 10 <sup>-6</sup> )	(N-m)
TRS100	BNM05	5	ВОТН	0.100	0.07 - 0.12	2,500	750	40.82	135.32	1.29	0.18
1110100	BNM10	10	BOTH 0.100		0.07 - 0.12	2,500	750	45.35	139.85	1.29	0.19
	BNM05	5	ВОТН	0.100	0.07 - 0.12	2,500	1,100	40.67	135.17	1.29	0.18
	BNM10	10	ВОТН	0.100	0.07 - 0.12	2,500	1,100	43.30	137.80	1.29	0.19
TDC165	RN05	5	LMI	0.010	0.03	2,500	575	38.48	_	0.99	0.21
TRS165	RN05	5	RP	0.010	0.03	2,500	557	_	132.98	0.99	0.23
	RN10	10	LMI	0.010	0.03	2,500	575	41.67	_	0.99	0.21
	RN10	10	RP	0.010	0.03	2,500	557	_	136.16	0.99	0.23

	TRS LEAD SCREWS u.s. CONVENTIONAL														
						MID	MU II		INERTIA		IIC ON E				
TOR		LEAD	48	LEAD ACCU- RACY		MAXIMUM Thrust	MAXIMUM Stroke	BASE A	CTUATOR	PER/in	NAN CTI				
ACTUATOR	REW	9	MOTOR	AC AC	BACKLASH	Z I	M IS	In Line	Rev. Parallel						
AC	SCRE	(mm)	MO	(in/ft)	(in)	(lbf)	(in)	(lb-in <sup>2</sup> )	(lb-in <sup>2</sup> )	(lb-in <sup>2</sup> )	(lb-in)				
TRS100	BNM05	5	вотн	0.004	0.0028 - 0.0050	562	29.5	0.1397	0.4631	0.0044	1.56				
100100	BNM10	10	вотн	0.004	0.0028 - 0.0050	562	29.5	0.1552	0.4786	0.0044	1.69				
	BNM05	5	вотн	0.004	0.0028 - 0.0050	562	43.3	0.1392	0.4626	0.0044	1.56				
	BNM10	10	вотн	0.004	0.0028 - 0.0050	562	43.3	0.1482	0.4716	0.0044	1.69				
TRS165	RN05	5	LMI	0.0004	0.0012	562	22.6	0.1317	_	0.0034	1.88				
103103	RN05	5	RP	0.0004	0.0012	562	21.9	_	0.4551	0.0034	2.00				
	RN10	10	LMI	0.0004	0.0012	562	22.6	0.1426	_	0.0034	1.88				
	RN10	10	RP	0.0004	0.0012	562	21.9	_	0.466	0.0034	2.00				

SCREW TYPE DESCRIPTION RN Roller Nut BN Ball Nut



Contact the factory for higher accuracy and lower backlash options.

### TRS CARRIER TO CARRIER MAX. LOAD



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### **ACTUATOR SPECIFICATIONS**

		TRS	100	TRS165									
		Ball	Nut	Ball	Nut	Rolle	r Nut						
		LMI	RP	LMI	RP	LMI	RP						
Carrier Assembly Weight	kg	2.16	2.16	3.20	3.20	3.55	3.55						
Base Weight (incl. carrier)	kg	5.97	7.79	8.44	10.26	8.74	10.56						
Weight per unit of stroke	kg/mm	0.010	0.010	0.015	0.015	0.014	0.014						
Carrier Assembly Weight	lb	4.75	4.75	7.06	7.06	7.82	7.82						
Base Weight (incl. carrier)	lb	13.17	17.18	18.61	22.62	19.28	23.29						
Weight per unit of stroke	lb/in	0.56	0.56	0.81	0.81	0.80	0.80						
Temperature Range			4-5	4 °C; 40-13	30 °F								

### FRICTION FORCE

 $N = 0.003 \times LOAD (kg) + 17.6$  $lbf = 0.0003 \times LOAD (lb) + 3.96$ 

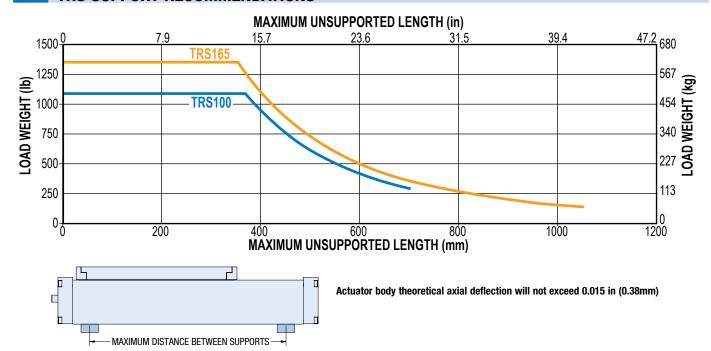
#### STRAIGHTNESS AND FLATNESS

Length of	mm	60	120	180	240	300	360	420	480	540	600	660	720	780	840	900	960	1,020	1,080	1,100
Travel	in	2.4	4.7	7.1	9.5	11.8	14.2	16.5	18.9	21.3	23.6	26.0	28.4	30.7	33.1	35.4	37.8	40.2	42.5	43.3
Straightness/ Flatness	μm	20	21	22	23	24	26	27	28	29	30	32	33	34	35	36	38	39	40	40



- Listed values are intended for reference purposes only, and not as an engineering standard of absolute tolerance for a given actuator. Reference values are measured in ideal conditions. Actual values in the field may vary due to temperature, mounting surface, or other environmental factors.
- Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that
  require operation outside of the recommended temperature range, contact the factory.
- An option is available at additional cost to document the straightness and flatness values specific to the actuator, contact the factory prior to ordering.

### TRS SUPPORT RECOMMENDATIONS

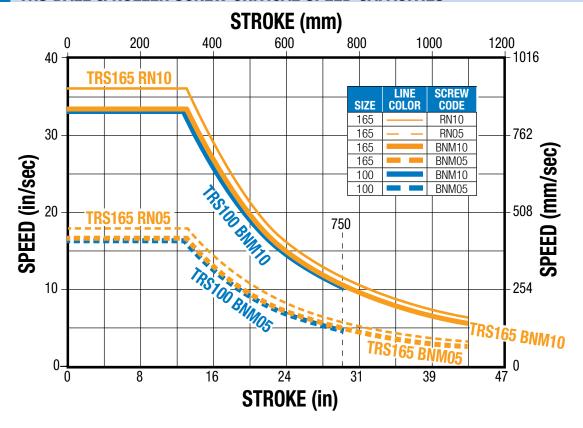




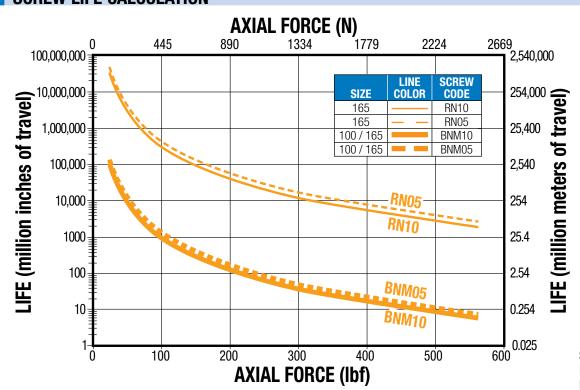


### **SCREW/NUT COMBINATIONS**

### TRS BALL & ROLLER SCREW CRITICAL SPEED CAPACITIES



### **SCREW LIFE CALCULATION**

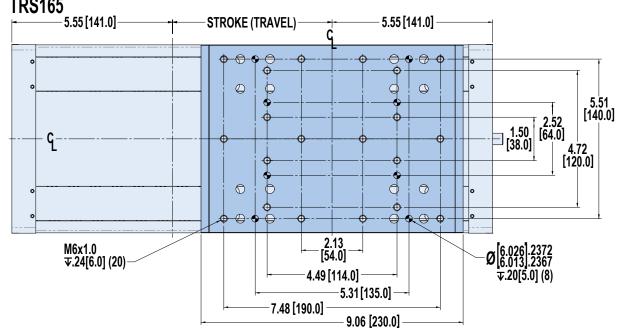


SCREW TYPE DESCRIPTION RN Roller Nut BN Ball Nut

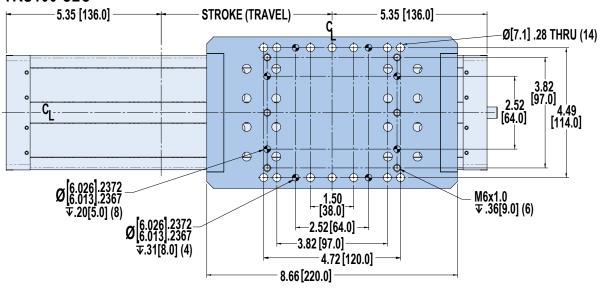
<sup>\*\*</sup>Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.

### DIMENSIONS, Top View TR\$165

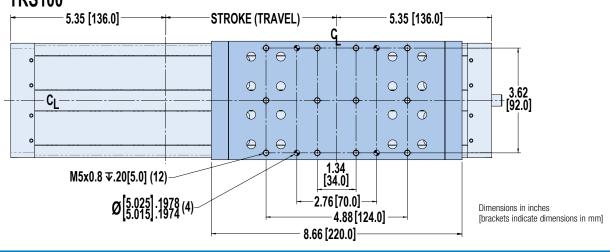




### **TRS100 C2C**

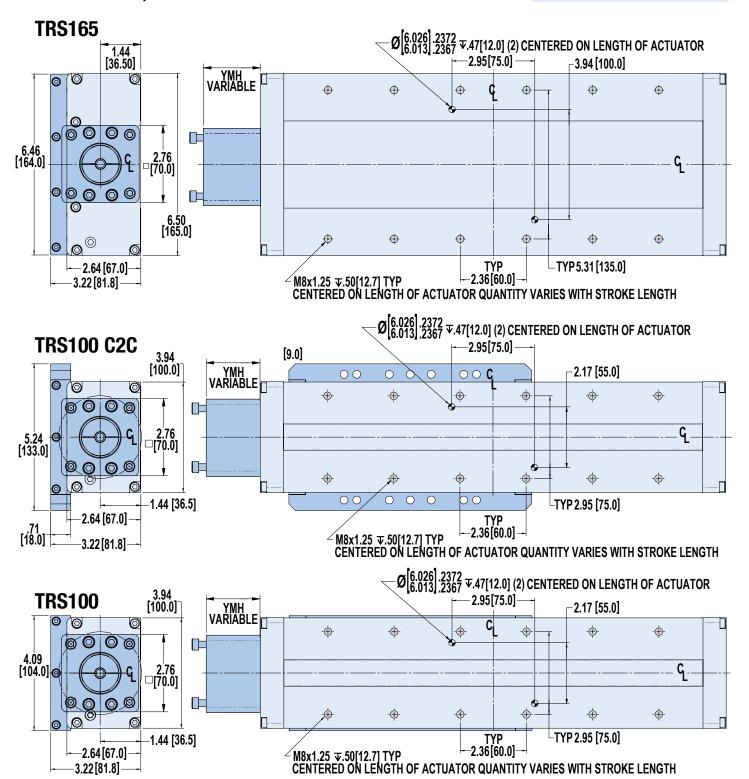


### **TRS100**



### **DIMENSIONS, End & Bottom Views**





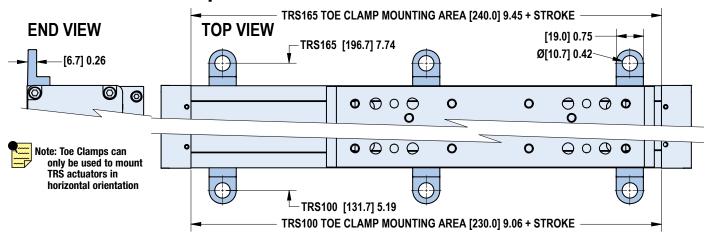
Dimensions in inches [brackets indicate dimensions in mm]



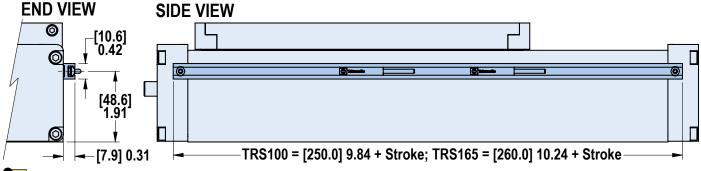
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### **DIMENSIONS: Toe Clamps**



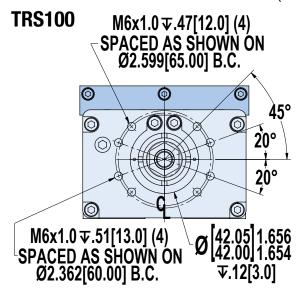


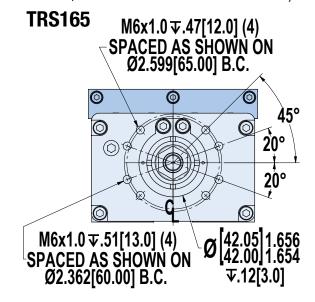
### **DIMENSIONS: Switch Rail**



Note: Switch rail is installed on the right side of the actuator (from the motor end) for all motor mounting configurations except RPR1 where it is installed on the left side of the actuator.

### DIMENSIONS: No Motor Mount (threaded holes and bolt circle; when no motor mount is selected)

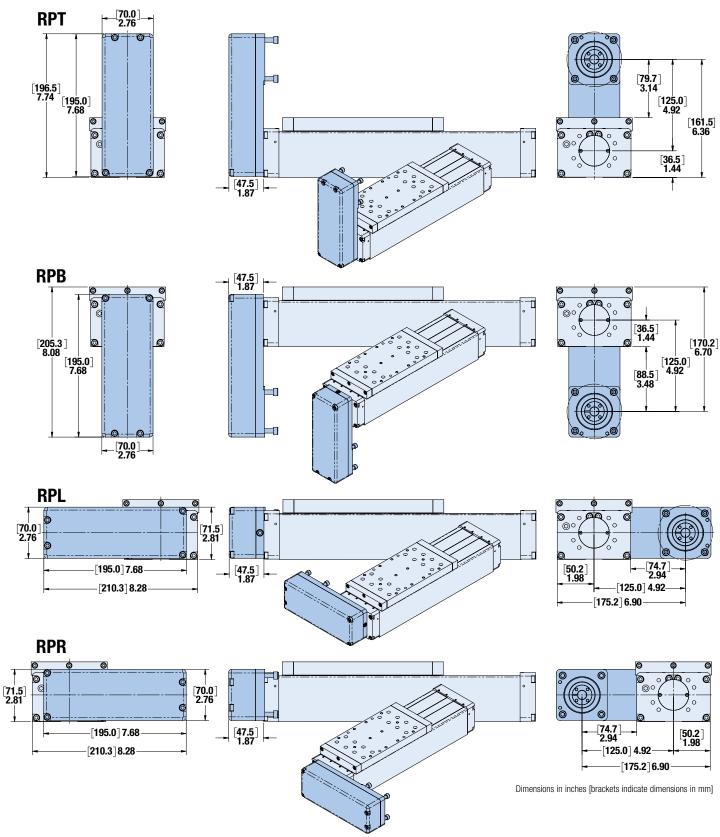




Dimensions in inches [brackets indicate dimensions in mm]

### **DIMENSIONS: RP Motor Mounts: TRS100**





A

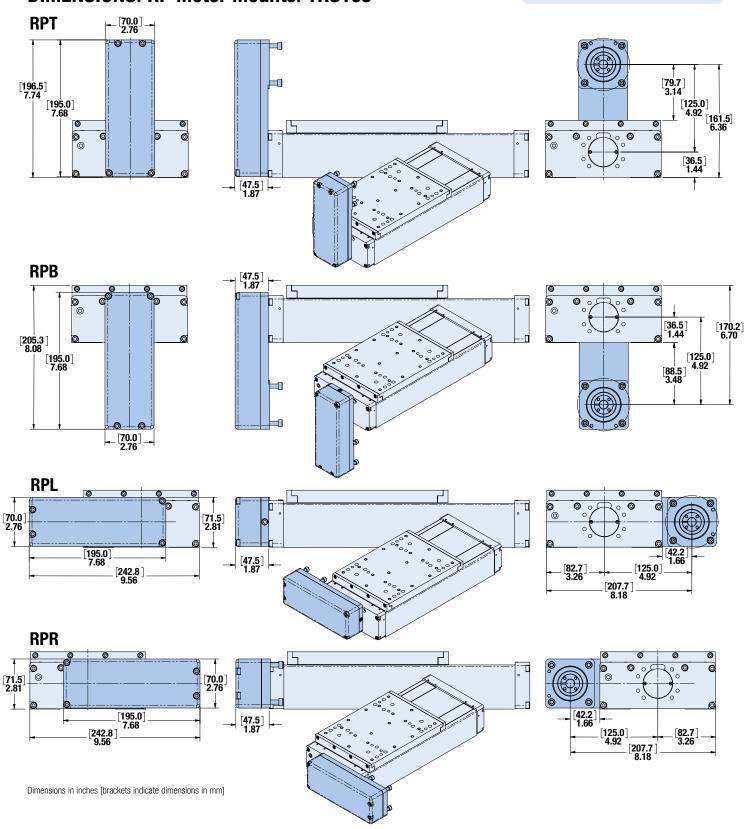
\*LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

Sold & Serviced By:



### **DIMENSIONS: RP Motor Mounts: TRS165**





A

\*LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

### **SWITCHES**

#### **SPECIFICATIONS**





TRS products offer a wide range of sensing choices. There are 12 switch choices: reed, solid state PNP (sourcing) or solid state NPN (sinking); in normally open or normally closed; with flying leads or quick-disconnect.

Commonly used for end-of-stroke positioning, these switches allow drop-in installation anywhere along the rail on the side of the actuator. The one-piece design includes the retained fastening hardware.

Switches are used to send digital signals to PLC (programmable logic controller), TTL, CMOS circuit or other controller device. Switches contain reverse polarity protection. Solid state QD cables are shielded; shield should be terminated at flying lead end.

All switches are CE rated and are RoHS compliant. Switches feature bright red or yellow LED signal indicators; solid state switches also have green LED power indicators.

	Order Code	Lead	Switching Logic	Power LED	Signal LED	Operat- ing Voltage	**Power Rating (Watts)	Switching Current (mA max.)	Current Consump- tion	Voltage Drop	Leakage Current	Temp. Range	Shock / Vibration
	RY	5m	SPST Normally	_	Red	5 - 240							
REED	RK	QD*	Open	Tolomatio	81009082	AC/DC	**10.0	100mA		3.0 V	_		
IILLD	NY	5m	SPST Normally	_	Yellow	5 - 110	10.0	TOOTIA		max.			
	NK	QD*	Closed	Tolomatio	81009084	AC/DC							
	TY	5m	PNP (Sourcing)	Green	Yellow							14	
	TK	QD*	Normally Open	Tolomatio	81009088							to 158°F	50 G /
	KY	5m	NPN (Sinking)	Green	Red							[-10 to	9 G
SOLID	KK	QD*	Normally Open	Tolomatio	81009090	10 - 30	**3.0	100mA	20 mA @	2.0 V	0.05 mA	70°C]	
STATE	PY	5m	PNP (Sourcing)	Green	Yellow	VDC	0.0		24V	max.	max.		
	PK	QD*	Normally Closed	Tolomatio	81009092								
	HY	5m	NPN (Sinking)	Green	Red								
	HK	QD*	Normally Closed	Tolomatio	81009094								

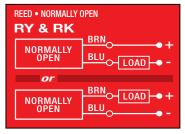
<sup>\*</sup>QD = Quick-disconnect

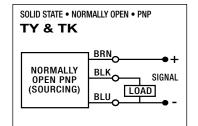
\*\*WARNING: Do not exceed power rating (Watt = Voltage x Amperage). Permanent damage to sensor will occur.

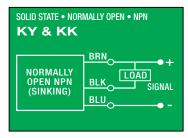
Enclosure classification IEC 529 IP67 (NEMA 6)

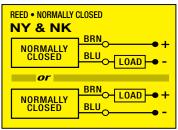
CABLES: Robotic grade, oil resistant polyurethane jacket, PVC insulation

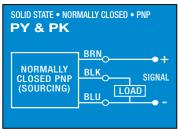
#### **WIRING DIAGRAMS**

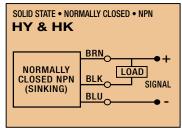


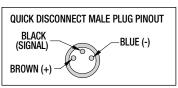


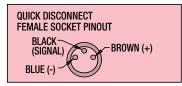




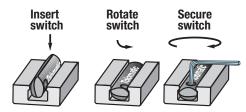








#### SWITCH INSTALLATION AND REPLACEMENT



☐ Y - direct connect

Place switch in side groove on tube at desired location with "Tolomatic" facing outward. While applying light pressure to the switch, rotate the switch is halfway into the groove. Maintaining light pressure, rotate the switch in the opposite direction until it is fully inside the groove with "Tolomatic" visible. Re-position the switch to the exact location and lock the switch securely into place by tightening the screw on the switch.

#### **SWITCH DIMENSIONS**

DETECTION POINT SOLID STATE

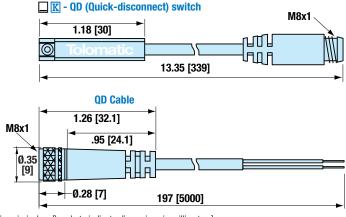
DETECTION POINT REED

.31 [8]

.51 [13]

197 [5000]





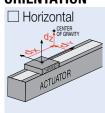
Dimensions in inches [brackets indicate dimensions in millimeters]

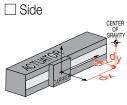
### **COMPILE APPLICATION REQUIREMENTS**

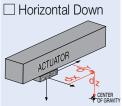
### **APPLICATION DATA WORKSHEET**

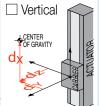
Fill in known data. Not all information is required for all applications

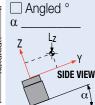
#### **ORIENTATION**

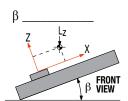












☐ Load attached to carrier OR ☐ Load supported by other mechanism

#### DISTANCE FROM CENTER OF CARRIER TO LOAD CENTER OF GRAVITY

inch (U.S. Standard)

☐ millimeter

### STROKE LENGTH

inch (SK)
(U.S. Standard)

LOAD

 $\square$  lb.

(U.S. Standard)

millimeter(SM)

NOTE: If load or force on carrier changes during cycle use the highest numbers for calculations

☐ kg.

THRUST REQUIRED

☐ Ibf. (U.S. Standard)

**SCREW DRIVE** 

Reverse Parallel

Inline

F<sub>Z</sub> \_\_\_\_\_ F<sub>y</sub> \_\_\_\_\_

### BENDING MOMENTS $M_X$ APPLIED TO CARRIER $M_V$

in.-lbs. (U.S. Standard)

N-m M<sub>Z</sub> \_\_\_\_\_

#### **PRECISION**

Repeatability

☐ inch ☐ millimeters

#### **OPERATING ENVIRONMENT**

Temperature, Contamination, etc.

#### **MOVE PROFILE**

Move Distance

☐ inch ☐ millimeters

Dwell Time After Move\_\_\_\_\_

Max. Speed \_\_\_\_

☐ in/sec ☐ mm/sec

MOVE TIME

☐ sec

#### NO. OF CYCLES

☐ per minute ☐ per hour

### **MOTION PROFILE**

 $\square$  N

(Metric)

Г	+	S	ne	ed	(		)_																							Ξ
	•				`		_																							
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Graph your most demanding cycle, including accel/decel, velocity and dwell times. You may also want to indicate load variations and I/O changes during the cycle. Label axes with proper scale and units.

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### **SELECTION GUIDELINES**

The process of selecting a load bearing actuator for a given application can be complex. It is highly recommended that vou contact Tolomatic or a Tolomatic Distributor for assistance in selecting the best actuator for your application. The following overview of the selection quidelines are for educational purposes only. The Tolomatic Sizelt Software is also available on Tolomatic.com

## CHOOSE ACTUATOR SIZE

Choose an actuator that has the thrust, speed and moment load capacity to move the load. Use the Critical Speed graph (page TRS\_9) for the screw and the Moment and Load Capacity table (pg. TRS\_6) for the actuator.

# 2 COMPARE LOAD TO MAXIMUM LOAD CAPACITIES

Calculate the application load (combination of load mass and forces applied to the carrier) and application bending moments (sum of all moments Mx, My, and Mz applied to the carrier). Be sure to evaluate the magnitude of dynamic inertia moments. When a rigidly attached load mass is accelerated or decelerated. its inertia induces bending moments on the carrier. Careful attention to how the load is decelerated at

the end of the stroke is required for extended actuator performance and application safety. If either load or any of your moments exceed figures indicated in the Moment and Load Capacity table (pg. TRS\_6) for the actuator consider:

- Higher capacity bearing style
- 2) A larger actuator size
- 4) External guide system

# 3 CALCULATE LOAD

For loads with a center of gravity offset from the carrier account for both applied (static) and dynamic loads. The load factor (LF) must not exceed the value of 1.0

$$L_F = \frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.0$$

If LF exceeds the value of 1.0, consider the four choices listed in step #2.

# 4 ESTABLISH YOUR MOTION PROFILE AND CALCULATE ACCELERATION RATE

Using the application stroke length and maximum carrier velocity (or time to complete the linear motion), establish the motion profile. Select either triangular (accel-decel) or trapezoidal (accel-constant speed-decel) profile. Now calculate the maximum acceleration and deceleration rates of the move. A TRS twin rail screw-driven actuator speed should not exceed the value in the critical speed capacity graph (page TRS\_9) for the screw/nut combination chosen. Also. do not exceed safe rates of dvnamic inertia moments determined in step #3.

# 5 SELECT THE LEAD SCREW

Based on the application requirements for accuracy,

backlash, quiet operation, life, etc. select the appropriate screw type (ball screw or roller screw) and the pitch (lead). For additional information on screw selection, consult "Selecting the Optimal Screw Technology" (#9900-4644) available at www.tolomatic.com.

# 6 SELECT MOTOR AND DRIVE

To help select a motor and drive, leverage the Tolomatic SizeIt software, available on Tolomatic.com to calculate the application thrust and torque requirements.

# **7** CONSIDER OPTIONS

- TC Toe clamps
- C2C Carrier-to-carrier mounting
- Switches Reed, Solid State PNP or NPN, all available normally open or normally closed

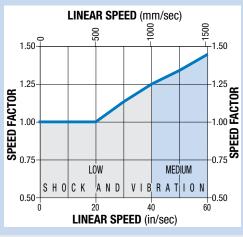


sizeit.tolomatic.com for fast, accurate actuator selection

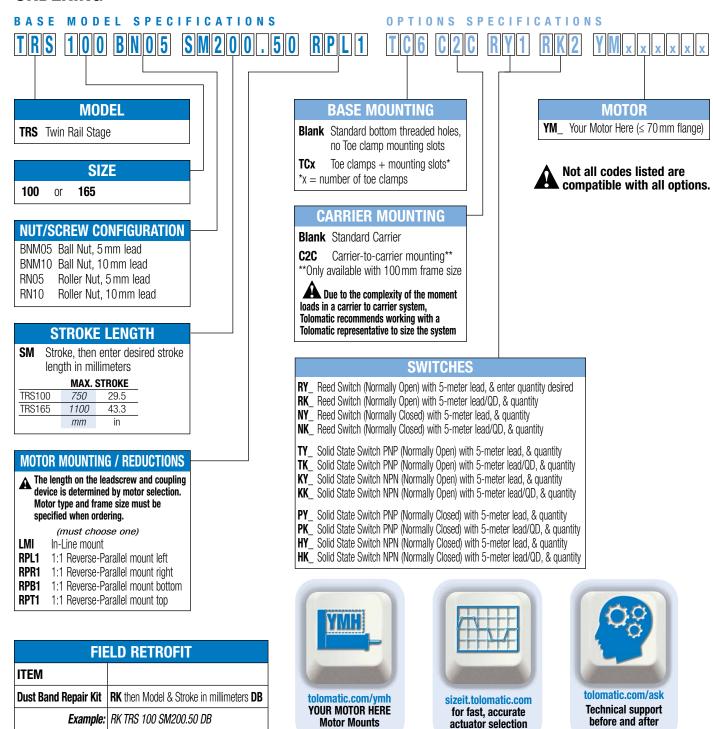
Use Tolomatic Sizing Software to determine available options and accessories based on your application requirements.

### **SPEED FACTOR**

FOR APPLICATIONS WITH HIGH SPEED OR SIGNIFICANT SHOCK AND VIBRATION: Loads and bending moments must be multiplied by speed factor from the graph below to obtain full rated life of profiled rail bearing system.



### **ORDERING**



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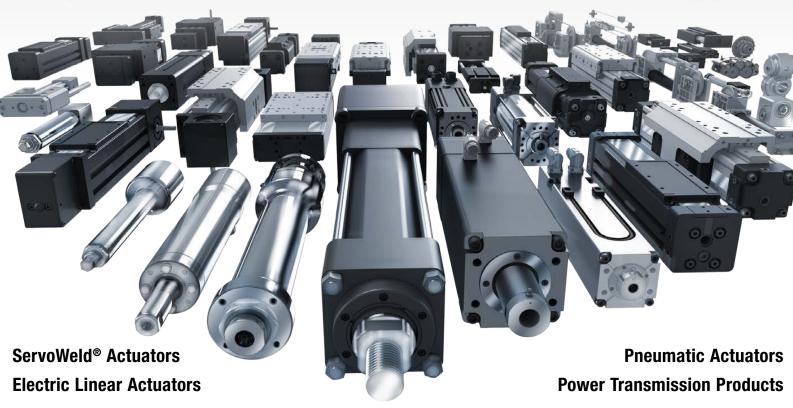


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#### **MEXICO**

Centro de Servicio

Parque Tecnológico Innovación Int. 23, Lateral Estatal 431, Santiago de Querétaro, El Marqués, México, C.P. 76246 Phone: +1 (763) 478-8000 help@tolomatic.com

#### EUROPE

**Tolomatic Europe GmbH** 

Elisabethenstr. 20 65428 Rüsselsheim Germany

**Phone:** +49 6142 17604-0 help@tolomatic.eu

#### **CHINA**

Tolomatic Automation Products (Suzhou) Co. Ltd.

No. 60 Chuangye Street, Building 2 Huqiu District, SND Suzhou Jiangsu 215011 - P.R. China Phone: +86 (512) 6750-8506

Phone: +86 (512) 6/50-8506 TolomaticChina@tolomatic.com

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