TORQUEMASTER BRUSH SERVO MOTORS



4100 SERIES

Performance Benefits

Torque Systems specializes in the design of high performance brush servo motors that provide efficiency, flexibility of application, and a long and trouble-free service life. Our TORQUEMASTER® 4100 series is no exception.

With fast response, accurate control and high torque-to-inertia ratios, you can count on the TORQUEMASTER 4100 Series of brush servo motors to provide smooth operation throughout a full speed range. The 4100 Series delivers smooth and superior low speed performance, and maximum power ratings with low thermal resistance for high speed performance. In addition, with maximum torque in a smaller package, you can count on better pricing for a better overall value.

When integrated with high performance brush amplifiers, TORQUE-MASTER 4100 Series brush servo motors provide effective and highly efficient motion control solutions for a wide range of applications—including factory automation, packaging, robotics, machine tools, medical instrumentation and more.



TORQUEMASTER 4100 Series brush servo motors are rated from 12 lb.-in. to 48 lb.-in. with speeds and torque stability up to 3500 RPM. They utilize the latest in high performance permanent magnet technology, and are available in eight standard windings (as well as custom windings) to meet your most demanding applications.

Each brush servo motor in the TORQUEMASTER 4100 Series is ruggedly designed and manufactured for reliable performance.

Motors can be customized to fit your exact application with tachometers, encoders, brakes and other options.



- Rugged industrial construction
- Continuous torque ratings up to 48 lb.-in.—with speeds up to 3,500 RPM
- Peak torque ratings up to 240 lb.-in.
- IP65 Sealing available
- Superior low speed performance
- Numerous custom options available
- · Available with 8 standard windings







BRUSH SERVO MOTOR CHARACTERISTICS

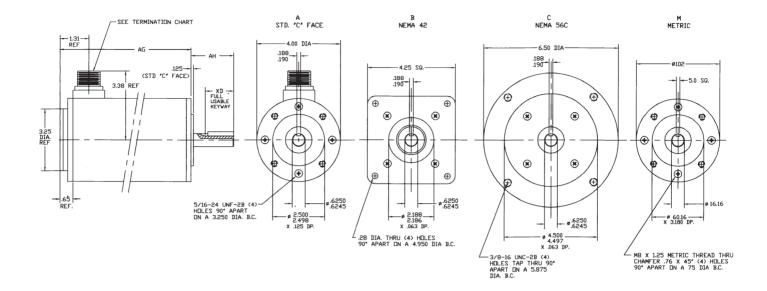
	SYMBOL		UNITS	4101	4102	4104	4106
	T _C	Cont. Torque	Lb-In	12	24	36	48
	T _P	Peak Torque	Lb-In	60	120	180	240
	T _F	Static Friction	Lb-In	1.1	1.1	1.1	1.1
	<u>F</u> i	Viscous Friction	Lb-In/KRPM	.30	.40	.70	.90
	T_R	Cogging Torque	Lb-In	.63	.63	.63	.63
	J _M	Inertia	Lb-In-sec ²	.0078	.011	.018	.024
	R _{TH}	Thermal Res	Deg C/watt	1.7	1.2	1.1	1.0
	T_TH	Thermal Time	Minute	52	55	58	60
	t _m	Mech Time	Millisec	20	10.5	7.6	6.9
	t _e	Elect Time	Millisec	4.8	5.2	5.4	5.7
	F _C	Commutation (41Bar)) Watts x Lb In / Aı	mps 575	956	1438	2011
	Wt	Weight	Lbs	12	15	20	25
	Note: All valu	ues at 25°C Ambient.					
WINDING							
В	K _T	Torq. Sens.	Lb-In/Amp	.76	1.37	2.40	3.47
	R _A	Arm. Resis.	Ohms	.150	.20	.30	.38
	K _V	Back E.M.F	Volts/KRPM	9	16	28	41
	F _C /K _T	P _b	Watts	757	689	599	580
C	K _T	Torq. Sens.	Lb-In/Amp	1.14	2.06	3.60	5.20
	R _A	Arm. Resis.	Ohms	.34	.43	.62	.85
	K _V	Back E.M.F	Volts/KRPM	13	24	42	61.5
	F _C /K _T	P _b	Watts	504	464	399	387
D	K _T	Torq. Sens.	Lb-In/Amp	1.52	2.75	4.80	6.94
	R _A	Arm. Resis.	Ohms	0.6	.78	1.15	1.55
	K _V	Back E.M.F	Volts/KRPM	18	33	57	82.1
	F _C /K _T	P _b	Watts	378	348	300	290
E	K _T	Torq. Sens.	Lb-In/Amp	1.90	3.44	6.01	8.68
	$\overline{R_A}$	Arm. Resis.	Ohms	.95	1.24	1.82	2.40
	K _V	Back E.M.F	Volts/KRPM	22	41	71	103
	F _C /K _T	P _b	Watts	303	278	239	231
F	K _T	Torq. Sens.	Lb-In/Amp	2.28	4.13	7.21	10.42
	R _A	Arm. Resis.	Ohms	1.32	1.68	2.46	3.24
	K _V	Back E.M.F	Volts/RPM	27	49	85	123
	F _C /K _T	P _b	Watts	252	232	199	193
G	K _T	Torq. Sens.	Lb-In/Amp	2.66	4.78	8.41	12.15
	R _A	Arm. Resis.	Ohms	1.89	2.47	3.62	4.77
	K _V	Back E.M.F	Volts/KRPM	31	57	99	144
	F _C /K _T	P _b	Watts	216	226	171	166
H	K _T	Torq. Sens.	Lb-In/Amp	3.04	5.50	9.61	13.9
	R _A	Arm. Resis.	Ohms	2.41	3.15	4.62	6.09
	K _V	Back E.M.F	Volts/KRPM	36	65	114	164
	F _C /K _T	P _b	Watts	189	172	150	145

For custom designs please consult factory.

All specifications subject to change without notice.



MECHANICAL SPECIFICATIONS*

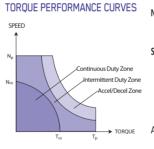


DIMENSION CHART* (Motor Length - AG in inches)

MOTOR	Α	В	С	M
	STD C Face	NEMA 42	NEMA 56C	Metric
4101	6.85	7.19	7.19	174
4102	7.85	8.19	8.19	199.4
4104	9.85	10.19	10.19	250.2
4106	11.85	12.19	12.19	301

F.E.P.	AH	XD
	Shaft Ext.	Key Way
STD. "C"	2.06	1.38
NEMA 42	1.38	.80
NEMA 56C	2.06	1.38
METRIC	45	30

Standard Direction of Rotation: CCW rotation viewed from shaft end with red motor terminal positive with respect to black motor terminal.



NOTE: Continuous torque specifications obtained with motor mounted to an 8.5"x12"x~0.5" aluminum plate at $25~\text{C}^\circ$ ambient.

Typical values are within ±10% of rating.

STANDARD WINDING SPEED/TORQUE CURVE DATA FOR SIZING A SERVO MOTOR

Nm = Maximum speed, continuous operation

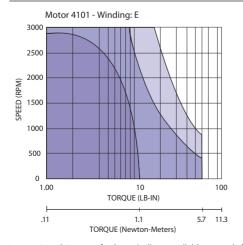
 $\label{eq:Np} \textbf{Np} = \text{Peak speed, acceleration/deceleration and intermittent duty}$

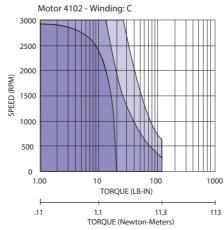
Tcs = Continuous stall torque

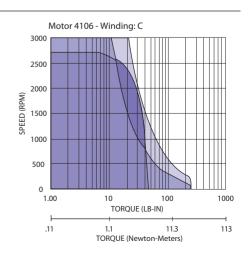
Tp = Peak torque

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TORQUE PERFORMANCE CURVES

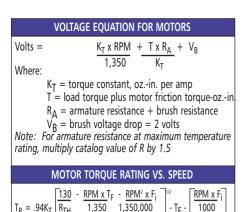


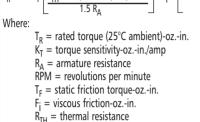




Torque Speed Curves of other windings available, consult factory.

^{*}All specifications are for reference only. Please consult the factory for certified dimension drawings.





To Find: Higher Torque Rating for Intermittent Duty total cycle time in seconds

thermal time constant of motors in seconds

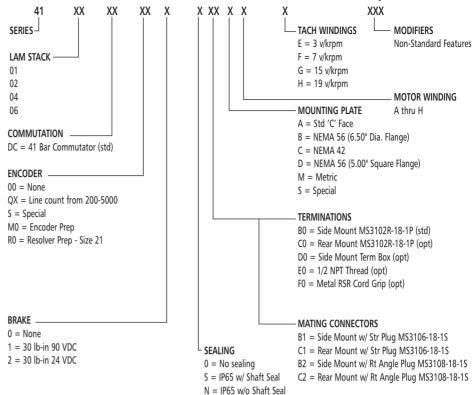
$$\begin{array}{c} \text{Let B} = \frac{\text{"on" time in seconds per cycle}}{\text{thermal time constant of motor in seconds}} \\ \text{then with T_R} = \text{Rated torque for 100\% duty} \\ \text{and T_{MAX}} = \text{Rated torque for intermittent duty} \\ T_{MAX} = T_R \, x \, \left\lceil \frac{1-e^{A^{-1}}}{1-e^{B^{-1}}} \right\rceil^{1/2} \\ \end{array}$$

Let A =

CUSTOMIZE THE 4100 SERIES TO YOUR EXACT REOUIREMENTS

To satisfy various applications with cost-effective solutions, 4100 Series motors are readily available with a wide range of standard capabilities. Final designs are often the result of cooperative efforts between the customer's engineering department and Torque Systems. For assistance, call your local distributor or Torque Systems direct. We look forward to meeting your custom requirements.

ORDERING INFORMATION (For Standard Options)



INTEGRAL DC TACHOMETER SPECIFICATIONS					
Winding Options	E	F	G	Н	
Output volts / 1000 RPM ± 10%	3	7	15	19	
Resistance (ohms) ± 15%	45	100	450	390	
Maximum ripple*	± 1.5%	± 1.5%	± 1.5%	± 2.0%	
Voltage change w/temp. per deg C	.016%	.016%	.016%	.016%	
Rotor inertia (Oz-In Sec 2)	0.001	0.001	0.001	0.001	

*With a 1.5 kHz filter and 10K ohm load impedence for E and F windings, 40K ohm load impedence for G and H windings

TERMINATION CHART MS3102R-20-29P					
	Connection code for CCW rotation				
	Motor/Tach/Mod	. Encoder/Brak	е		
PIN	Function	PIN	Function		
Α	Motor+	K	B Output		
В	Motor	L	B Output		
С	Ground	M	M Output		
D	Tach+	N	M Output		
E	Tach	Р	+5 VDC		
F	Thermostat	R	Common		
G	Thermostat	S	Case Gnd.		
Н	A Output	T	Brake		
J	Ā Output	U	Brake		

	TERMINATION CHART MS3102R-18-1P					
	Connection code for CCW rotation					
	Motor/Tach/Brake					
PIN	Function	PIN	Function			
Α	Motor+	F	Thermostat			
В	Motor	G	Thermostat			
С	Ground	Н	Brake			
D	Tach+	J	Brake			
Е	Tach -					

